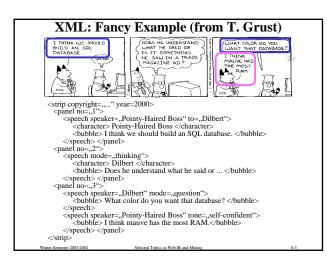
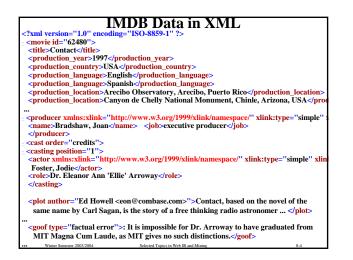
8 Ranked Retrieval of XML Data

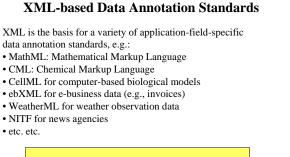
- 8.1 Basics of XML and XPath
- 8.2 Search with Ontological Similarities (XXL, COMPASS)
- 8.3 Search with Structural Similarities (XSEarch)
- 8.4 Text Adjacency Search (XRank)

8.1 Basic Concepts of XML • (Freely definable) tags: book, title, author • with start tag: <book> etc. • and end tag: </book> etc. • Elements: <book> ... </book> Elements have a name (book) and a content (...) Elements may be nested. · Each XML document has a root element and forms a tree. Element content may be typed (mostly PCDATA parsed character data, i.e., strings, possibly with nested elements). Elements may have attributes that have a name and a value (content), e.g. <article year=1999> Elements optionally have id attributes (element ids) from which references within a document can be constructed via idref attributes. Elements may have outgoing hyperlinks via href attributes.

Elements with a common parent are ordered.







XML is mere syntax, but it creates a momentum towards standardized terminologies (ontologies), thus potentially enabling large-scale data exchange (and more effective information search)

CML Example

<cml title=,,ethanol" id=,,cml_ethanol_karne"> <molecul title=,,ethanol" id=mol_ethanol_karne"> <formula> C2 H6 O </formula> <string title=,,CAS">64-17-5</string> <float title=,,molecular weight">46.07</float> <atomArray> <atom id=,,ethanol_karne_a_1"> <float builtin=,,x3" units=,,A">1.0303</float> <float builtin=,,y3" units=,,A">0.8847</float> <float builtin=,,z3" units=,,A">0.9763</float> <string builtin=,,elementType">C</string> </atom> <atom id=,,ethanol_karne_a_2"> ... </atom> .. </atomArray> <bondArray> <body>
did=..ethanol karne b 1"></br> <string builtin=,,atomRef">ethanol_karne_a_1</string> <string builtin=,,atomRef">ethanol_karne_a_2</string> <string builtin=..order" convention=..MDL">1</string> </bond>

Boolean Retrieval with XPath and XQuery

XPath and XQuery are query languages for XML data, both standardized by the W3C and supported by various database products. Their search capabilities include

- logical conditions over element and attribute content (first-order predicate logic a la SQL; simple conditions only in XPath)
- regular expressions for pattern matching of element names along paths or subtrees within XML data
- + joins, grouping, aggregation, transformation, etc. (XQuery only)

In contrast to database query languages like SQL an XML query does not necessarily (need to) know a fixed structural schema for the underlying data.

A **query result** is a set of qualifying nodes, paths, subtrees, or subgraphs from the underyling data graph,

or a set of XML documents constructed from this raw result.

XPath by Examples

/movie/casting/actor	all actors in the castings of all movies		
/movie[title=,,Contact"]/casting	all people in the casting of a given movie		
/movie[title=,,Contact"]//actor /movie[title=,,Contact"]/*/actor	all actors in a given movie		
/movie/casting[@position=1]/actor	all stars		
/movie[casting/actor = ,,Foster, Jodie]//title	titles of movies with a given actor		
/movie[casting/actor = ,,Foster, Jodie]/casting[@position=1]/actor stars of movies with a given actor			
/movie[//goof]/casting/* /movie/casting/*[ancestor::*[name() = goof]]	casting details for movies with goofs		

