

## EUROGRAPHICS 2007

### Tutorial 6 Capturing Reflectance From Theory to Practice

Hendrik P.A. Lensch, MPI Informatik  
Michael Goesele, TU Darmstadt  
Gero Müller, Bonn University

## Schedule

- 14:00-14:25 – Introduction (Lensch)
- 14:25-15:00 – Acquisition Basics (Goesele)
- 15:00-15:30 – Reflectance Sharing (Goesele)
- 15:30-16:00 – Break
- 16:00-16:45 – Reflectance Fields for Distant Lights (Müller)
- 16:45-17:20 – Near-field Reflectance Fields (Lensch)
- 17:20-17:30 – Conclusion, Q/A

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## Capturing Reflectance From Theory to Practice

### Introduction

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MPI Informatik

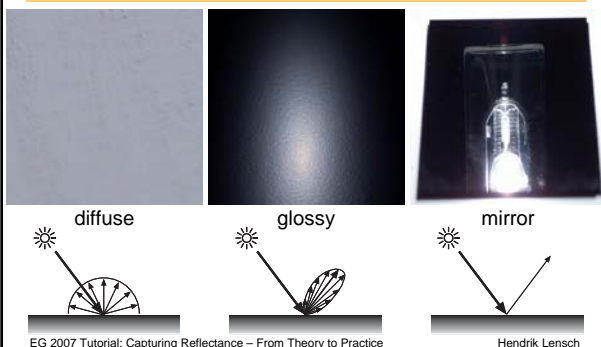
## Material Samples



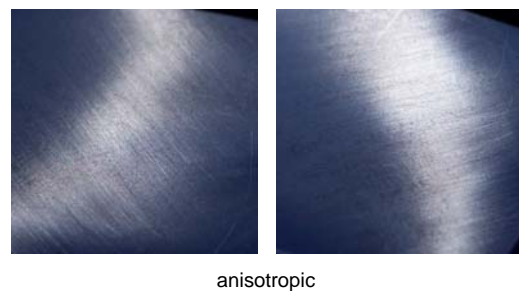
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## Material Samples



## Material Samples



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## Material Samples

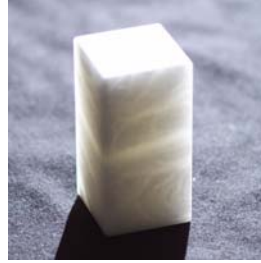


translucent

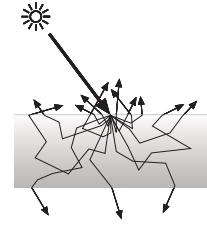
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## Material Samples



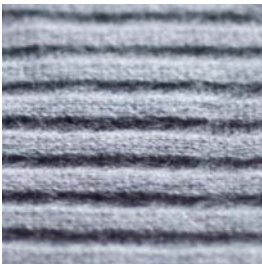
translucent



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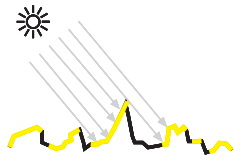
## Material Samples



complex surface structure

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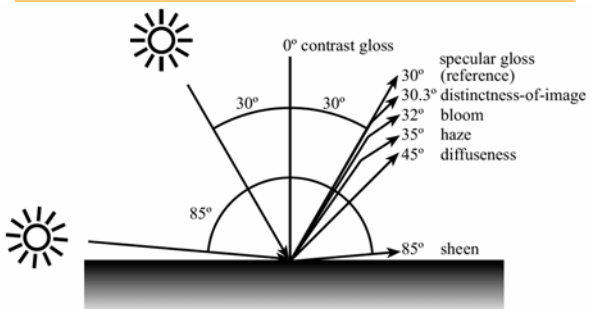
## How to describe materials?

