Feedback welcome! If you find any typos or anything is unclear or misleading, please email me and know! For additional detail, see the companion paper, "Box-Simplex Games : Algorithms, Applications, and Algorithmic Graph Theory" on my website.

Box-Simplex Games Algorithms, Applications, and Algorithmic Graph Theory

Part I

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Lecture Plan

Today and Tomorrow

- Box-simplex games
- Their structure
- Applications
- Algorithms

Why?

- (Applications) Continuous and combinatorial.
- (Tools) New optimization methods
- (Reinforce) Modifications of common methods

<u>Friday</u>

- Interior point methods
- Introduction of state-of-the-art method

The Problem

Input

- *n*-dimensional box: $B_{\infty}^n \stackrel{\text{\tiny def}}{=} \{x \in \mathbb{R}^n \mid ||x||_{\infty} \leq 1\}$
- *m*-dimensional simplex: $\Delta^m \stackrel{\text{\tiny def}}{=} \{y \in \mathbb{R}^m_{\geq 0} \mid \|y\|_1 = 1\}$

Probability distributions

on *m* elements

Bounded vectors in \mathbb{R}^n

Output:

• An approximate solution to

$$\min_{x \in B_{\infty}^{n}} \max_{y \in \Delta^{m}} f(x, y) \stackrel{\text{def}}{=} y^{\mathsf{T}} A x + c^{\mathsf{T}} x - b^{\mathsf{T}} y$$
Box-Simplex Game
$$\ell_{1} - \ell_{\infty} \text{ Game}$$

Key Motivating Questions

- Box: $B_{\infty}^n \stackrel{\text{\tiny def}}{=} \{x \in \mathbb{R}^n \mid ||x||_{\infty} \le 1\}$
- Simplex: $\Delta^m \stackrel{\text{\tiny def}}{=} \{ y \in \mathbb{R}^m_{\geq 0} \mid \|y\|_1 = 1 \}$
- $\min_{x \in B_{\infty}^{n}} \max_{y \in \Delta^{m}} f(x, y) \stackrel{\text{\tiny def}}{=} y^{\top} A x + c^{\top} x b^{\top} y$

Question #1

How can we design efficient methods for solving box-simplex games?

Question #2

How can we leverage box-simplex solvers to solve continuous and combinatorial optimization problems?

Talk Plan (Today and Tomorrow)

- Box: $B_{\infty}^n \stackrel{\text{def}}{=} \{x \in \mathbb{R}^n \mid ||x||_{\infty} \leq 1\}$
- Simplex: $\Delta^m \stackrel{\text{\tiny def}}{=} \{ y \in \mathbb{R}^m_{>0} \mid ||y||_1 = 1 \}$
- $\min_{x \in B_{\infty}^{n}} \max_{y \in \Delta^{m}} f(x, y) \stackrel{\text{\tiny def}}{=} y^{\mathsf{T}} A x + c^{\mathsf{T}} x b^{\mathsf{T}} y$



Applications

Part 3 Algorithms

- Primal and dual problems
- Approximate solutions
- Discuss state-of-the-art runtimes

Friday Interior Point Methods

- Box-constrained ℓ_{∞} -regression
- Linear programming •
- Maximum cardinality bipartite matching •
- Undirected maximum flow
- ℓ_{∞} -Gradient Descent (constrained steepest descent)
- ℓ_1 -Mirror Descent (multiplicative weights)
- Mirror prox and primal dual regularizers

Primal Problem

- Box: $B_{\infty}^n \stackrel{\text{\tiny def}}{=} \{ x \in \mathbb{R}^n \mid ||x||_{\infty} \le 1 \}$
- Simplex: $\Delta^m \stackrel{\text{\tiny def}}{=} \{ y \in \mathbb{R}^m_{\geq 0} \mid \|y\|_1 = 1 \}$
- $\min_{x \in B_{\infty}^{n}} \max_{y \in \Delta^{m}} f(x, y) \stackrel{\text{def}}{=} y^{\mathsf{T}} \mathbf{A} x + c^{\mathsf{T}} x b^{\mathsf{T}} y$

Lemma:
$$\max_{x \in \Delta^m} d^{\mathsf{T}} x = \max_{i \in [m]} d_i$$
 for all $d \in \mathbb{R}^m$ and therefore
$$f_{\max}(x) \stackrel{\text{def}}{=} \max_{y \in \Delta^m} f(x, y) = c^{\mathsf{T}} x + \max_{i \in [m]} [Ax - b]_i$$

Proof:

- Let $i_* \in \operatorname{argmax}_{i \in [m]} d_i$. Note that $\vec{1}_{i_*} \in \Delta^m$.
 - $\Rightarrow \max_{x \in \Delta^m} d^\top x \ge d^\top \vec{1}_{i_*} = d_{i_*} = \max_{i \in [m]} d_i$
- $d_i \leq d_{i_*}$ and $x_i \geq 0$ for $x \in \Delta^m$ and $i \in [m]$
 - $\Rightarrow \max_{x \in \Delta^m} d^\top x = \max_{x \in \Delta^m} \sum_{i \in [m]} d_i x_i \le \max_{x \in \Delta^m} \sum_{i \in [m]} d_{i_*} x_i = d_{i_*} = \max_{i \in [m]} d_i$

Dual Problem

• Box:
$$B_{\infty}^n \stackrel{\text{\tiny def}}{=} \{ x \in \mathbb{R}^n \mid ||x||_{\infty} \le 1 \}$$

- Simplex: $\Delta^m \stackrel{\text{\tiny def}}{=} \{ y \in \mathbb{R}^m_{\geq 0} \mid \|y\|_1 = 1 \}$
- $\max_{y \in \Delta^m} \min_{x \in B_{\infty}^n} f(x, y) \stackrel{\text{\tiny def}}{=} y^{\mathsf{T}} A x + c^{\mathsf{T}} x b^{\mathsf{T}} y$

Lemma: $\min_{x \in B_{\infty}^{n}} d^{\mathsf{T}}x = -\|d\|_{1} \text{ for all } d \in \mathbb{R}^{n} \text{ and therefore}$ $f_{\min}(y) \stackrel{\text{def}}{=} \min_{x \in B_{\infty}^{n}} f(x, y) = -b^{\mathsf{T}}y - \|A^{\mathsf{T}}y - b\|_{1}$

Proof:

• Let $sign(d) \in \mathbb{R}^n$ with $sign(d)_i$ as 1 if $d_i > 0$, -1 if $d_i < 0$, and 0 othewise

•
$$\Rightarrow \min_{x \in B_{\infty}^{n}} d^{\mathsf{T}}x \le d^{\mathsf{T}} (-\operatorname{sign}(d)) = -\sum_{i \in [n]} |d_{i}| = -||d||_{1}$$

•
$$|x_i| \le 1$$
 for all $x \in B_\infty^n$ and $i \in [n]$
• $\Rightarrow \min_{x \in B_\infty^n} d^\top x = \min_{x \in B_\infty^n} -\sum_{i \in [n]} |d_i| |x_i| \ge \min_{x \in B_\infty^n} -\sum_{i \in [n]} |d_i| = -||d||_1$

Primal Dual Relationship

Primal Problem

- $\min_{x \in B_{\infty}^{n}} f_{\max}(x) = \max_{y \in \Delta^{m}} f(x, y)$
- $f_{\max}(x) = c^{\top}x + \max_{i \in [m]} [Ax b]_i$

- Box: $B_{\infty}^n \stackrel{\text{def}}{=} \{x \in \mathbb{R}^n \mid ||x||_{\infty} \le 1\}$
- Simplex: $\Delta^m \stackrel{\text{\tiny def}}{=} \{ y \in \mathbb{R}^m_{\geq 0} \mid \|y\|_1 = 1 \}$
- $\min_{x \in B_{\infty}^{n}} \max_{y \in \Delta^{m}} f(x, y) \stackrel{\text{def}}{=} y^{\top} A x + c^{\top} x b^{\top} y$

Dual Problem

- $\max_{y \in \Delta^m} f_{\min}(y) = \min_{x \in B_{\infty}^n} f(x, y)$
- $f_{\min}(y) = -b^{\mathsf{T}}y \|A^{\mathsf{T}}y b\|_1$

Comparison

- Trivially: $f_{\max}(x) \ge f_{\min}(y)$ (weak duality)
- Interestingly: $\min_{x \in B_{\infty}^{n}} f_{\max}(x) = \max_{y \in \Delta^{m}} f_{\min}(y)$ (strong duality)

We will prove algorithmically later

Approximate Solutions

Primal Problem

- $\min_{x \in B_{\infty}^{n}} f_{\max}(x) = \max_{y \in \Delta^{m}} f(x, y)$
- $f_{\max}(x) = c^{\top}x + \max_{i \in [m]} [Ax b]_i$

- Box: $B_{\infty}^n \stackrel{\text{\tiny def}}{=} \{ x \in \mathbb{R}^n \mid ||x||_{\infty} \le 1 \}$
- Simplex: $\Delta^m \stackrel{\text{\tiny def}}{=} \{ y \in \mathbb{R}^m_{\geq 0} \mid \|y\|_1 = 1 \}$
- $\min_{x \in B_{\infty}^{n}} \max_{y \in \Delta^{m}} f(x, y) \stackrel{\text{def}}{=} y^{\mathsf{T}} A x + c^{\mathsf{T}} x b^{\mathsf{T}} y$

