

Topic III.2: Maximum Entropy Models

Discrete Topics in Data Mining
Universität des Saarlandes, Saarbrücken
Winter Semester 2012/13

Topic III.2: Maximum Entropy Models

1. The Maximum Entropy Principle

1.1. Maximum Entropy Distributions

1.2. Lagrange Multipliers

2. MaxEnt Models for Tiling

2.1. The Distribution for Constraints on Margins

2.2. Using the MaxEnt Model

2.3. Noisy Tiles

3. MaxEnt Models for Real-Valued Data

The Maximum-Entropy Principle

- **Goal:** To define a distribution over data that satisfies given constraints
 - Row/column sums
 - Distribution of values
 - ...
- Given such a distribution
 - We can sample from it (as with swap randomization)
 - We can compute the likelihood of the observed data
 - We can compute how surprising our findings are given the distribution
 - ...

Maximum Entropy

- We expect the constraints to be linear
 - If $\mathbf{x} \in X$ is one data set, $\text{Pr}(\mathbf{x})$ is the distribution, and $f_i(\mathbf{x})$ is a real-valued function of the data, the constraints are of type
$$\sum_{\mathbf{x}} \text{Pr}(\mathbf{x})f_i(\mathbf{x}) = d_i$$
- Many distributions can satisfy the constraints; which to choose?
- We want to select the distribution that **maximizes the entropy** and satisfies the constraints
 - Entropy of a discrete distribution: $-\sum_{\mathbf{x}} \text{Pr}(\mathbf{x})\log(\text{Pr}(\mathbf{x}))$

Why Maximize the Entropy?

- No other assumptions
 - Any distribution with less-than-maximal entropy must have some reason for the reduced entropy
 - Essentially, a latent assumption about the distribution
 - We want to avoid these
- Optimal worst-case behaviour w.r.t. coding lengths
 - If we build an encoding based on the maximum entropy distribution, the worst-case expected encoding length is the minimum over any distribution

Finding the MaxEnt Distribution

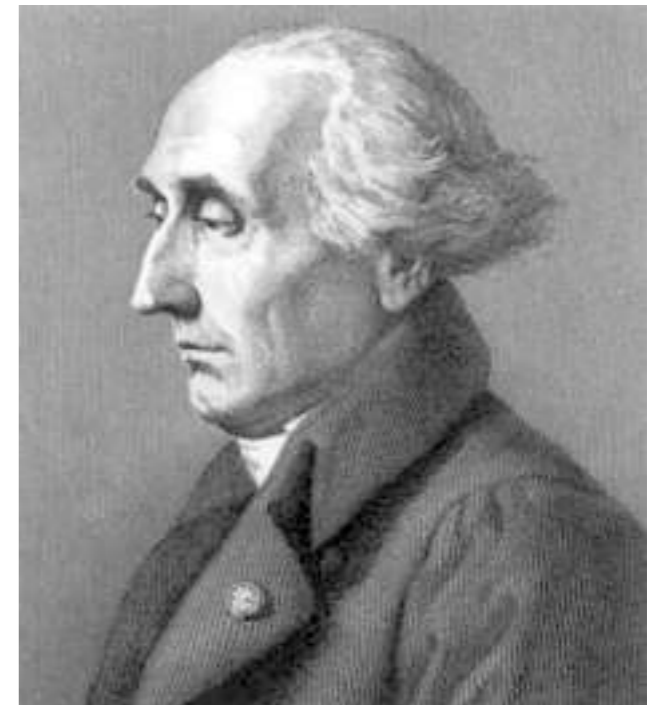
- Finding the MaxEnt distribution is a convex program with linear constraints

$$\begin{aligned} \max_{\Pr(\mathbf{x})} \quad & - \sum_{\mathbf{x}} \Pr(\mathbf{x}) \log \Pr(\mathbf{x}) \\ \text{s.t.} \quad & \sum_{\mathbf{x}} \Pr(\mathbf{x}) f_i(\mathbf{x}) = d_i \quad \text{for all } i \\ & \sum_{\mathbf{x}} \Pr(\mathbf{x}) = 1 \end{aligned}$$