- mechanical, chemical, electrical properties
- reflection properties
- surface roughness
- geometry/meso-structure
- **relightable** representation of appearance

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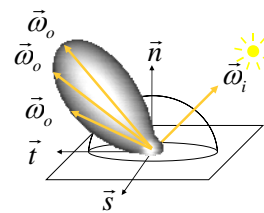
## Gloss Model



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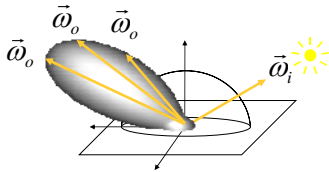
## Reflection of an Opaque Surface



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## Reflection of an Opaque Surface



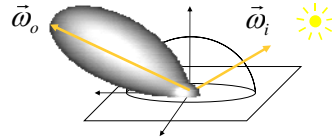
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## BRDF – 4D

(bidirectional reflectance distribution function)

$$f_r(\vec{\omega}_i \rightarrow \vec{\omega}_o)$$



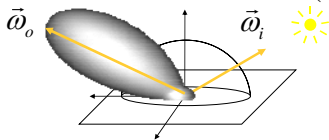
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## BRDF – 4D

(bidirectional reflectance distribution function)

$$f_r(\vec{\omega}_i \rightarrow \vec{\omega}_o) = \frac{dL(\vec{\omega}_o)}{dE(\vec{\omega}_i)}$$



ratio of reflected radiance to incident irradiance

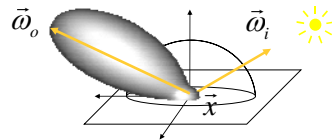
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## Spatially Varying BRDF – 6D

- heterogeneous materials

$$f_r(\vec{\omega}_i \rightarrow \vec{\omega}_o)$$



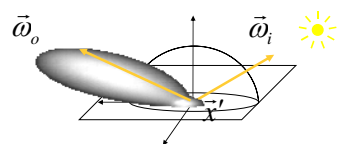
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## Spatially Varying BRDF – 6D

- heterogeneous materials

$$f_r(\vec{x})(\vec{\omega}_i \rightarrow \vec{\omega}_o)$$

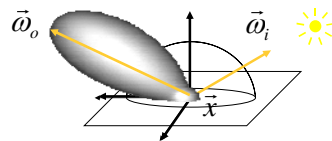


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## Isotropic BRDF – 3D

- invariant with respect to rotation about the normal



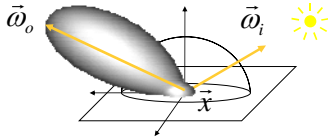
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### Isotropic BRDF – 3D

- invariant with respect to rotation about the normal

$$f_r(\vec{\omega}_i \rightarrow \vec{\omega}_o)$$



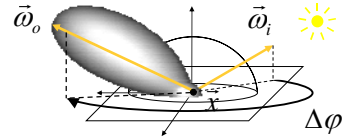
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### Isotropic BRDF – 3D

- invariant with respect to rotation about the normal

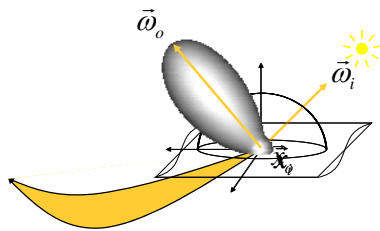
$$f_r((\theta_i, \phi_i) \rightarrow (\theta_o, \phi_o))$$



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### Subsurface Scattering



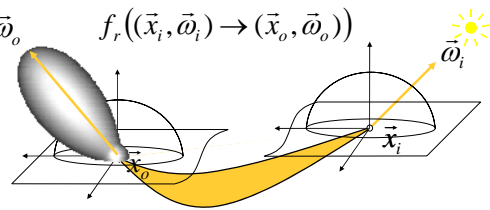
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### BSSRDF – 8D

(bidirectional scattering surface reflectance distribution function)

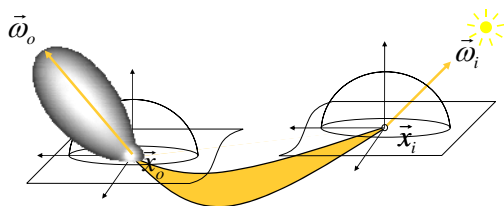
$$f_r((\vec{x}_i, \vec{\omega}_i) \rightarrow (\vec{x}_o, \vec{\omega}_o))$$