Dual Problem

•
$$\max_{y \in \Delta^m} f_{\min}(y) = \min_{x \in B^n_{\infty}} f(x, y)$$

• $f_{\min}(y) = -b^{\top}y - ||A^{\top}y - b||_1$

Approximate Solutions

- Let $x_* \in \underset{x \in B_{\infty}^n}{\operatorname{argmin}} f_{\max}(x)$ and $y_* \in \underset{y \in \Delta^m y \in \Delta^m}{\operatorname{argmax}} f_{\min}(y)$
- ϵ -approximate primal solution: $x_{\epsilon} \in B_{\infty}^{n}$ with $f_{\max}(x_{\epsilon}) \leq f_{\max}(x_{*}) + \epsilon$
- ϵ -approximate dual solution: $y_{\epsilon} \in \Delta^m$ with $f_{\min}(y_{\epsilon}) \ge f_{\min}(y_*) \epsilon$
- ϵ -approximate (primal-dual) saddle point (or equilibrium): $(x_{\epsilon}, y_{\epsilon}) \in B_{\infty}^{n} \times \Delta^{m}$

$$f_{\max}(x_{\epsilon}) - f_{\min}(y_{\epsilon}) \le \epsilon$$

Equilibrium

- Primal Problem
- $\min_{x \in B^n_{\infty}} f_{\max}(x) = \max_{y \in \Delta^m} f(x, y)$
- $f_{\max}(x) = c^{\top}x + \max_{i \in [m]} [Ax b]_i$

- Box: $B_{\infty}^{n} \stackrel{\text{\tiny def}}{=} \{ x \in \mathbb{R}^{n} \mid ||x||_{\infty} \leq 1 \}$
- Simplex: $\Delta^m \stackrel{\text{\tiny def}}{=} \{ y \in \mathbb{R}^m_{\geq 0} \mid \|y\|_1 = 1 \}$
- $\min_{x \in B_{\infty}^{n}} \max_{y \in \Delta^{m}} f(x, y) \stackrel{\text{def}}{=} y^{\top} A x + c^{\top} x b^{\top} y$

Dual Problem

- $\max_{y \in \Delta^m} f_{\min}(y) = \min_{x \in B^n_{\infty}} f(x, y)$
- $f_{\min}(y) = -b^{\top}y \|A^{\top}y b\|_1$

<u>e-approximate (primal-dual) saddle point (or equilibrium)</u>

- **Definition**: $(x_{\epsilon}, y_{\epsilon}) \in B_{\infty}^n \times \Delta^m$ and $f_{\max}(x_{\epsilon}) f_{\min}(y_{\epsilon}) \le \epsilon$
- **Duality gap**: $gap(x_{\epsilon}, y_{\epsilon}) = f_{max}(x_{\epsilon}) f_{min}(y_{\epsilon})$
 - Total $f(x_{\epsilon}, y_{\epsilon})$ change by best responses: $= f_{\max}(x_{\epsilon}) f(x_{\epsilon}, y_{\epsilon}) + [f(x_{\epsilon}, y_{\epsilon}) f_{\min}(y_{\epsilon})]$
 - Sum of x_{ϵ} and y_{ϵ} suboptimality: $= f_{\max}(x_{\epsilon}) f(x_{\epsilon}, y_{\epsilon}) + [f(x_{\epsilon}, y_{\epsilon}) f_{\min}(y_{\epsilon})]$

Don't need x_* and y_* to compute!

State-of-the-art

- Box: $B_{\infty}^n \stackrel{\text{\tiny def}}{=} \{x \in \mathbb{R}^n \mid ||x||_{\infty} \le 1\}$
- Simplex: $\Delta^m \stackrel{\text{\tiny def}}{=} \{ y \in \mathbb{R}^m_{\geq 0} \mid \|y\|_1 = 1 \}$
- $\min_{x \in B_{\infty}^{n}} \max_{y \in \Delta^{m}} f(x, y) \stackrel{\text{def}}{=} y^{\top} A x + c^{\top} x b^{\top} y$

Theorem: there is a method which can compute an ϵ -approximate saddle point in time $\tilde{O}(nnz(A) ||A||_{op,\infty}/\epsilon)$

Nearly linear time algorithm

Notation

- $\operatorname{nnz}(A) \stackrel{\text{\tiny def}}{=} n + m + \operatorname{number} \operatorname{of} \operatorname{nonzero} \operatorname{entries} \operatorname{in} A$
- $||A||_{\text{op},\infty} \stackrel{\text{\tiny def}}{=} \sup_{x \neq 0} \frac{||Ax||_{\infty}}{||x||_{\infty}} = \max \ell_1 \text{ norm of row of } A$

size of the input

- " ℓ_{∞} operator norm" bounds up to constant how suboptimal primal/dual solutions which just optimize *b* and *c* are
- $\tilde{O}(\cdot)$ hides logarithmic factors in nnz(A), $||A||_{op,\infty}/\epsilon$