- Can be solved, e.g., using the Lagrange multipliers

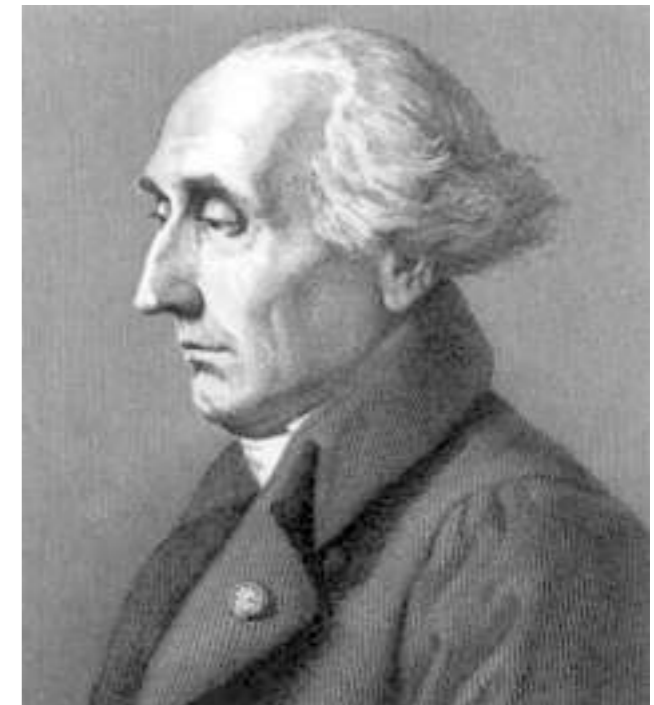
Intermezzo: Lagrange multipliers

- A method to find extrema of constrained functions via derivation
- Problem: minimize $f(\mathbf{x})$ subject to $g(\mathbf{x}) = 0$
 - Without constraint we can just derive $f(\mathbf{x})$
 - But the extrema we obtain might be unfeasible given the constraints
- Solution: introduce **Lagrange multiplier** λ
 - Minimize $L(\mathbf{x}, \lambda) = f(\mathbf{x}) - \lambda g(\mathbf{x})$
 - $\nabla f(\mathbf{x}) - \lambda \nabla g(\mathbf{x}) = 0$
 - $\partial L / \partial x_i = \partial f / \partial x_i - \lambda \times \partial g / \partial x_i = 0$ for all i
 - $\partial L / \partial \lambda = g(\mathbf{x}) = 0$



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 - $\partial L / \partial x_i = \partial f / \partial x_i - \lambda \times \partial g / \partial x_i = 0$ for all i
 - $\partial L / \partial \lambda = g(\mathbf{x}) = 0$ **The constraint!**