Semantics of XPath Queries

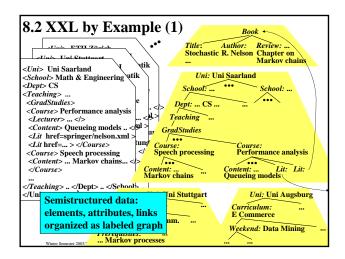
An XPath **path expression** (the core of a query) is a sequence of **location steps**, separated by /, each of which has

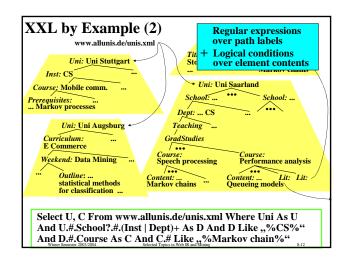
- a navigation axis (e.g., children denoted by /, descendants //, etc.) relative to a context node (i.e., a current node) and a
- condition to be matched, which may in turn be a path expression with a logical condition for the end node of a qualifying path

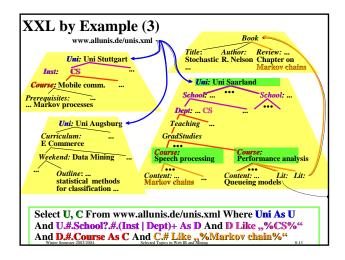
The evaluation of a path expression computes a function nodes $\rightarrow 2^{nodes}$,

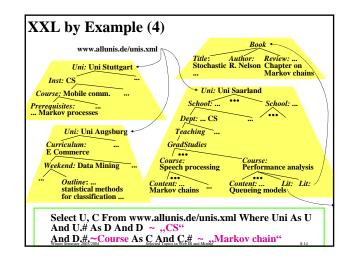
i.e., determines for a given initial context node the set of nodes that are reachable by the given sequence of location steps and whose paths satisfy all specified conditions.

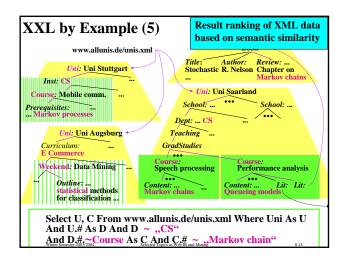
XPath Location Axes The general form of a location step is <i>axis::test[predicate]</i> where test is a function on a node (with Boolean result, e.g., referring to the element name or position) and predicate is a function or a path expression			
Axis	Shortcut	Comment_	
child::node()		node() is true for all nodes	
descendant::node()	//		
descendant-or-self::node()			
self::node()			
parent::node()			
ancestor::node()			
ancestor-or-self::node()			
following::node()		in preorder traversal of doc tree	
preceding::node()		-	
following-sibling::node()		siblings to the right	
preceding-sibling::node()		siblings to the left	
attribute::	@	-	

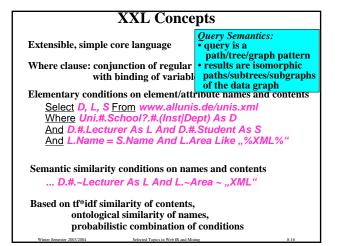


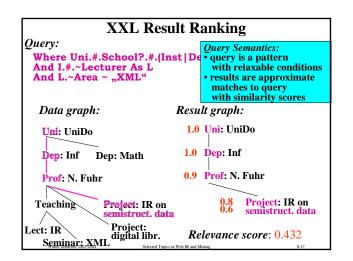


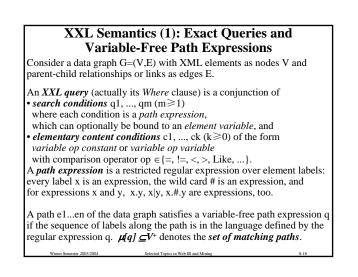












XXL Semantics (2): Exact Queries with Variables

Every path expression can have an optional As clause which binds the end points of the qualifying paths to an element variable.

The "uses" relation between path expressions q1, ..., qm of the same query is defined as follows: qi < qj (qj uses qi) if qj contains a variable that is bound to the qualifying paths of qi, We restrict the uses relation such that its transitive closure is irreflexive and acyclic.