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### Subsurface Scattering Homogeneous Material

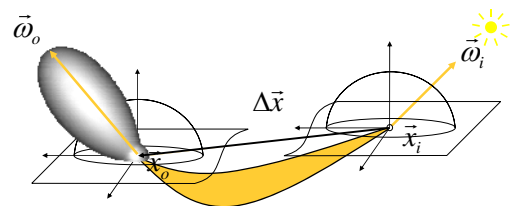


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### Homogeneous Material BSSRDF – 6D

$$f_r((\Delta\vec{x}, \vec{\omega}) \rightarrow (\vec{\omega}_o, \vec{\omega}_i))$$

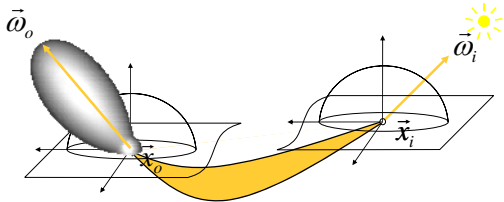


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## Generalization – 12D

$$f_r(\lambda; (\vec{x}_i, \vec{\omega}_i) \rightarrow (\vec{x}_o, \vec{\omega}_o))$$

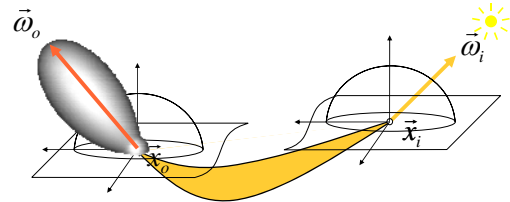


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## Generalization – 12D

$$f_r(\lambda; (\vec{x}_i, \vec{\omega}_i) \rightarrow (\vec{x}_o, \vec{\omega}_o))$$



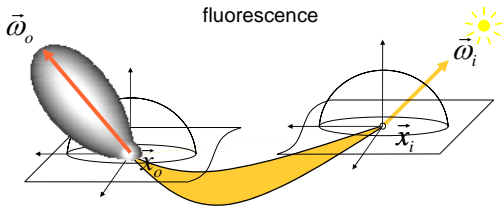
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## Generalization – 12D

$$f_r((\vec{x}_i, \vec{\omega}_i, \lambda_i) \rightarrow (\vec{x}_o, \vec{\omega}_o, \lambda_o))$$

fluorescence



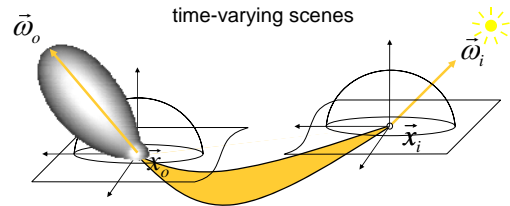
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## Generalization – 12D

$$f_r(t; (\vec{x}_i, \vec{\omega}_i, \lambda_i) \rightarrow (\vec{x}_o, \vec{\omega}_o, \lambda_o))$$

time-varying scenes



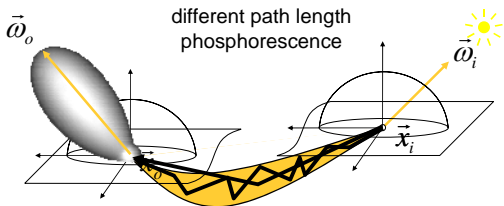
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## Generalization – 12D

$$f_r((\vec{x}_i, \vec{\omega}_i, t_i, \lambda_i) \rightarrow (\vec{x}_o, \vec{\omega}_o, t_o, \lambda_o))$$