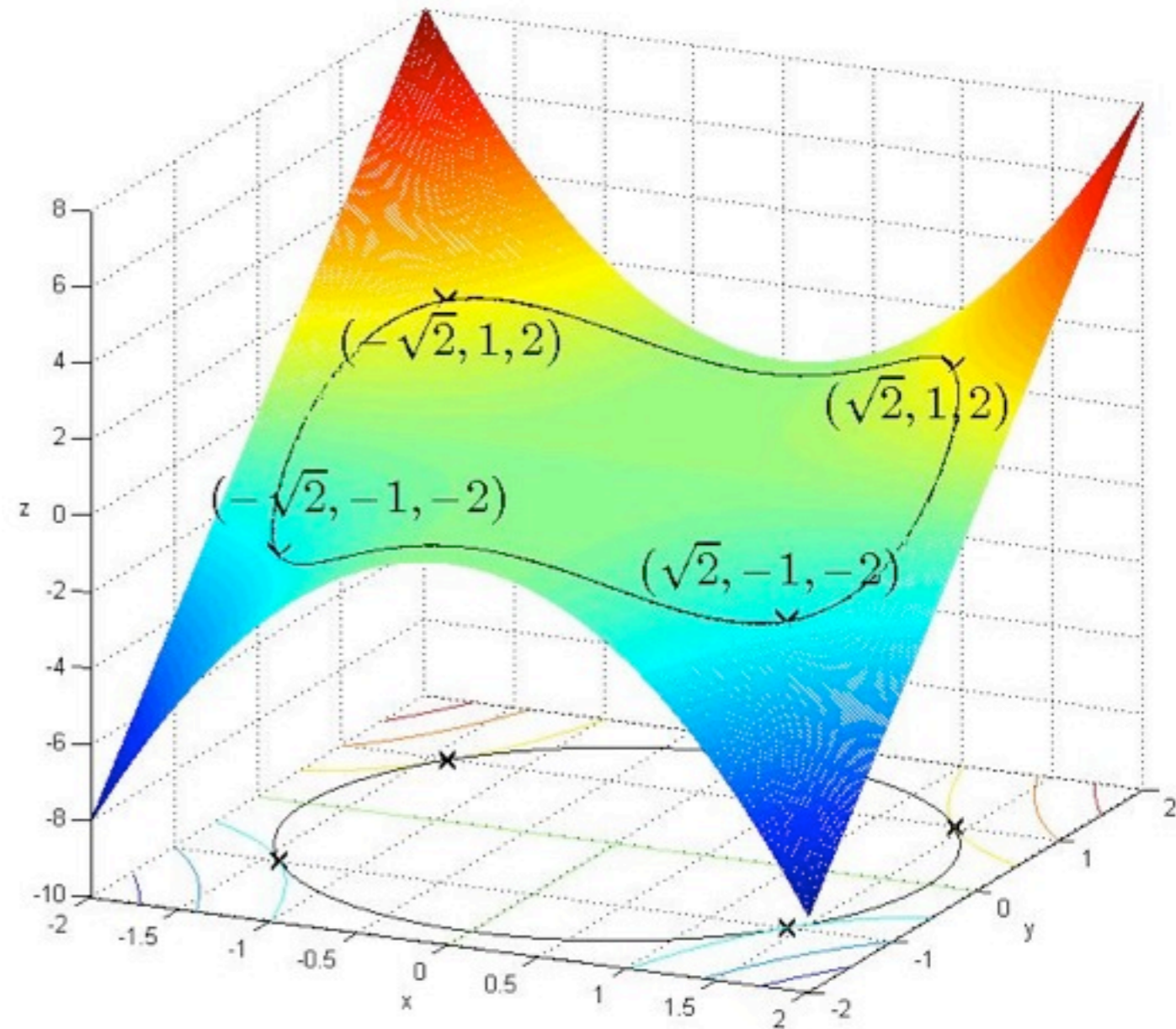


More on Lagrange multipliers

- For many constraints, we need to add one multiplier for each constraint
 - $L(\mathbf{x}, \boldsymbol{\lambda}) = f(\mathbf{x}) - \sum_j \lambda_j g_j(\mathbf{x})$
 - Function L is known as the **Lagrangian**
- Minimizing the unconstrained Lagrangian equals minimizing the constrained f
 - But not all solutions to $\nabla f(\mathbf{x}) - \sum_j \lambda_j \nabla g_j(\mathbf{x}) = 0$ are extrema
 - The solution is in the boundary of the constraint only if $\lambda_j \neq 0$