A path expression qi may contain element variables. The elements that are bound to the variables are substituted into p. For a given variable binding v: VAR \rightarrow V, the *result* $\mu_v[qi] \subseteq V^+$

of qi containing variables x, y, ... is $\mu[qi[x/v(x).name, y/v(y).name, ...]]$.

A subgraph of G is a *result of the query* with path expressions q1, ..., qm and elementary content conditions c1, ..., ck with variables x, y, ... if there is a (global) variable binding v such that the subgraph is the union of paths p1, ..., pm with $pi \in \mu_v[qi]$ for all i

the subgraph is the union of paths p1, ..., pm with pi $\in \mu_{v}[qi]$ for all and cj[x/v(x).content, y/v(y).content, ...] evaluates to true for all j.

Assume that similarity functions are defined between element names and between texts (and between dates, spatial names, etc.) An element with label *l* **approximately matches** subcondition ~*label* in path expression qi if the similarity sim(l, label) > 0. An element with content *c* bound to variable *x* approximately matches elementary content condition $x \sim const$ if sim(c, const) > 0, and two elements with contents *c*, *c* ' bound to variables *x*, *x* ' approximately satisfy elementary content condition $x \sim x'$ if sim(c,c') > 0. A subgraph of G is an **approximate result** of query q with path expressions q1, ..., qm and elementary content conditions c1, ..., ck with variables x, y, ... if there is a (global) variable binding v such that

XXL Semantics (3): Queries with Similarity Conditions

the subgraph is the union of paths p1, ..., pm such that

• pi is an approximate result in $\mu_{v}[qi]$ for all i and

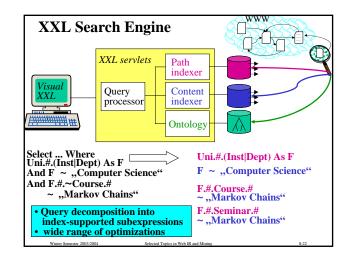
• cj[x/v(x)].content, y/v(y).content, ...] is approximately satisfied for all j

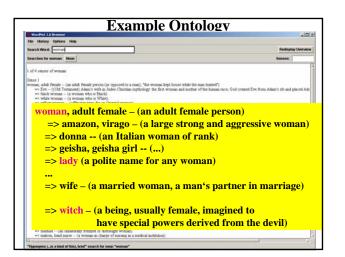
XXL Semantics (4): Query Result Scoring

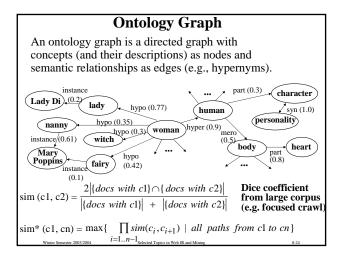
An *element e or a path p is scored*with regard to a subcondition of the form *x*, #, *x/y*, ~*x* by the the similarity with which it approximately matches the subcondition, and an *element e or a pair (e, e') of elements is scored*with regard to an elementary content condition *x* ~ *const* or *x* ~ *x'* by the similarity between e and the given constant or between e and e'.
An approximately matching *subgraph is scored*

with regard to a query by the product of the scores of its components with regard to the underlying path subconditions and elementary content conditions.

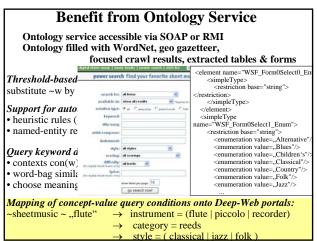
The *result of an XXL query with similarity conditions* is a ranked list of approximately matching subgraphs in descending order of scores.