First-order method

- Box: $B_{\infty}^n \stackrel{\text{def}}{=} \{x \in \mathbb{R}^n \mid ||x||_{\infty} \le 1\}$
- Simplex: $\Delta^m \stackrel{\text{\tiny def}}{=} \{x \in \mathbb{R}^m_{\geq 0} \mid ||x||_1 = 1\}$
- $\min_{x \in B_{\infty}^{n}} \max_{y \in \Delta^{m}} f(x, y) \stackrel{\text{\tiny def}}{=} y^{\top} A x + c^{\top} x b^{\top} y$

Theorem: there is a method which solves box-simplex games to accuracy ϵ in time $\tilde{O}(nnz(A) ||A||_{op,\infty}/\epsilon)$.

- First order method: only access objective by evaluating the function and computing the gradient, $\nabla f(x, y) = (A^{T}y + c, Ax b)$
- Note: only need b, c, and matrix vector multiplies.
 - Can compute in parallel $\tilde{O}(1)$ depth and O(nnz(A)) work.
- The method for this theorem?
 - First order method + matrix vector multiplies with |A|

Entrywise absolute value

• Parallel with $ilde{O}(1)$ depth

History and More State-of-the-art

First Order Methods

- $\tilde{O}(\operatorname{nnz}(A) \|A\|_{\operatorname{op},\infty} / \epsilon)$
 - First in [S17]
 - Later variants (influencing this presentation [J**S**T19,C**S**T21,AJJ**S**T21]
- Prior state of the art
 - $\tilde{O}(\text{nnz}(A) ||A||_{\text{op},\infty}^2 / \epsilon^2)$ folklore / [S13, KLO**S**14] (influencing this presentation)
 - $\tilde{O}(nnz(A)\sqrt{n}||A||_{op,\infty}/\epsilon)$ AGD and smoothing.
- [ST18] alternative approach and improvements in sparse case

Interior Point Methods

- [CLS19,B20] $\tilde{O}(\max\{m,n\}^{\omega})$ where $\omega < 2.373$ is fast matrix multiplication constant
- [BLLS**S**SW21] $\tilde{O}(mn + \min\{m, n\}^{2.5})$
- [LS14,LS15] $\tilde{O}(nnz(A)\sqrt{\min\{m,n\}} + \min\{m,n\}^{2.5})$

w < 2.373 is current fast matrix multiplication (FMM) constant [W13]







<u>Part 3</u> Algorithms

- Primal and dual problems
- Approximate solutions
- Discuss state-of-the-art runtimes

<u>Friday</u> Interior Point Methods

Box: $B_{\infty}^{n} \stackrel{\text{def}}{=} \{x \in \mathbb{R}^{n} \mid ||x||_{\infty} \leq 1\}$

Simplex: $\Delta^m \stackrel{\text{\tiny def}}{=} \{y \in \mathbb{R}^m_{>0} \mid ||y||_1 = 1\}$

 $\min_{x \in B_{\infty}^{n}} \max_{y \in \Delta^{m}} f(x, y) \stackrel{\text{\tiny def}}{=} y^{\mathsf{T}} \mathbf{A} x + c^{\mathsf{T}} x - b^{\mathsf{T}} y$

- Box-constrained ℓ_{∞} -regression
- Linear programming
- Maximum cardinality bipartite matching
- Undirected maximum flow
- ℓ_{∞} -Gradient Descent (constrained steepest descent)
- ℓ_1 -Mirror Descent (multiplicative weights)
- Mirror prox and primal dual regularizers

Problem #1: Box-constrained ℓ_{∞} -Regression

Box-constrained ℓ_{∞} Regressioon

- Input: matrix $A \in \mathbb{R}^{m \times n}$ and vector $b \in \mathbb{R}^m$
- **Problem**: $OPT_{\infty} = \min_{x \in B_{\infty}^{n}} ||Ax b||_{\infty}$
- **Goal**: find ϵ -additive approximation, i.e. $x_{\epsilon} \in B_{\infty}^{n}$ with $||Ax_{\epsilon} b||_{\infty} \leq OPT_{\infty} + \epsilon$

Claim: can compute in $\tilde{O}(nnz(A) ||A||_{op,\infty} \epsilon^{-1})$ **Proof**:

- $||Ax b||_{\infty} = \max_{i \in [m]} [\max\{[Ax b]_i, -[Ax b]_i\}] = \max_{y \in \Delta^{2m}} y^{\top} {Ax b \choose -(Ax b)}$
- New matrix has same $\|\cdot\|_{op,\infty}$ and just double nnz

