

Symmetry Transforms

Motivation

Symmetry is everywhere



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Symmetry is everywhere



Perfect Symmetry

[Blum '64, '67]

[Wolter '85]

[Minovic '97]

[Martinet '05]

Motivation

Symmetry is everywhere



Local Symmetry

[Blum '78]

[Thrun '05]

[Simari '06]

Motivation

Symmetry is everywhere



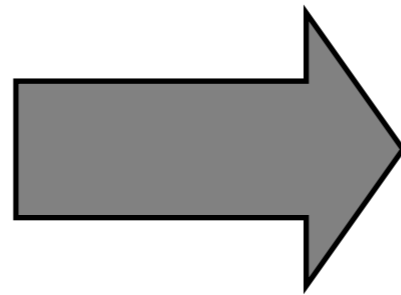
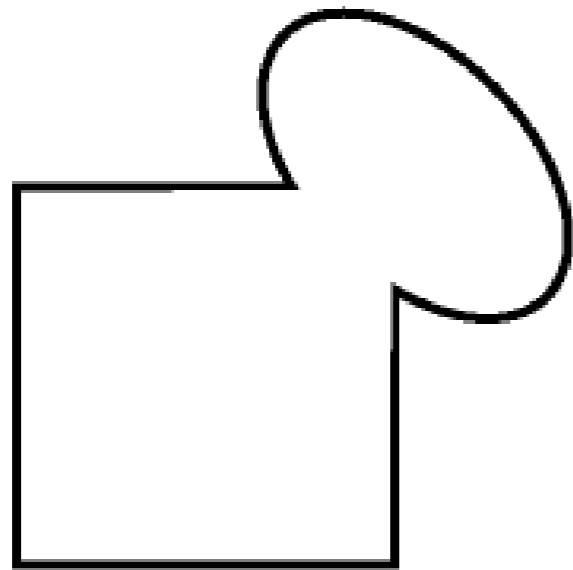
Partial Symmetry

[Zabrodsky '95]

[Kazhdan '03]

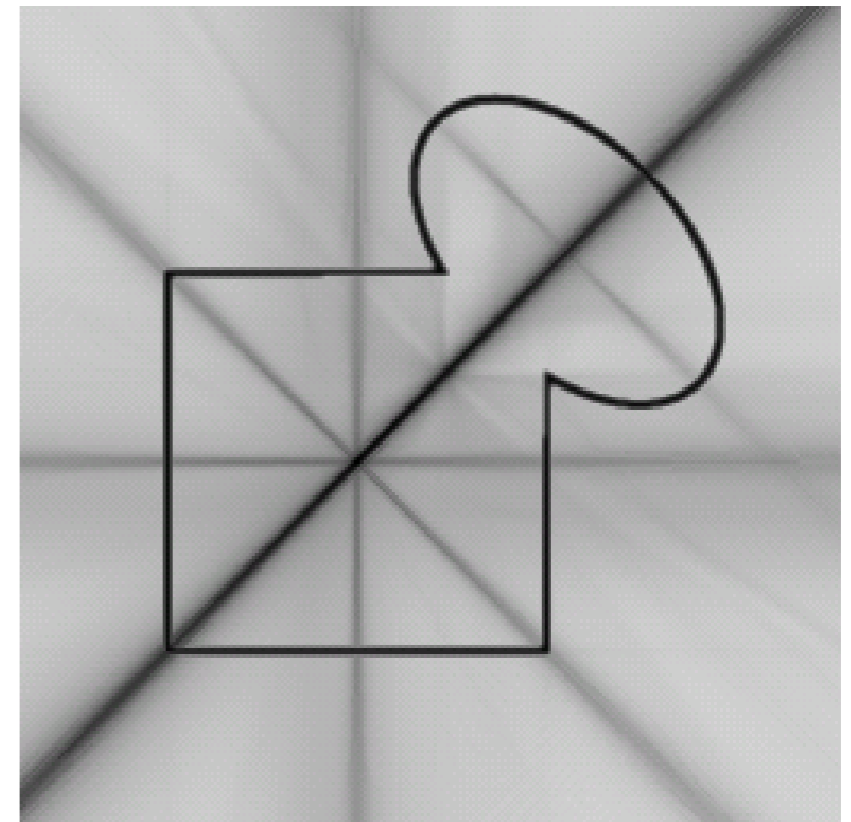
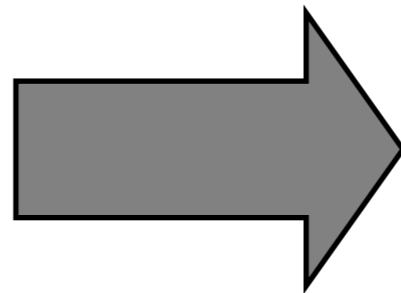
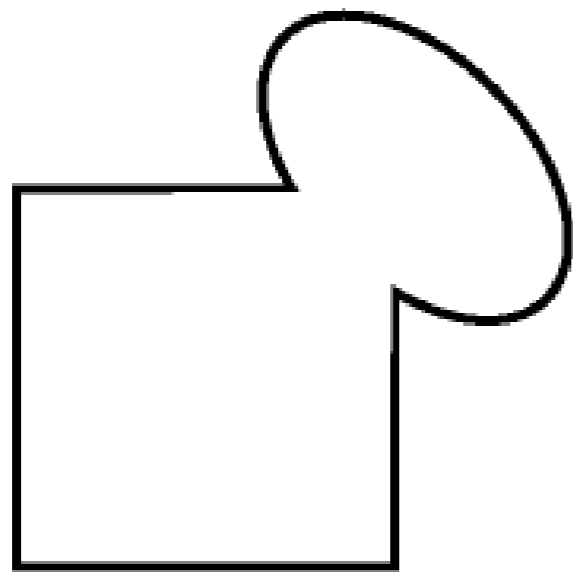
Goal