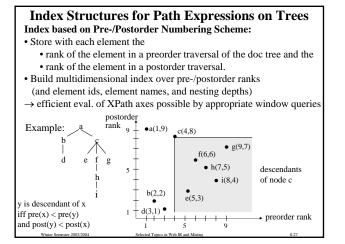


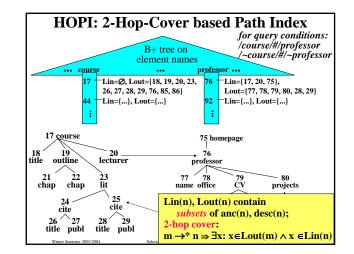




Benefit from Ontology Service	
Ontology service accessible via SOAP or RMI Ontology filled with WordNet, geo gazetteer, focused crawl results, extracted tables & forms	
Threshold-based query expansion: substitute ~w by $(c_1 c_k)$ with all c_i for which $sim(w, c_i) \ge \delta$	
 Support for automatic tagging of HTML data: heuristic rules (<homepage>, <publication>, table headings, etc.)</publication></homepage> named-entity recognition (persons, companies, cities, temporal phrases) 	
<i>Query keyword disambiguation:</i> • contexts con(w) and con(ci) for word w and concepts c _i ∈ {c ₁ ,, c _k } • word-bag similarity sim(con(w), con(c)) based on cos or KL diff • choose meaning argmax _c {sim(con(w), con(c))}	
Mapping of concept-value query conditions onto Deep-Web portals: ~sheetmusic ~ "flute" → instrument = (flute piccolo recorder) → category = reeds → style = (classical jazz folk)	

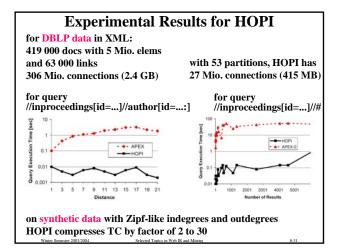


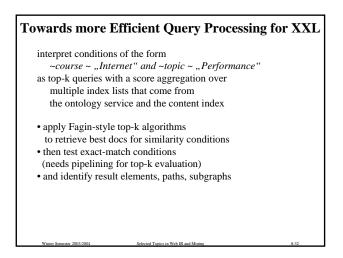




Constructing a 2-Hop Cover			
Definition (E. Cohen et al., SODA 2002):			
a <i>2-hop cover</i> of a graph G=(V,E)			
is a labeling (Lin, Lout) of all nodes where			
1. $\operatorname{Lin}(n) \subseteq \{m \mid m \to * n\}, \operatorname{Lout}(n) \subseteq \{p \mid n \to * p\}, \text{ and }$			
2. \forall (m,n) \in E+ \exists center node x with x \in Lout(m) \land x \in Lin(n)			
Theorem (Cohen et al.):			
The size of a 2-hop cover is $\sum_{n \in V} Lin(n) + Lout(n) $.			
Finding a minimal 2-hop cover is NP-complete.			
Polynomial Algorithm with O(log	+ keep center graphs in priority queue + incrementally update center subgraphs		
T' := E+ //uncovered connections;	+ avoid complete transitive closure		
while T' ≠Ø {	+ support incremental updates		
for each node n construct center graph			
$C(n) := \{(m,p) \mid (m,n), (n,p) \in E+\};$			
find node n with densest subgraph $S(n)$ of $C(n) \cap T'$; Lin(n) := sources of $S(n)$; Lout(n) := sinks of $S(n)$;			
remove edges of $S(n)$; from T^{ϵ} };			
remote euges of B(ii) from T j,			

Efficient HOPI Construction
 Divide-and-conquer: Partition G by partitioning the XML document graph (using greedy heuristics) with node weights = #elems in doc & edge weights = #cross-doc links Compute 2-hop cover for each partition Merge covers: for each cross-partition edge x → y with x∈P, y∈Q add x to Lout(a) for all a ∈ P with a →* x and
to Lin(b) for all $b \in P$ with $y \to *b$
Implementation: stores Lin and Lout sets in database tables Lin (Id, InId) with indexes on <i>Id InId</i> and <i>InId Id</i> Lout (Id, OutId) with indexes on <i>Id OutId</i> and <i>OutId Id</i> Elems (Id, ElemName) efficiently supports connection queries for all XPath axes on arbitrary XML data graphs