Problem #2: Linear Programming

Approximate Linear Programming

• Input: $A \in \mathbb{R}^{m \times n}$, $b \in \mathbb{R}^m$, $c \in \mathbb{R}^n$, and $\epsilon, \delta, D \ge 0$

• **Problem**:
$$OPT_{lp} = \min_{x \in \mathbb{R}^n \mid Ax \ge b} c^{\top}x$$

- **Promise**: $\exists x_*^{\text{lp}} \in \underset{x \in \mathbb{R}^n \mid Ax \ge b}{\operatorname{argmin}} c^{\top}x \text{ with } \left\| x_*^{\text{lp}} \right\|_{\infty} \le D$
- **Goal**: find $x_{\epsilon,\delta}$ with $c^{\mathsf{T}}x_{\epsilon,\delta} \leq \operatorname{OPT}_{\operatorname{lp}}$ and $Ax_{\epsilon,\delta} \geq b \delta \vec{1}$

Notes

- One of many ways to formulate the problem.
- Key difficulty: how handle that constraint $Ax \ge b$?
- Recurring idea: penalty functions in the objective

Linear Programming

Approach

- $p(x) \stackrel{\text{\tiny def}}{=} M \cdot \max\left\{0, \max_{i \in [m]} [b Ax]_i\right\}$
- OPT_p = $\min_{x \in \mathbb{R}^n | \|x\|_{\infty} \le R} c^{\mathsf{T}} x + p(x)$

<u>Claim</u>: For $M = (\epsilon + 2 ||c||_1 R) \delta^{-1}$ any ϵ approximate minimizer to OPT_p problem is (ϵ, δ) -approximate linear program solution.

<u>Theorem</u>: Can compute (ϵ, δ) -approximate linear program solution in

$$\tilde{O}\left(\operatorname{nnz}(\boldsymbol{A}) \cdot \frac{D \|\boldsymbol{A}\|_{op,\infty}}{\delta} \max\left\{1, \frac{D \|\boldsymbol{c}\|_{1}}{\epsilon}\right\}\right)$$

Input: $A \in \mathbb{R}^{m \times n}$, $b \in \mathbb{R}^{m}$, $c \in \mathbb{R}^{n}$, and $\epsilon, \delta, D \ge 0$ **Problem**: $OPT_{lp} = \min_{x \in \mathbb{R}^{n} \mid Ax \ge b} c^{\top}x$ **Promise**: $\exists x_{*}^{lp} \in \operatorname*{argmin}_{x \in \mathbb{R}^{n} \mid Ax \ge b} c^{\top}x$ with $\|x_{*}^{lp}\|_{\infty} \le D$ **Goal**: find $x_{\epsilon,\delta}$ with $c^{\top}x \le OPT_{lp}$ and $Ax \ge b - \delta\vec{1}$

Proof of Theorem from Claim

Can write penalized problem as box-simplex

•
$$\bar{x} = D^{-1}x$$
 and $\bar{c} = Dc$
• $\bar{A} = \begin{pmatrix} -DMA \\ \vec{0}_n^{\mathsf{T}} \end{pmatrix}$ and $b = \begin{pmatrix} -Mb \\ \vec{0}_n^{\mathsf{T}} \end{pmatrix}$

Penalized problem is the same as

$$\min_{\bar{x}\in B_{\infty}^{n}} \bar{c}^{\top}\bar{x} + \max_{i\in[m+1]} [\overline{A}\bar{x} - b]_{i}$$

Note that $\|\overline{A}\|_{op,\infty} = O(DM \|A\|_{op,\infty})$ and $M/\epsilon = O(\delta^{-1} \max\{1, D \|c\|_1 \epsilon^{-1}\})$

Linear Programming

Approach

- $p(x) \stackrel{\text{\tiny def}}{=} M \cdot \max\left\{0, \max_{i \in [m]} [b Ax]_i\right\}$
- OPT_p = $\min_{x \in \mathbb{R}^n | \|x\|_{\infty} \le R} c^{\mathsf{T}} x + p(x)$

<u>Claim</u>: For $M = (\epsilon + 2 ||c||_1 R) \delta^{-1}$ any ϵ approximate minimizer to OPT_p problem is (ϵ, δ) -approximate linear program solution.