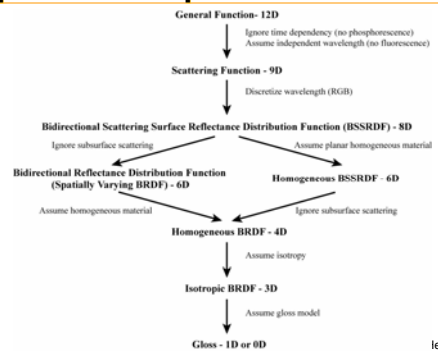
different path length  
phosphorescence



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## Taxonomy of Appearance Representations



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## Properties of Reflectance Functions

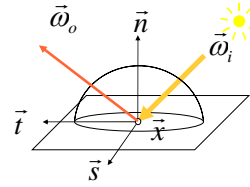
- Helmholtz reciprocity
- energy conservation
- Fresnel effect

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## Helmholtz Reciprocity

$$f_r(\vec{\omega}_i \rightarrow \vec{\omega}_o)$$

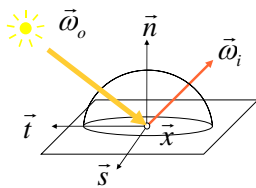


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## Helmholtz Reciprocity

$$f_r(\vec{\omega}_i \rightarrow \vec{\omega}_o) = f_r(\vec{\omega}_o \leftarrow \vec{\omega}_i)$$



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## Energy Conservation

- The sum of energy reflected into all directions has to be smaller or equal than the incident energy.

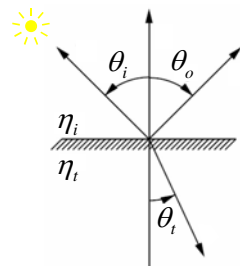
$$\int_{\Omega_o} f_r(\vec{\omega}_i \rightarrow \vec{\omega}_o) \cos(\theta_i) d\omega_o \leq 1$$

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## Snell's Law

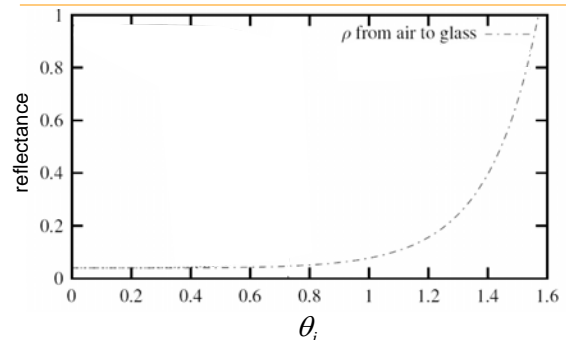
$$\eta_i(\lambda) \sin \theta_i = \eta_t(\lambda) \sin \theta_t$$



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## Fresnel Formula



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## Material Acquisition

- single picture
  - no interaction



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## Material Acquisition

- diffuse color + geometry model
  - no relighting



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## Material Acquisition

- BRDF + geometry model
  - moving highlights



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## Material Acquisition

- spatially-varying BRDF + geometry model
  - moving highlights

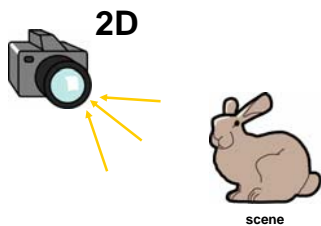


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## Digitizing real-world Objects

a single photograph

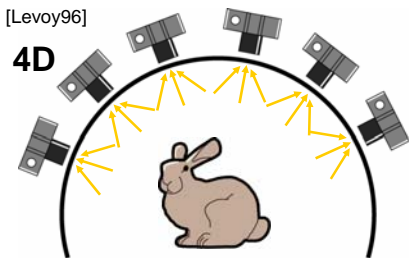


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## Light Fields

[Gortler96], [Levoy96]



distribution of all reflected light rays

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### Relighting

one picture for each light direction

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### Relighting

[Debevec2000]

superposition principle

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### 4D Reflectance Fields

[Debevec2000]

2D

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### Far- vs. Near-Field Illumination

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### 6D Reflectance Fields

#### Near Field illumination

[Masselus2003]