A computational representation that describes all planar symmetries of a shape



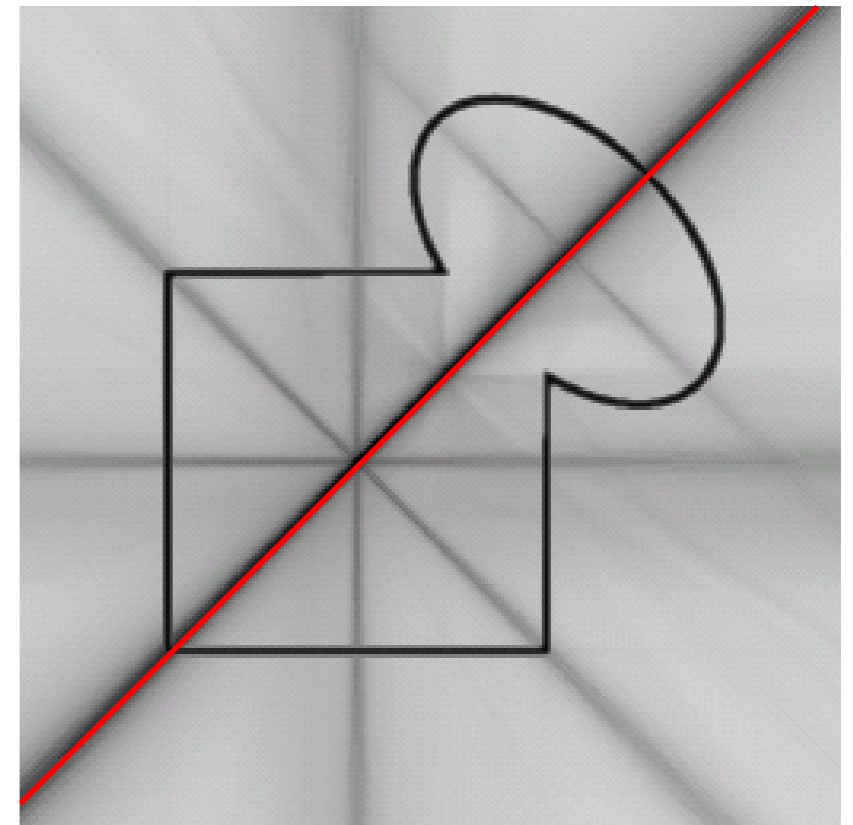
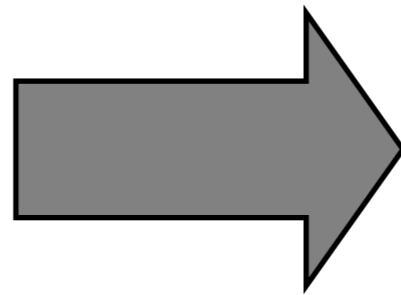
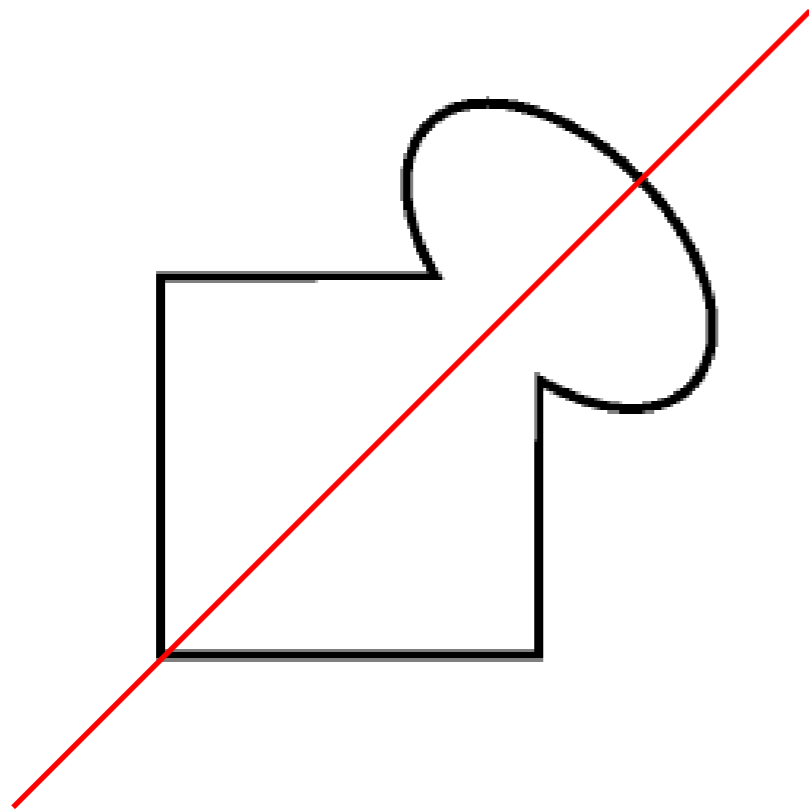
Symmetry Transform

A computational representation that describes all planar symmetries of a shape



Symmetry Transform

A computational representation that describes all planar symmetries of a shape

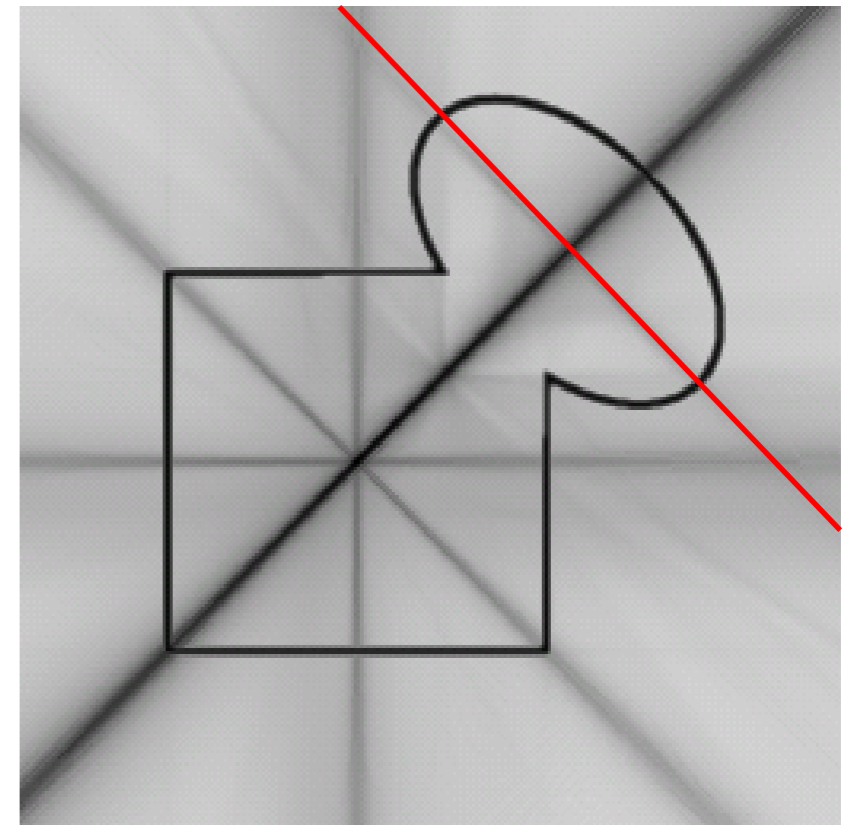
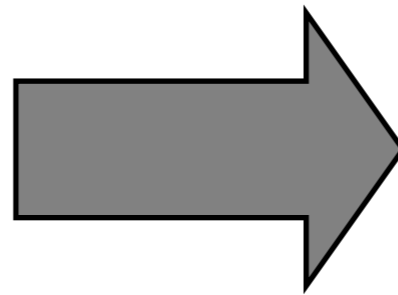
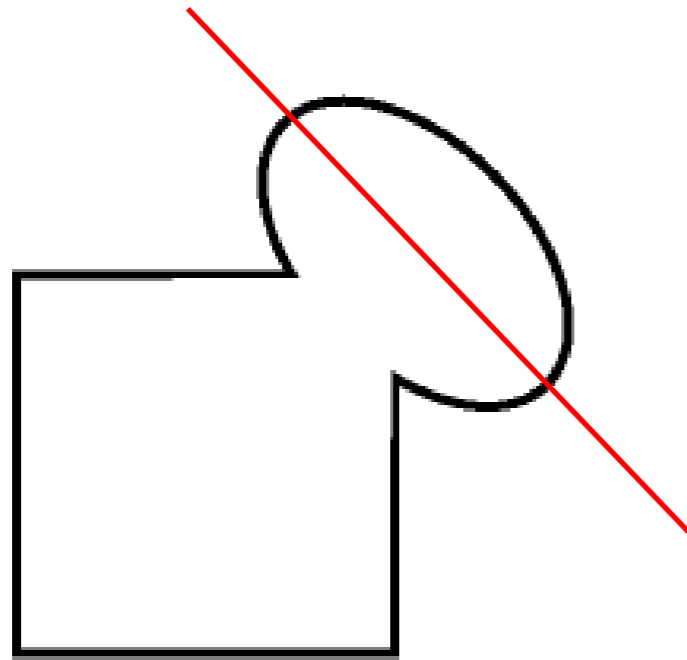