<u>**Theorem</u>**: Can compute (ϵ, δ) -approximate linear program solution in</u>

$$\tilde{O}\left(\operatorname{nnz}(\boldsymbol{A}) \cdot \frac{D \|\boldsymbol{A}\|_{op,\infty}}{\delta} \max\left\{1, \frac{D \|\boldsymbol{c}\|_{1}}{\epsilon}\right\}\right)$$

Input: $A \in \mathbb{R}^{m \times n}$, $b \in \mathbb{R}^{m}$, $c \in \mathbb{R}^{n}$, and $\epsilon, \delta, D \ge 0$ **Problem**: $OPT_{lp} = \min_{x \in \mathbb{R}^{n} \mid Ax \ge b} c^{\top}x$ **Promise**: $\exists x_{*}^{lp} \in \operatorname*{argmin}_{x \in \mathbb{R}^{n} \mid Ax \ge b} c^{\top}x$ with $\|x_{*}^{lp}\|_{\infty} \le D$ **Goal**: find $x_{\epsilon,\delta}$ with $c^{\top}x \le OPT_{lp}$ and $Ax \ge b - \delta\vec{1}$

Proof of Claim

- Let x_{ϵ} be ϵ -approximate minimizer
- Since x_*^{lp} is feasible for penalized problem, $OPT_p \le OPT_{lp}$
- $c^{\top}x_{\epsilon} + p(x_{\epsilon}) \le OPT_{p} + \epsilon \le OPT_{lp} + \epsilon$

•
$$p(x_{\epsilon}) \leq \epsilon + c^{\mathsf{T}}(x_*^{\mathrm{lp}} - x_{\epsilon})$$

•
$$c^{\top} \left(x_*^{\operatorname{lp}} - x_{\epsilon} \right) \le \| c \|_1 \left\| x_*^{\operatorname{lp}} - x_{\epsilon} \right\|_{\infty}$$

•
$$\left\|x_*^{\operatorname{lp}} - x_{\epsilon}\right\|_{\infty} \le \left\|x_*^{\operatorname{lp}}\right\|_{\infty} + \|x_{\epsilon}\|_{\infty}$$

Problem #3: Bipartite Matching

Maximum Cardinality (Bipartite) Matching (MCM)

- Input: undirected, bipartite graph G = (V, E)
- Matching: $M \subseteq E$ such that $e_1 \cap e_2 = \emptyset$ for all $e_1, e_2 \in M$ with $e_1 \neq e_2$
- **Problem**: compute matching M_* of maximum cardinality $|M_*|$
- **Goal**: find (1ϵ) -approximate MCM, i.e. matching M_{ϵ} with $|M_{\epsilon}| \ge (1 \epsilon)|M_{*}|$



MCM History Fundamental, incredibly well-studied, notoriously difficult (to improve) problem.

Year	Authors	Runtime $\widetilde{oldsymbol{ heta}}(\cdot)$		
1969-1973	Dinic, Karzanov, Hopcroft, Karp	$ E \sqrt{ V }$		
1981	Ibarra, Moran	$ V ^{\omega}$		
2013	Mądry	$ E ^{10/7}$	Improvements since 1980s all use interior point methods which we may	
2020	Liu, S	$ E ^{11/8+o(1)}$		
2020	Liu, Kathuria, S	$ E ^{4/3+o(1)}$		
2020	Brand, Lee, Nanongkai, Peng, Saranurak, S , Song, Wang	$ E + V ^{1.5}$	discuss off finday.	

Note: procedure will use very little graph structure.

- **Result**: can use box-simplex solver to compute (1ϵ) -approximate MCM in $\tilde{O}(|E|\epsilon^{-1})$ time and $\tilde{O}(\epsilon^{-1})$ depth
- Time matched by Dinic, Karzanov, Hopcroft, Karp and Allen-Zhu, Orecchia 2015
- Unaware of alternative method that gets this parallelism and this time.
- Alternative method either have large ϵ , |E|, or |V| dependence
- Also, implementable semi-streaming (Assadi, Jambulapati, Jin, S, Tian 2021)

w < 2.373 is current fast matrix multiplication (FMM) constant [W13]

Approach

 $N(a) \stackrel{\text{\tiny def}}{=} \{b \in V \mid \{a, b\} \in E\}$ denotes the neighbors of A

- Input: undirected, bipartite graph G = (V, E)
- **Matching**: $M \subseteq E$; $e_1 \cap e_2 = \emptyset$ for all $e_1, e_2 \in M$ with $e_1 \neq e_2$
- **Problem**: compute matching M_* maximizing $|M_*|$
- **Goal**: matching M_{ϵ} with $|M_{\epsilon}| \ge (1 \epsilon)|M_{*}|$

Fractional Matching: in the MCM problem $f \in \mathbb{R}^{E}_{\geq 0}$ is a fractional matching if for all $a \in V$ it is the case that $\sum_{b \in N(a)} f_{\{a,b\}} \leq 1$.

Theorem [GPST91]: There is an algorithm which given any fractional matching $f \in \mathbb{R}_{\geq 0}^{E}$ can compute an integral matching of cardinality at least $||f||_1$ in time $\tilde{O}(|E|)$ and depth $\tilde{O}(1)$.

Corollary: The minimum ℓ_1 -norm of a fractional matching is $|M_*|$ and it suffices to compute a fractional matching of ℓ_1 -norm $\geq (1 - \epsilon)|M_*|$.