2D

4D

relighting with 4D incident light fields

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### 8D Reflectance Fields

4D

4D

arbitrary perspective + arbitrary illumination

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## Acquisition Approaches

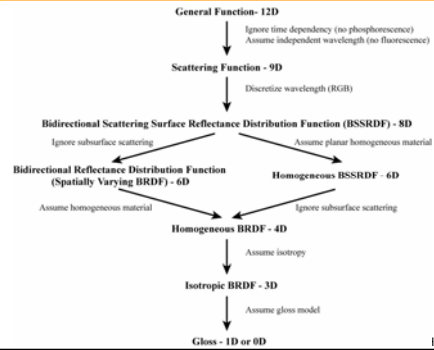
- hard to sample an 8D function
- dimensionality reduction
- sampling density
- restricted viewing and relighting capabilities
- restriction to a specific class of materials/objects



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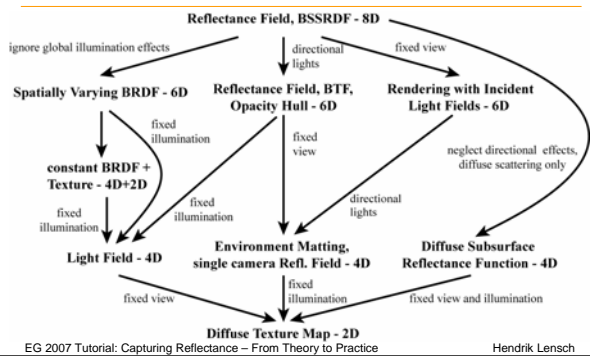
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## Taxonomy of Appearance Representations



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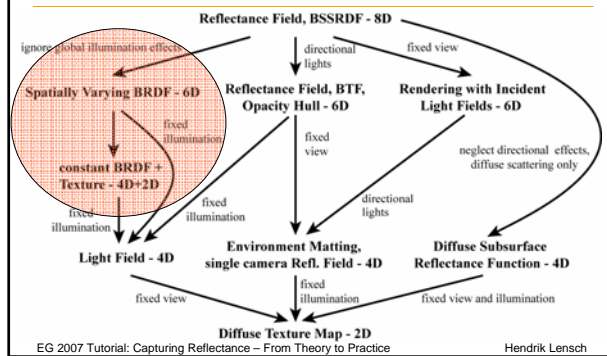
## Acquisition Taxonomy



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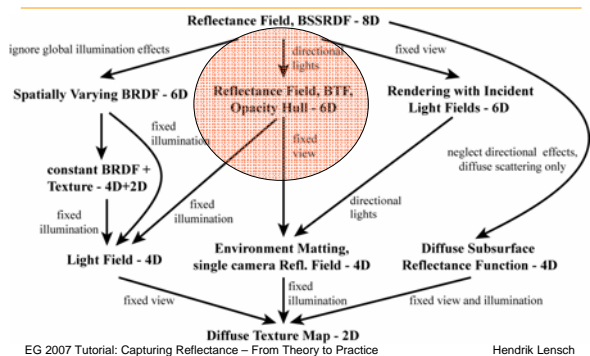
## Reflectance Sharing



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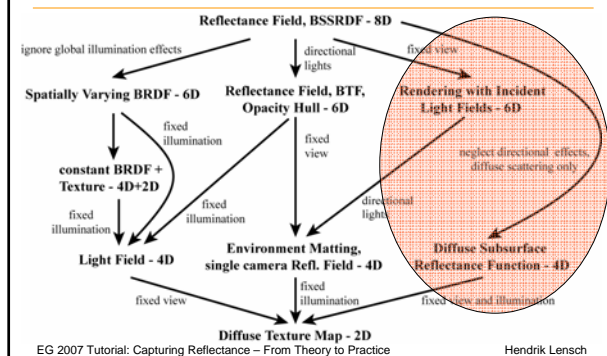
## Reflectance Fields for Distant Lights



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## Near-Field Reflectance Fields



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## Summary

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- densely sampling 8D functions almost impossible
- less dimensions might be sufficient for specific tasks / materials