Perfect Symmetry

Symmetry = 1.0

Symmetry Transform

A computational representation that describes all planar symmetries of a shape

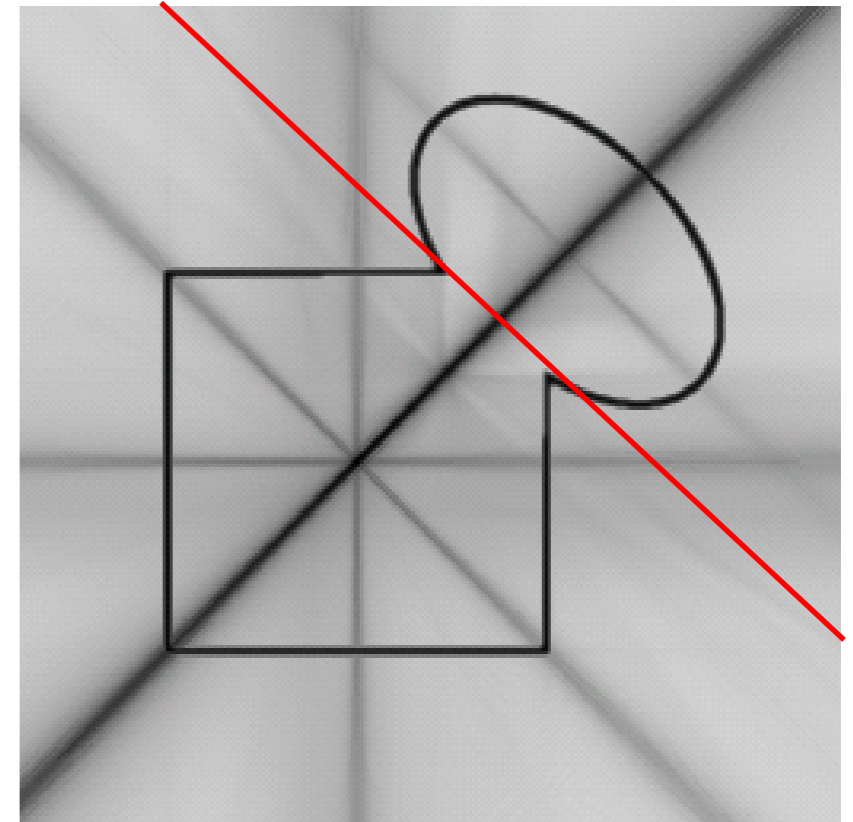
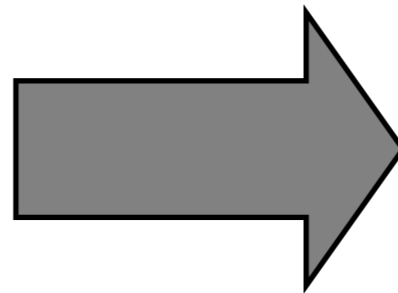
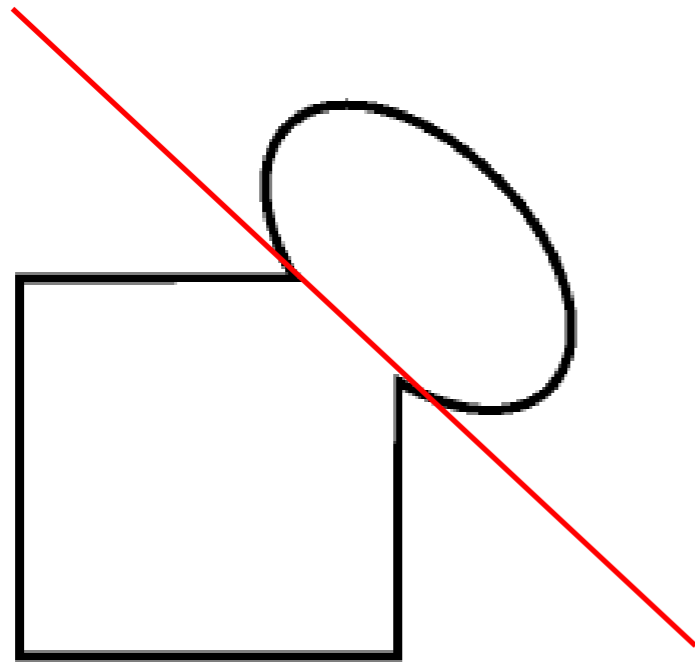