Linear Algebraic Representation

Unsigned (edge-vertex) Incidence Matrix: $|\mathbf{B}| \in \mathbb{R}^{E \times V}$ with $|\mathbf{B}|_{\{a,b\},c} = \begin{cases} 1 & c \in \{a,b\} \\ 0 & \text{otherwise} \end{cases}$ for all $\{a,b\} \in E$ and $c \in V$

Lemma: $f \in \mathbb{R}^{E}_{\geq 0}$ is a fractional matching if and only if $|\mathbf{B}|^{\top} f \leq 1$. **Proof**: $[|\mathbf{B}|^{\top} f]_{a} = \sum_{\{b,c\}\in E} f_{\{b,c\}} |\mathbf{B}|_{\{a,b\},c} = \sum_{b\in N(a)} f_{\{a,b\}}$

Upshot: it suffices to solve $\max_{f \in \mathbb{R}_{\geq 0}^{E} ||\mathbf{B}|^{\mathsf{T}} f \leq \vec{1}} \vec{1}^{\mathsf{T}} f \text{ or equivalently } \min_{f \in \mathbb{R}_{\geq 0}^{E} ||\mathbf{B}|^{\mathsf{T}} f \leq \vec{1}} (-\vec{1})^{\mathsf{T}} f$

Penalty and Rounding

In contrast to previous problem where we just solved approximately and bounded how infeasible, here we add a penalty term that allows us to reason more directly about obtaining a feasible solution.

Overflow (excess): overflow $(f) \stackrel{\text{def}}{=} \max\{\vec{0}, |\boldsymbol{B}|^{\top}f - \vec{1}\}$ entrywise **Note**: $f \in \mathbb{R}^{E}$ is a fractional matching if and only if $\operatorname{overflow}(f) = \vec{0}$

Lemma: given $f \in \mathbb{R}_{\geq 0}^{E}$ let $\tilde{f} \in \mathbb{R}^{E}$ be defined for all $\{a, b\} \in E$ with $\tilde{f}_{\{a,b\}} = 0$ if $f_{\{a,b\}} = 0$ and otherwise $\tilde{f}_{\{a,b\}} = f_{\{a,b\}} \left(1 - \max \left\{ \frac{[\operatorname{overflow}(f)]_{a}}{[|B|^{\top}f]_{a}}, \frac{[\operatorname{overflow}(f)]_{b}}{[|B|^{\top}f]_{b}} \right\} \right)$ Then $0 \leq \tilde{f} \leq f$, \tilde{f} is a fractional matching, and $\|f - \tilde{f}\|_{1} \leq \|\operatorname{overflow}(f)\|_{1}$. **Proof**: $f_{\{a,b\}} \cdot \frac{[\operatorname{overflow}(f)]_{a}}{[|B|^{\top}f]_{a}}$ is the relative contribution of $f_{\{a,b\}}$ to overflow

Upshot: $-|M_*| = \min_{\substack{f \in \mathbb{R}_{\geq 0}^E \\ e \in \mathbb{N}}} -\vec{1}^{\mathsf{T}}f + \sum_{a \in V} [\operatorname{overflow}(f)]_a$ and given any ϵ -additive minimizer can compute matching of size $\geq |M_*| - \epsilon$ in time $\tilde{O}(|E|)$.

The Result

- overflow(f) $\stackrel{\text{\tiny def}}{=} \max\{\vec{0}, |\boldsymbol{B}|^{\mathsf{T}}f \vec{1}\}$
- $\epsilon |M_*|$ additive approximation to $\min_{f \in \mathbb{R}^E_{\geq 0}} -\vec{1}^\top f + \sum_{a \in V} [\operatorname{overflow}(f)]_a$ suffices

Question #1: how to encode overflow(*f*)?

• Tool: max{0,
$$a$$
} = $\frac{1}{2}[a + |a|]$ What is $|B|\vec{1}$? = $2 \cdot \vec{1}$!

• Suffices to compute $\epsilon |M_*|$ additive approximation to

$$\min_{f \in \mathbb{R}_{\geq 0}^{E}} -\vec{1}^{\mathsf{T}}f + \frac{1}{2}\vec{1}^{\mathsf{T}}|\boldsymbol{B}|^{\mathsf{T}}f + \frac{1}{2}|V| + \left\|\frac{1}{2}|\boldsymbol{B}|^{\mathsf{T}}f - \vec{1}\right\|_{1}$$

Question #2: how to put *f* in simplex?