Example

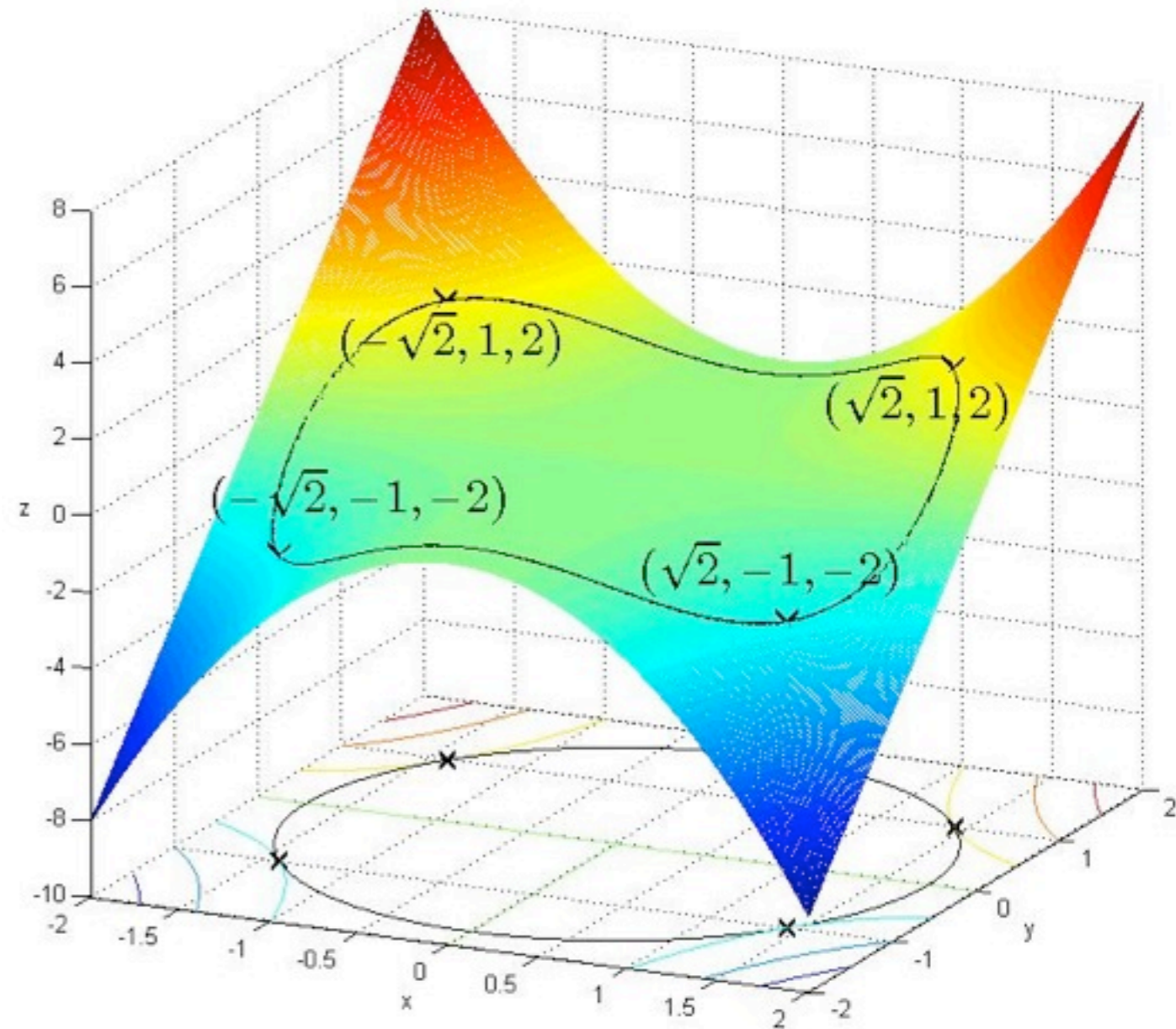
minimize $f(x,y) = x^2y$
subject to $g(x,y) = x^2 + y^2 = 3$



Example

minimize $f(x,y) = x^2y$
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$$L(x,y,\lambda) = x^2y + \lambda(x^2 + y^2 - 3)$$