Local Symmetry

Symmetry = 0.3

Symmetry Transform

A computational representation that describes all planar symmetries of a shape

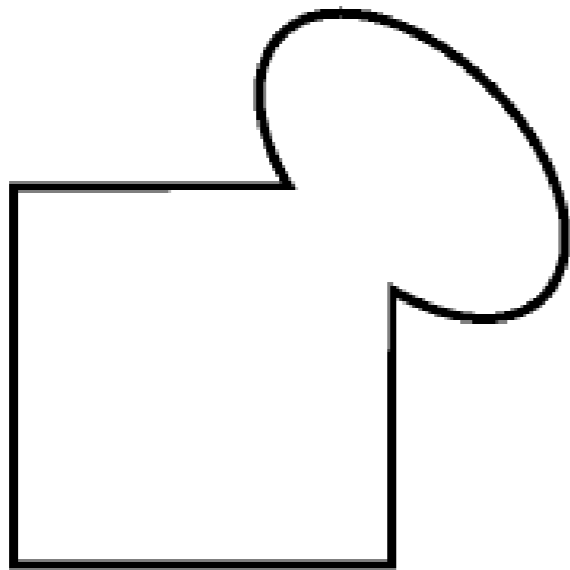


Partial Symmetry

Symmetry = 0.2

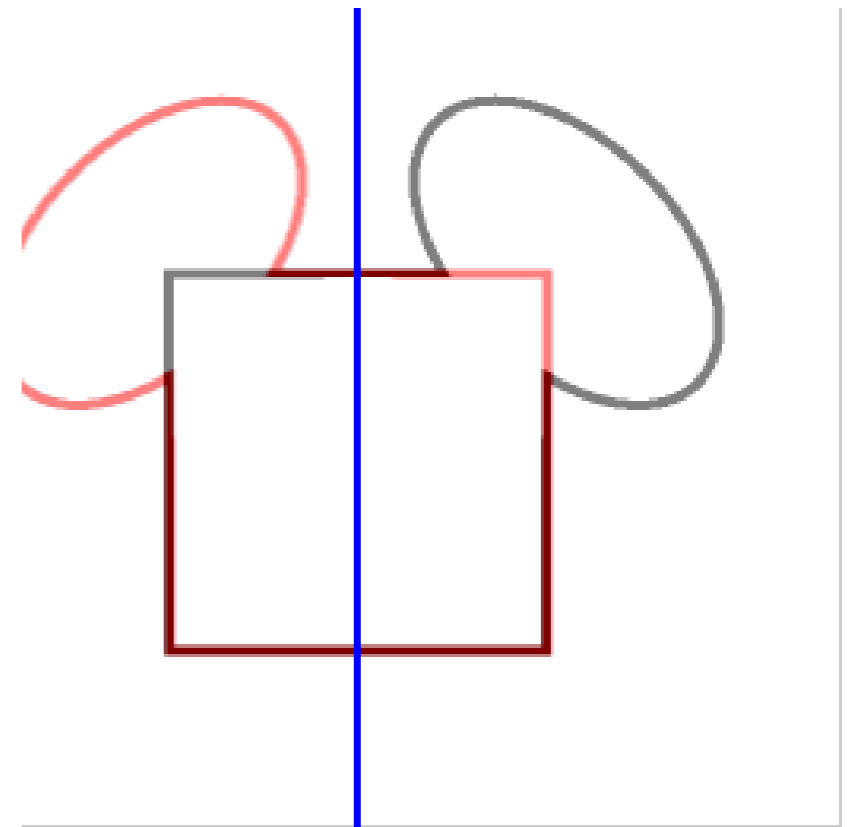
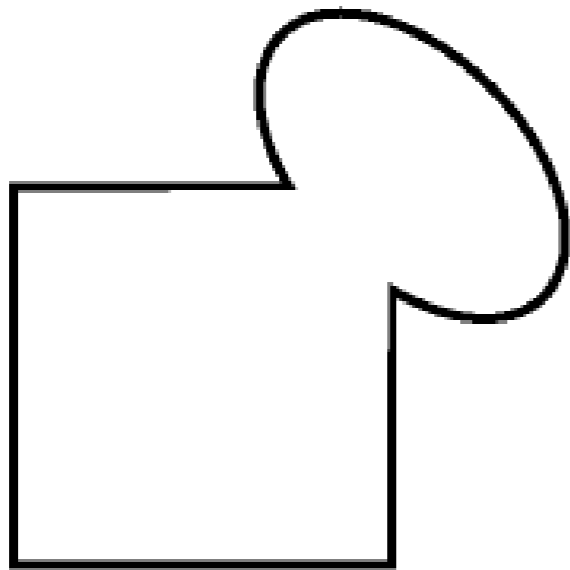
Symmetry Measure

Symmetry of a shape is measured by correlation with its reflection



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Symmetry of a shape is measured by correlation with its reflection

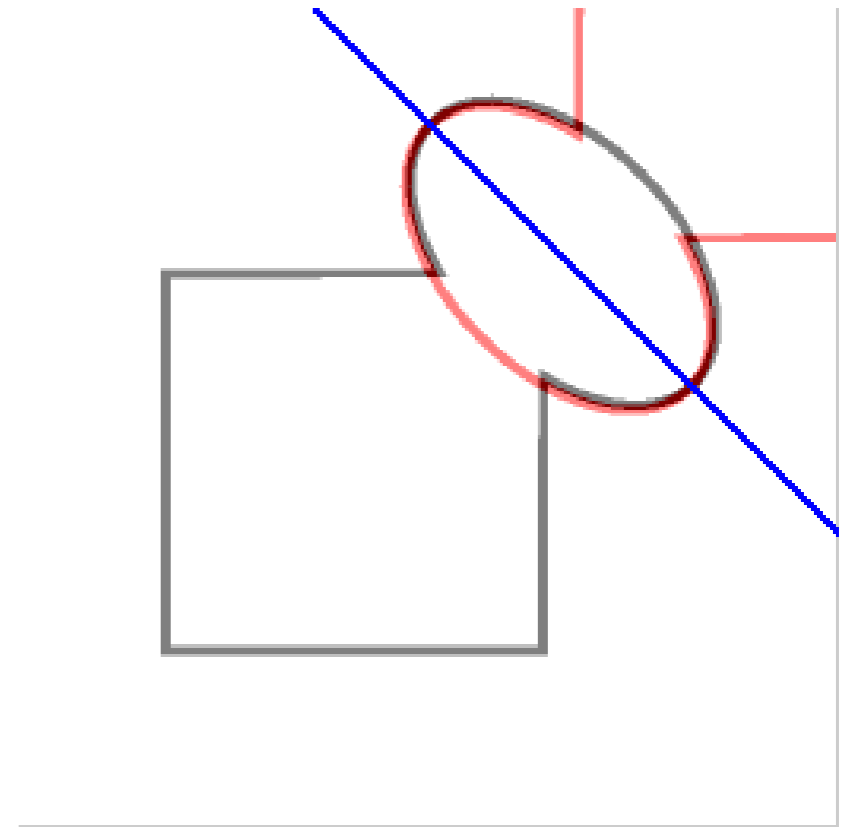
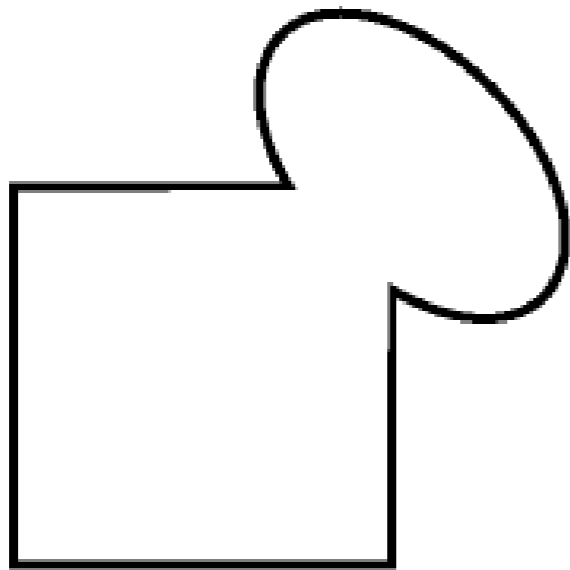