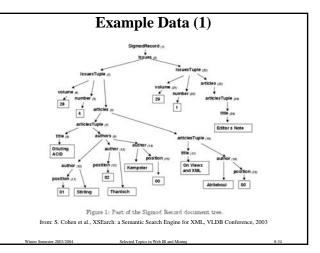


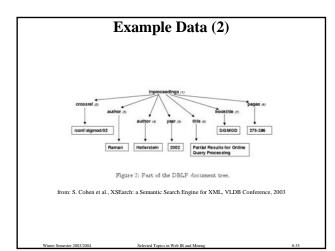
8.3 XSEarch

Data: set of XML trees with interior nodes having names and leaf nodes having contents <u>Queries</u>: set of generalized keywords of the form *name:content, name:, :content,* referring to element names and contents, with each condition optionally having a + flag for mandatory matches Key idea: results should be semantically coherent tree fragments

Definition:

element e satisfies condition n:c if e has label n and a descendant whose contents contains c





$\label{eq:product} \begin{array}{l} \textbf{Query Answers} \\ \text{For two nodes n, n' in a tree the$ *interconnection tree* $T_{n,n'} consists of lca(n, n') as the root and the paths from lca(n,n') to n and n'. \\ \text{Nodes n, n' are$ *meaningfully related* $, denoted n \approx n', if T_{n,n'} \\ \bullet \text{ does not contain two distinct nodes with the same name or } \\ \bullet \text{ the only two distinct nodes with the same name are n and n'} \\ \text{A set N of nodes is} \\ \begin{array}{l} \textbf{all-pairs related}, \text{ denoted } \approx_a(N), \text{ if } n \approx n' \text{ for all } n,n' \in N \text{ and} \\ \textbf{star-related}, \text{ denoted } \approx_s(N), \text{ if there is } n^* \in N \text{ s.t. } n \approx n^* \text{ for all } n \in N. \end{array} \end{array}$

For a query with conditions c1 ... ck the sequence n1 ... nk of nodes and null values is an *all-pairs answer* if • the non-null elements in {n1, ..., nk} are all-pairs related, • ni is not the null-value if ci is a mandatory condition, and • ni satisfies ci if it is not the null value. A *star-related answer* is analogously defined.

An answer N⁴ for a query q subsumes answer N if N⁴ is equal to N on all non-null elements. N is a maximum answer if every N⁴ that subsumes N is equal to N. Were treased 2002/04

Query Answers

For two nodes n, n' in a tree the *interconnection tree* $T_{n,n'}$ consists of lca(n, n') as the root and the paths from lca(n,n') to n and n'.

Nodes n, n' are *meaningfully related*, denoted $n \approx n'$, if $T_{n,n'}$ • does not contain two distinct nodes with the same name or • the only two distinct nodes with the same name are n and n'

A set N of nodes is

all-pairs related, denoted $\approx_a(N)$, if $n \approx n'$ for all $n, n' \in N$ and *star-related*, denoted $\approx_a(N)$, if there is $n^* \in N$ s.t. $n \approx n^*$ for all $n \in N$.

For a query with conditions $c1 \dots ck$ the sequence $n1 \dots nk$ of nodes and null values is an *all-pairs answer* if

- the non-null elements in {n1, ..., nk} are all-pairs related,
- ni is not the null-value if ci is a mandatory condition, and
- ni satisfies ci if it is not the null value.

A star-related answer is analogously defined.

An answer N' for a query q subsumes answer N if N' is equal to N on all non-null elements. N is a *maximal answer* if every N' that subsumes N is equal to N.

Ranking Answers (1)

For query word w and leaf node n use tf*idf as a weight of node n. For query word w and interior node n use the sum of weights over all leaf nodes below n.

For label l and node n use 1 as a weight if n's label is l, 0 otherwise.

Represent each node as an *L*C-dimensional vector* with the above weights as components, where L is # of all possible labels and C the # of distinct words.

For query word w and label l set *query weight* to tf*idf for condition l:w, 1.0 for condition :w, and user-specified (importance) weight for condition l: in all affected dimensions.

The *similarity score for answer set* N and query q, sim(q,N), is the sum, over all $n \in N$, of the cosine similarities between n and q.