Example

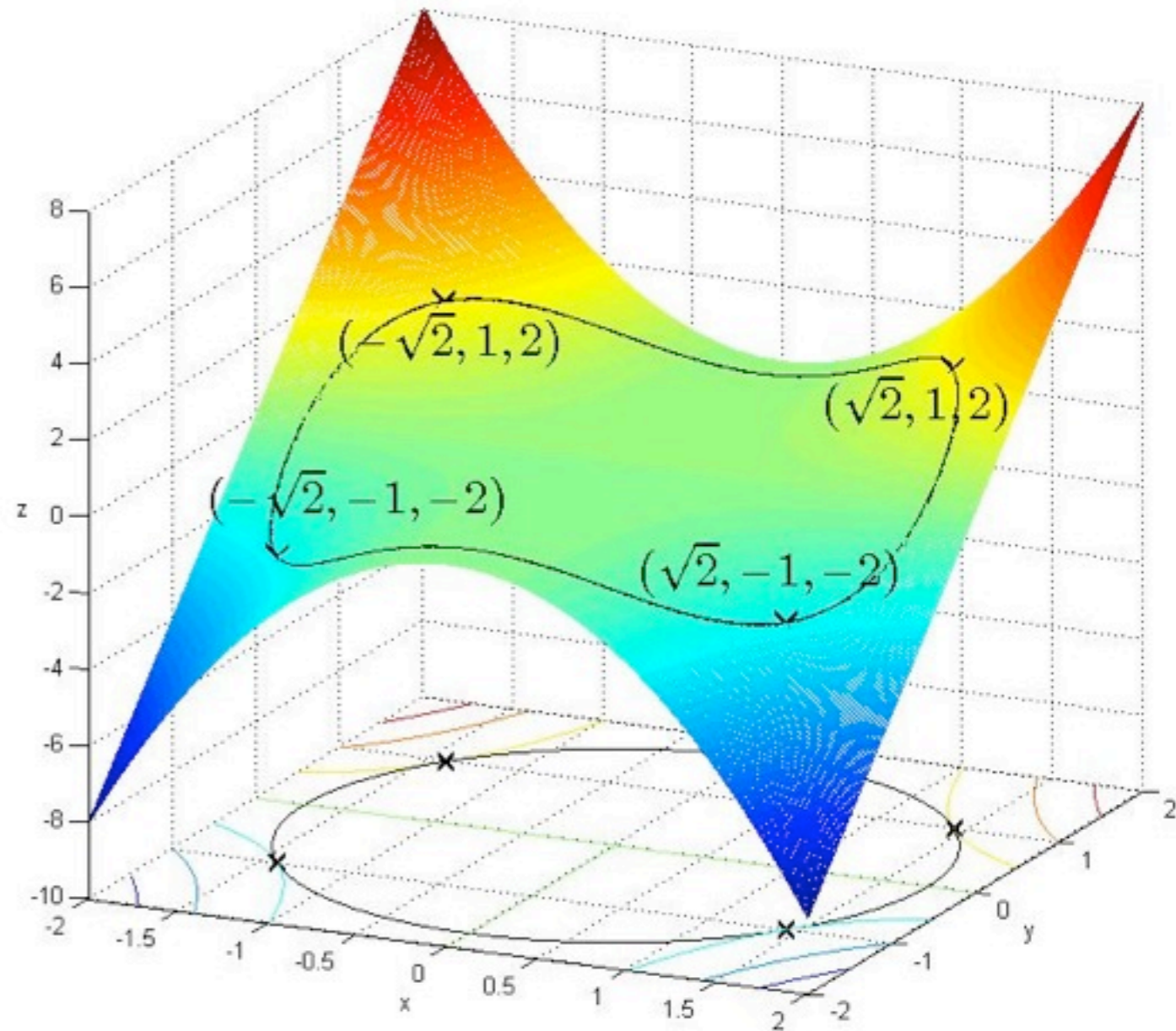
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$$L(x,y,\lambda) = x^2y + \lambda(x^2 + y^2 - 3)$$