$$D(f, \gamma) = f \cdot \gamma(f)$$

Symmetry = 0.7

Symmetry Measure

Symmetry of a shape is measured by correlation with its reflection

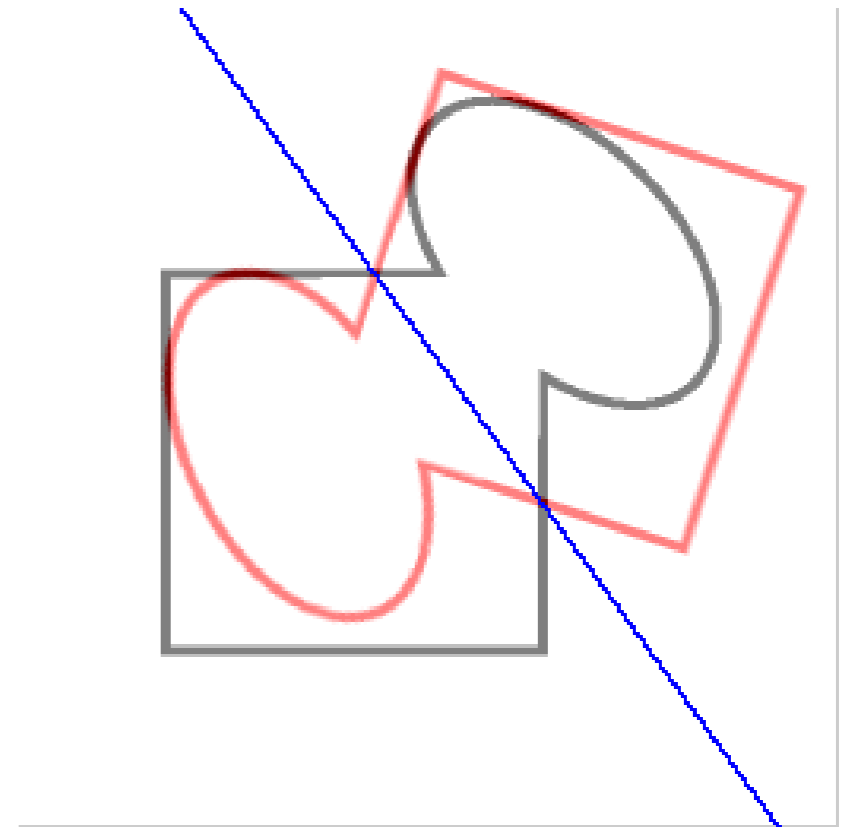
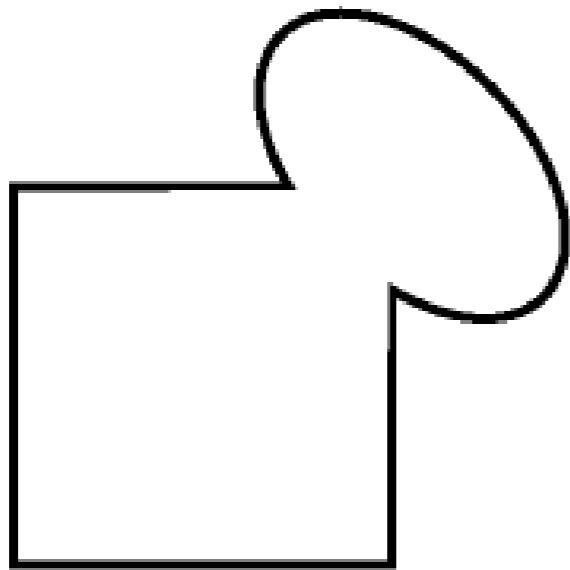


$$D(f, \gamma) = f \cdot \gamma(f)$$

Symmetry = 0.3

Symmetry Measure

Symmetry of a shape is measured by correlation with its reflection

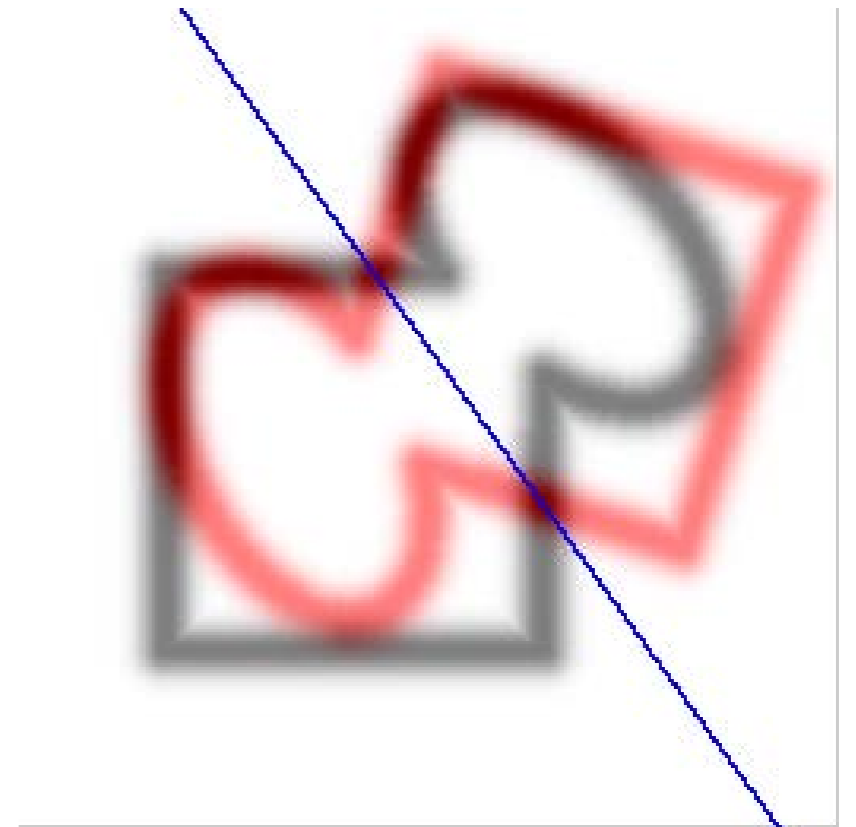


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$$D(f, \gamma) = f \cdot \gamma(f)$$

Symmetry Measure

Symmetry of a shape is measured by correlation with its reflection



$$D(f, \gamma) = f \cdot \gamma(f)$$

Symmetry = 0.1

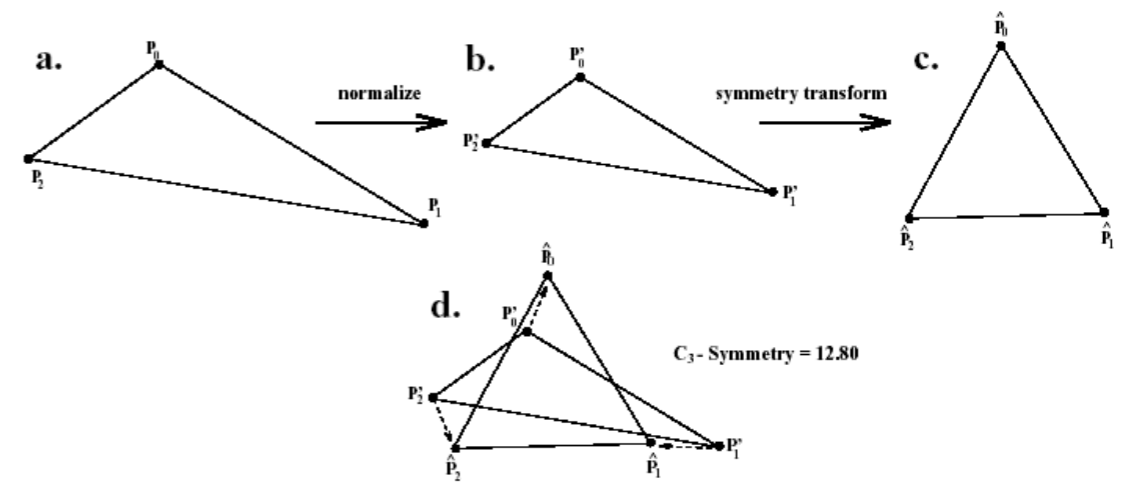
Previous Work

Zabrodsky '95

Kazhdan '03

Thrun '05

Martinet '05



Define the *Symmetry Distance* of a function f with respect to any transformation γ as the L^2 distance between f and the nearest function invariant to γ