- Suppose $\nu \ge |M_*|$, then suffices to work with $x = \left(\frac{1}{\nu}f, 1 \frac{1}{\nu}||f||_1\right) \in \Delta^{|E|+1}$
- Let $b = (-\frac{\nu}{2}\vec{1}_{|E|}, 0)$, and let $A = \frac{\nu}{2}|B|^{\top}$ with 0 column added
- Suffices to compute $\epsilon |M_*|$ additive approximation to $\min_{x \in \Lambda^{|E|+1}} b^\top x + ||Ax \vec{1}||_1$
- Suffices to compute $\epsilon |M_*|$ additive approximation to $\max_{x \in \Delta^{|E|+1}} -b^\top x \|Ax \vec{1}\|_1$
- Note that $||A||_{op,\infty} = \nu$ so can solve in $\tilde{O}\left(\frac{|E|\nu}{\epsilon |M_*|}\right)$.
- Get result by picking ν as every power of 2 between 0 and 2|V|!

Can also computing 2 approximation by greedy.

Improvable?

Theorem: Given any algorithm which compute an ϵ -approximate MCM for any input $\epsilon \in (0,1)$ in time $\tilde{O}(|E|\epsilon^{-\delta})$ for some fixed constant δ , there is an algorithm that computes exact MCM in time $\tilde{O}(|E| \cdot |V|^{\frac{\delta}{1+\delta}})$.

Proof

- Given any ϵ -approximate MCM, there are at most $\epsilon |M_*| \le \epsilon |V|$ more edges that could be matched.
- Augmenting paths finds at least one more matched edge in time O(|E|)
- Total time: $\tilde{O}(|E|\epsilon^{-\delta} + \epsilon|E||V|)$ solving for δ yields result

Implication: $\tilde{O}(|E|\epsilon^{-1})$ time $(1 - \epsilon)$ -approximate MCM yields $\tilde{O}(|E|\sqrt{|V|})$ time exact MCM **Barrier to improving**: only improvements known to date use interior point methods

Problem #4: Flow Problems

• Graph G = (V, E)

• Vertices $s, t \in V$



<u>Goal</u> Send 1 unit of flow, $f \in \mathbb{R}^{E}$, between *s* and *t* in the "best" way possible.

Natural family of problems in combinatorial optimization.



Introduce maximum flow problem more formally



Note: there are additional improvements with $\log(\epsilon^{-1})$.

Such results give exact directed flow algorithms. Undirected Maxflow



 $\frac{(1-\epsilon)\text{-}Approximate Flow}{\text{feasible }s \rightarrow t \text{ flow of value } \geq (1-\epsilon)OPT}$

		Authors	Time for ϵ -Approximate Undirected Flow	Capacitated (U \neq 1)
0	ſ	:	÷	÷
ℓ ₁ -ish	1	[Kar98]	$\tilde{O}(m\sqrt{n}\epsilon^{-1})$	Yes
_	ī	[CKMST11]	$\tilde{O}(mn^{1/3}\epsilon^{-11/3})$	Yes
ℓ_2	ſ	[LRS13]	$ ilde{O}(mn^{1/3}\epsilon^{-2/3}$	No
	Ì	[S13,KLO S 14]	$O(m^{1+o(1)}\epsilon^{-2})$	Yes
0		[P16]	$\tilde{O}(m\epsilon^{-2})$	Yes
ℓ_{∞}	ſ	[S17]	$\tilde{O}(m\epsilon^{-1})$	Yes
1	L	[S T18]	$\tilde{O}(m + \sqrt{mn}\epsilon^{-1})$	Yes

<u>How?</u> Work more directly in ℓ_{∞} . Reduction to and methods for box-simplex-like games. **Step 1** (Combinatorial Advance) Build coarse ℓ_{∞} -approximator (e.g. oblivious routing or congestion approximator) to change representation. <u>Step 2</u> (Optimization Advance) Apply iterative method to boost accuracy (e.g. gradient descent, area-convex dual extrapolation, mirror prox, coordinate descent) <u>Note</u> (Further Implications) Parallel optimal transport [JST19], streaming matching [JST20], optimization methods [CST21]

Talk Plan



 $\frac{(1 - \epsilon) \text{-} Approximate Flow}{\text{feasible } s \to t \text{ flow of value } \geq (1 - \epsilon) OPT}$

	Authors	Time for ϵ -Approximate Undirected Flow	Capacitated (U \neq 1)
0	f :	÷	÷
l_1 -ish	[Kar98]	$\tilde{O}(m\sqrt{n}\epsilon^{-1})$	Yes
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	[S13,KLO S 14]	$O(m^{1+o(1)}\epsilon^{-2})$	Yes
0	[P16]	$\tilde{O}(m\epsilon^{-2})$	Yes
t_{∞}	[S17]	$\tilde{O}(m\epsilon^{-1})$	Yes
	[S T18]	$\tilde{O}(m + \sqrt{mn}\epsilon^{-1})$	Yes

- Talk 1 & 2: Focus on $\tilde{O}(m\epsilon^{-1})$ runtime.
- Talk 3: Discuss state-of-the art small ϵ results

Thank you

Questions?

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