$$\frac{\partial L}{\partial x} = 2xy + 2\lambda x = 0$$

$$\frac{\partial L}{\partial y} = x^2 + 2\lambda y = 0$$

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Example

minimize $f(x,y) = x^2y$
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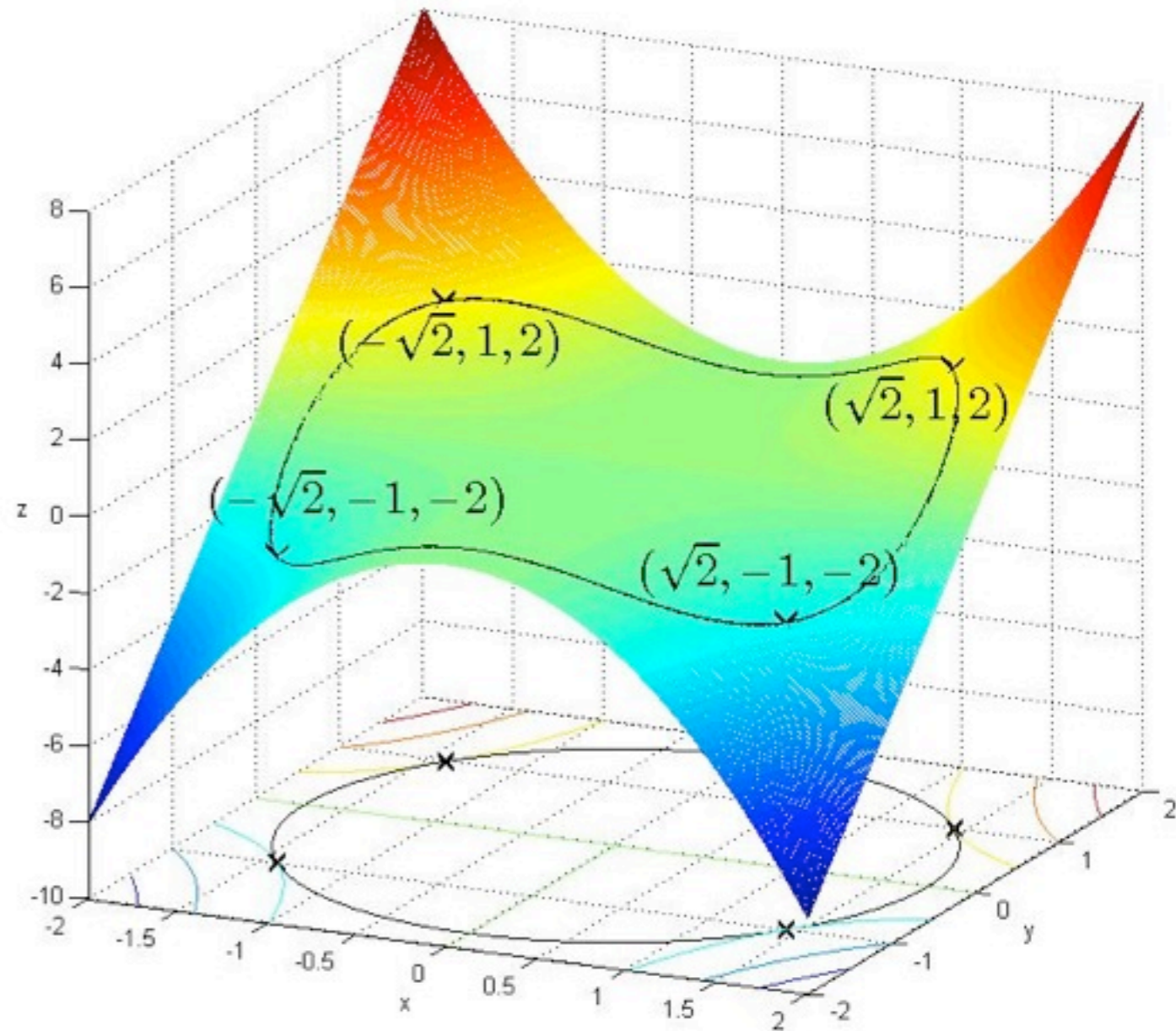
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$$\frac{\partial L}{\partial y} = x^2 + 2\lambda y = 0$$

$$\frac{\partial L}{\partial \lambda} = x^2 + y^2 - 3 = 0$$

Solution: $x = \pm\sqrt{2}, y = -1$



Solving the MaxEnt

- The Lagrangian is

$$L(\Pr(\mathbf{x}), \mu, \lambda) = - \sum_{\mathbf{x}} \Pr(\mathbf{x}) \log \Pr(\mathbf{x}) + \sum_i \lambda_i \left(\sum_{\mathbf{x}} \Pr(\mathbf{x}) f_i(\mathbf{x}) - d_i \right) + \mu \left(\sum_{\mathbf{x}} \Pr(\mathbf{x}) - 1 \right)$$