Can show that Symmetry Measure $D(f, \gamma) = f \cdot \gamma(f)$ is related to symmetry distance by

$$D(f, \gamma) = -2SD^2 + \|f\|^2$$

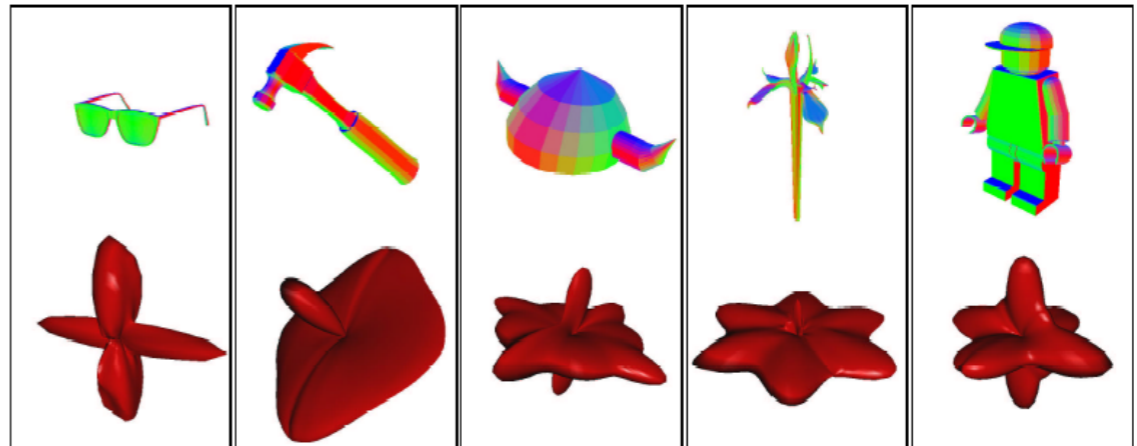
Previous Work

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Previous Work

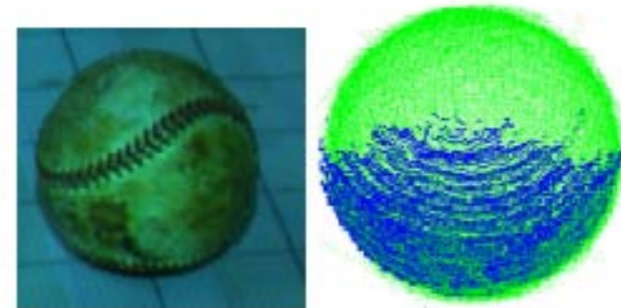
Zabrodsky '95

Kazhdan '03

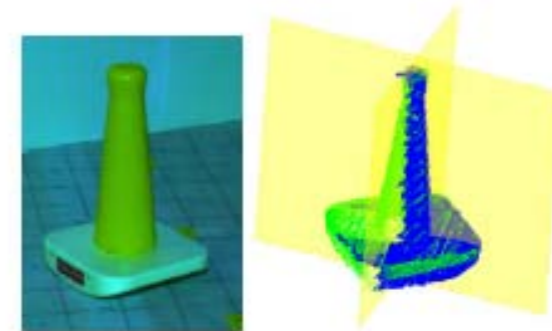
Thrun '05

Martinet '05

Baseball: spherical symmetry



Traffic Cone: two orthogonal plane reflection



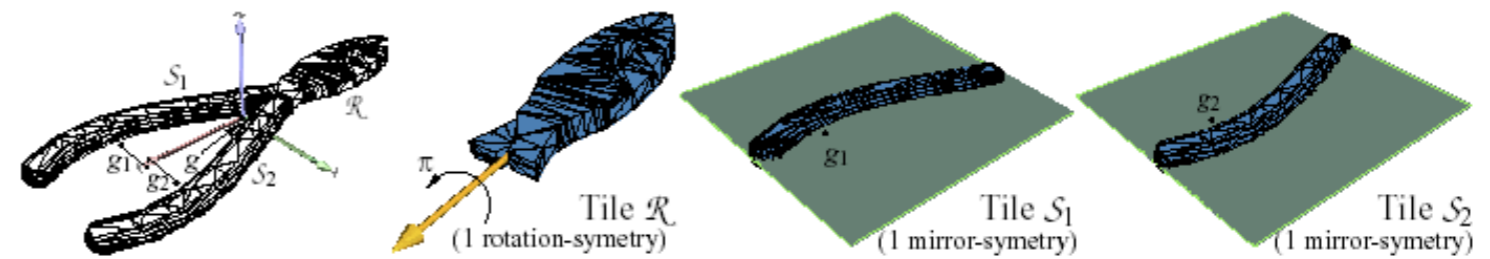
Previous Work

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Computing Discrete Transform