Ranking Answers (2)

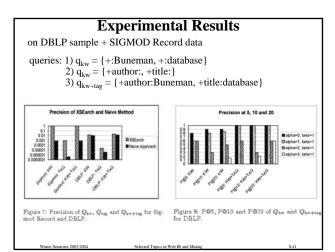
For answer set N to query q define tsize(N) = # nodes in interconnection tree of N ancdes(N) = # node pairs (n, n') in N where n is ancestor of n' or vice versa

The total score of answer N to query q is:

 $\frac{sim(q,N)^{\alpha}}{tsize(N)^{\beta}} \cdot (1 + \gamma \, ancdes(N))$

with calibration parameters α , β , γ

Interrelationship Indexing Goal: efficiently testing nodes n, n' if they are meaningfully related Lemma: If n is ancestor of n', then $n \approx n'$ iff $n \approx parent(n')$ and $label(n) \neq label(parent(n'))$ and $child(n) \approx n'$ and $label(child(n)) \neq label(n')$. If neither n is ancestor of n' nor vice versa, then $n \approx n'$ iff $n \approx parent(n')$ and $label(n) \neq label(parent(n'))$ and $parent(n) \approx n' and label(parent(n)) \neq label(n').$ Dynamic programming algorithm on Boolean matrix interrel[1..#nodes] with depth-first node numbering: for i := #nodes - 1 down to 0 { for j := i+1 to #nodes { if i is ancestor of j { i is ancestor of j {
 let ch(i) be child of i on path to j and par(j) be parent of j;
 interrel[i,j] := interrel[ch(i),j] and label(ch(i)) != label(j) and interrel[i,par(j)] and label(i) != label(par(j)); } }; for i := 1 to #nodes -1 { for j := i+1 to #nodes {



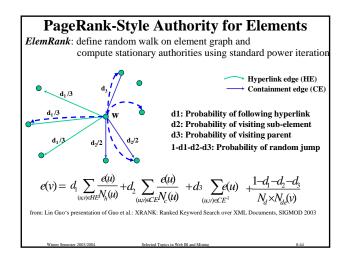
8.4 XRank
Data: interlinked XML documents
Queries: simple keyword queries
Query results: ranked lists of elements
Key ideas:
• result ranking should consider
• element-wise PageRank-style authorities
• tree-node proximity of keyword-matching nodes
• query results are the most specific elements that

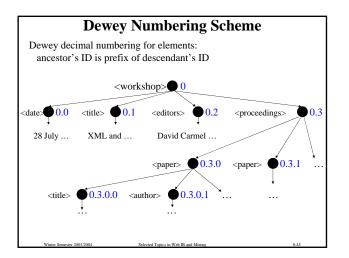
have children with all keywords present

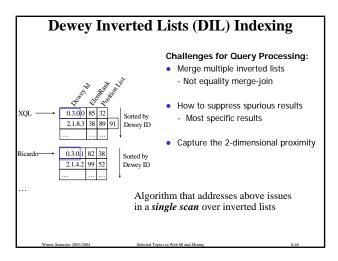
Node Proximity Aware Scoring

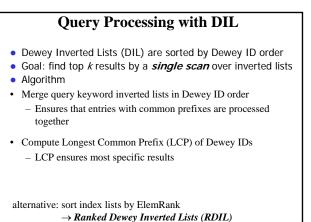
For query keyword w consider element e such that e' contains w and the path (within the tree) between e and e' has length t. We define *score(e, e', w) = score (e',w) * decay (e,e')* with *score(e',w) = ElemRank(e')* if e' contains w, 0 otherwise, *decay(e, e') = \delta^{t-1}*, and calibration parameter δ , $0 < \delta < 1$. If multiple e' exist that contain w then *score(e,w) = max{score(e,e',w)}*.

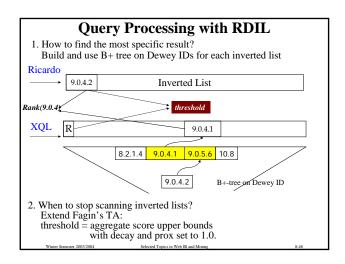
For query with keywords w1, ..., wk $score(e, w1, ..., wk) = (\sum_{i=1..k} score(e, wi)) * prox(e, w1, ..., wk)$ where $prox(e, w1, ..., wk) = size(smallest text window containing w1, ..., wk)^{-1}$ measures the proximity of keywords in the linearized text below e











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