- Setting the derivative w.r.t. $\Pr(\mathbf{x})$ to 0 gives

$$\Pr(\mathbf{x}) = \frac{1}{Z(\lambda)} \exp \left(\sum_i \lambda_i f_i(\mathbf{x}) \right)$$

- Where $Z(\lambda) = \sum_{\mathbf{x}} \exp(\sum_i \lambda_i f_i(\mathbf{x}))$ is called the *partition function*

The Dual and the Solution

- Substituting the $\text{Pr}(\mathbf{x})$ in the Lagrangian yields the **dual objective** $L(\boldsymbol{\lambda}) = \log(Z(\boldsymbol{\lambda})) - \sum_i \lambda_i d_i$
- Minimizing the dual gives the maximal solution to the original constrained equation
- The dual is convex, and can therefore be minimized using well-known methods

Using the MaxEnt Distribution

- p -Values: we can sample from the distribution and re-run the algorithm as with swap randomization
- Self-information: the negative log-probability of the observed pattern under the MaxEnt model is its *self-information*
 - The higher, the more information the pattern contains
- Information compression ratio: more complex patterns are harder to communicate (longer description length); when contrasted to self-information, this gives us the *information compression ratio*

MaxEnt Models for Tiling

- The Tiling problem
 - Binary data, aim to find fully monochromatic submatrices
- Constraints: the *expected* row and column margins

$$\sum_{\mathbf{D} \in \{0,1\}^{n \times m}} \Pr(\mathbf{D}) \left(\sum_{j=1}^m d_{ij} \right) = r_i$$

$$\sum_{\mathbf{D} \in \{0,1\}^{n \times m}} \Pr(\mathbf{D}) \left(\sum_{i=1}^n d_{ij} \right) = c_j$$

- Note that these are in the correct form

The MaxEnt Distribution

- Using the Lagrangian, we can solve the $\Pr(\mathbf{D})$,

$$\Pr(\mathbf{D}) = \prod_{i,j} \frac{1}{Z(\lambda_i^r, \lambda_j^c)} \exp(d_{ij}(\lambda_i^r + \lambda_j^c))$$

– where $Z(\lambda_i^r, \lambda_j^c) = \sum_{d_{ij} \in \{0,1\}} \exp(d_{ij}(\lambda_i^r + \lambda_j^c))$

- Note that $\Pr(\mathbf{D})$ is a product of independent elements
 - We did not *enforce* this independency, it's a consequence of the MaxEnt model
- Also, each element is Bernoulli distributed with success probability $\exp(\lambda_i^r + \lambda_j^c) / (1 + \exp(\lambda_i^r + \lambda_j^c))$

Other Domains

- If our data contains nonnegative integers, the distribution changes to the **geometric distribution** with success probability $1 - \exp(-(\lambda_i^r + \lambda_j^c))$
- If our data contains nonnegative real numbers, the partition function becomes

$$Z(\lambda_i^r, \lambda_j^c) = \int_0^{\infty} \exp(-x(\lambda_i^r + \lambda_j^c)) dx = \frac{1}{\lambda_i^r + \lambda_j^c}$$

- Assuming $\lambda_i^r + \lambda_j^c > 0$
- The distribution is the **exponential distribution** with rate parameter $\lambda_i^r + \lambda_j^c$ for d_{ij}
- Note: a continuous distribution

Maximizing the Entropy

- The optimal Lagrange multipliers can be found using standard gradient descent methods
- Requires computing the gradient for the multipliers
 - There are $m + n$ multipliers for an n -by- m matrix
 - But we only need to consider λ s for distinct r_i and c_j , which can be considerably less
 - E.g. $\sqrt{(2s)}$ for s non-zeros in a binary matrix
- Overall worst-case time per iteration is $O(s)$ for gradient descent
 - For Newton's method, it's $O(\sqrt{s^3})$