Brute Force

$O(n^6)$

Convolution

Monte-Carlo

$O(n^3)$ planes

X

$O(n^3)$ dot product



Computing Discrete Transform

Brute Force

$$O(n^6)$$

Convolution

$$O(n^5 \text{Log } n)$$

Monte-Carlo

$O(n^2)$ normal directions

X

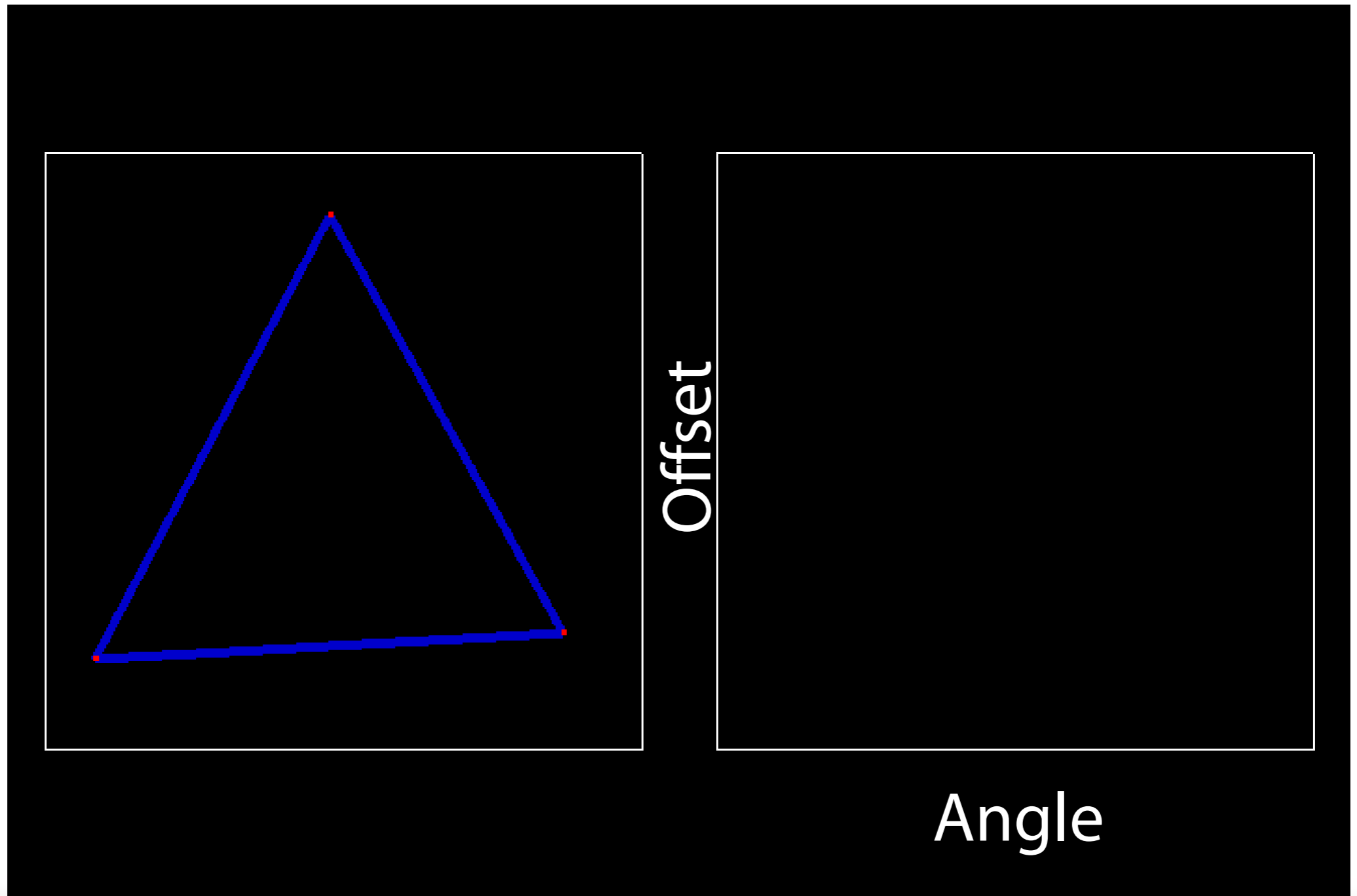