MaxEnt and Swap Randomization

- MaxEnt models constrain the *expected margins*; swap randomization constrains the actual margins
 - Does it matter?
- If $\mathcal{M}(r, c)$ is the set of all n -by- m binary matrices with same row and column margins, the MaxEnt model will give the same probability for each matrix in $\mathcal{M}(r, c)$
 - More generally, the probability is invariant under adding a constant in the diagonal and reducing it from the anti-diagonal of any 2-by-2 submatrix

The Interestingness of a Tile

- Given a tile τ and a MaxEnt model for the binary data (w.r.t. row and column margins), the **self-information** of τ is $-\sum_{(i,j) \in \tau} \log(p_{ij})$
 - $p_{ij} = \exp(\lambda_i^r + \lambda_j^c) / (1 + \exp(\lambda_i^r + \lambda_j^c))$
- The **description length** of the tile is the number of bits it takes to explain the tile
- The **compression ratio** of τ is the fraction $\text{SelfInformation}(\tau) / \text{DescriptionLength}(\tau)$

Set of Tiles

- The description length for a set of tiles is the sum of tiles' description lengths
- The self-information for a set of tiles is the self-information of their union
 - Repeatedly covering a value doesn't increase the self-information
- Finding a set of tiles with maximum self-information but with a description length below a threshold is NP-hard problem
 - Budgeted maximum coverage
 - A greedy approximation achieves $(e - 1)/e$ approximation

Noisy Tiles

- If we allow noisy tiles, the self-information changes
 - The 0s also convey information

$$\text{SelfInformation}(\tau) = \sum_{(i,j) \in \tau: d_{ij}=1} \log \left(\frac{\exp(\lambda_i^r + \lambda_j^c)}{1 + \exp(\lambda_i^r + \lambda_j^c)} \right) + \sum_{(i,j) \in \tau: d_{ij}=0} \log \left(\frac{1}{1 + \exp(\lambda_i^r + \lambda_j^c)} \right)$$

- The location of 0s in the tile can be encoded in the description length using at most $\log \binom{IJ}{n_0}$ bits for a tile of size I -by- J that have n_0 zeros

Real-Valued Data

- We already saw how to build MaxEnt model with constraints on the means of rows and columns
- Here: constraint means and variances —or— constraint the histograms of rows and columns
 - Similar to the options from last week
 - Second option is obviously stronger

Preserving Means and Variances

- To preserve row and column means and variances, we need to constraint
 - Row and column sums
 - Row and column sums-of-squares
- After solving the MaxEnt equation, we again get that the MaxEnt distribution for \mathbf{D} is a product of probabilities for d_{ij}
 - $\Pr(d_{ij}) \sim \mathcal{N}\left(-\frac{\lambda_i^r + \lambda_j^c}{2(\mu_i^r + \mu_j^c)}, (2(\mu_i^r + \mu_j^c))^{-1/2}\right)$
 - λ s are Lagrange multipliers associated with the constraints on sums
 - μ s are Lagrange multipliers associated with the constraints on sums-of-squares

Preserving the Histograms

- We can express the distribution using a histogram of its values
 - Bin number and widths are selected automatically based on MDL
- The constraints for histograms requires we keep the contents of the bins (on expectation) intact
- The resulting distribution is a histogram itself

Some Notes

- These methods—again—assume that summing over rows and columns makes sense
- Sampling is considerably faster than with swap randomizations
 - Order-of-magnitude difference in worst case
- MaxEnt models also allow computing analytical p -values for individual patterns

Essay Topics

- *Swap-based methods vs maximum entropy methods*
 - What are they? How they work? Similarities? Differences? Is one better than other? Consider both binary and continuous cases
- *Method for finding a frequency threshold for significant itemsets vs other methods*
 - Kirsch et al. 2012 paper
 - Explained in the TIII.intro lecture
 - How is it different from the swap-based or MaxEnt based methods we've discussed
 - Only for binary data
- **DL 29 January**

Exam Information

- 19 February (Tuesday)
- Oral exam
- Room 021 at MP11 building (E1.4)
- Time frame: 10 am – 6 pm
 - If you have constraints within this time frame, send me email
 - About 20 min per student
- I will ask questions on one or two topic areas
 - You can veto one proposed topic area—but only one