$O(n^3 \text{ log } n)$ per direction

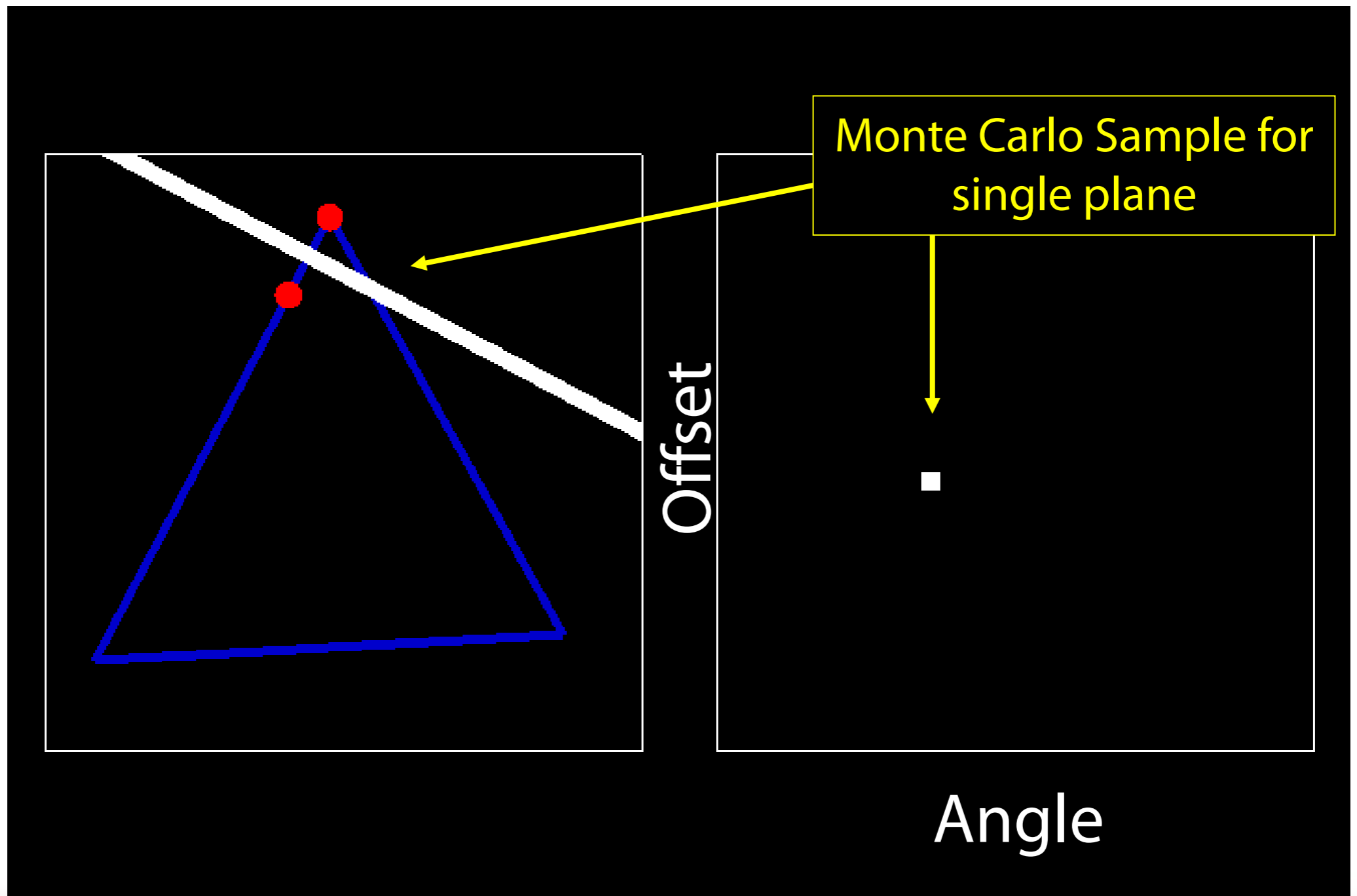


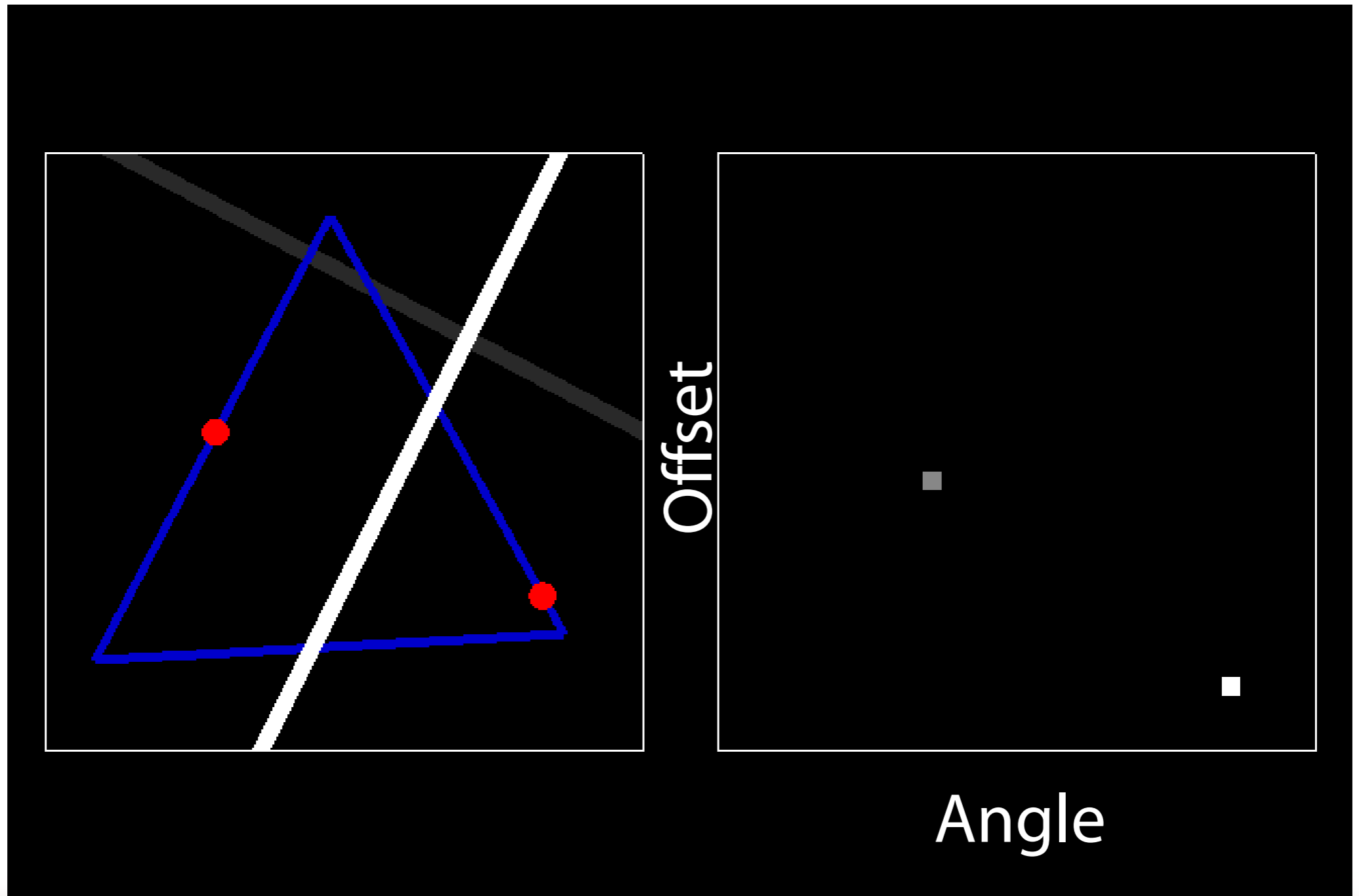
Computing Discrete Transform

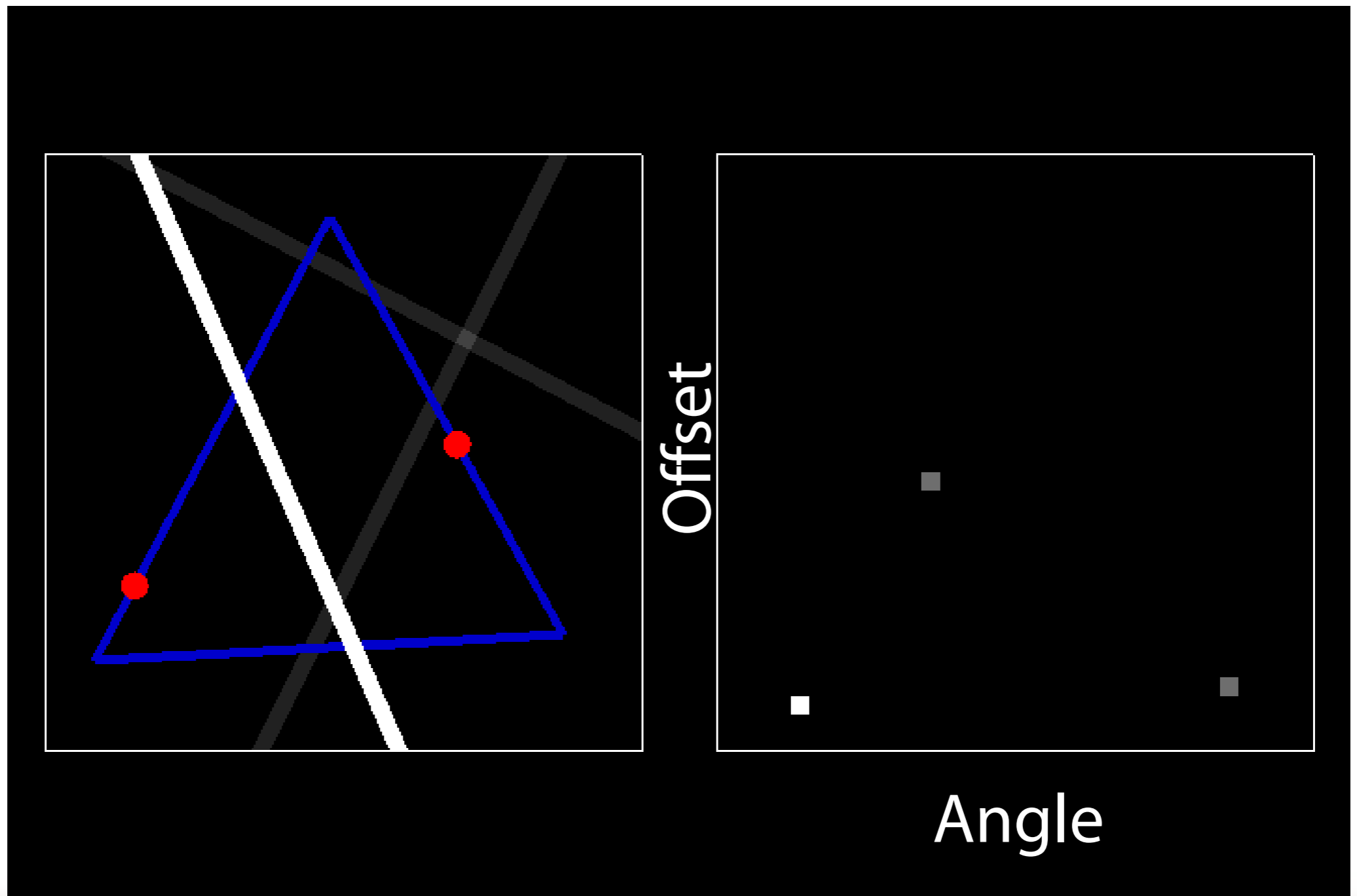
Brute Force	$O(n^6)$
Convolution	$O(n^5 \text{Log } n)$
Monte-Carlo	$O(n^4)$ For 3D meshes

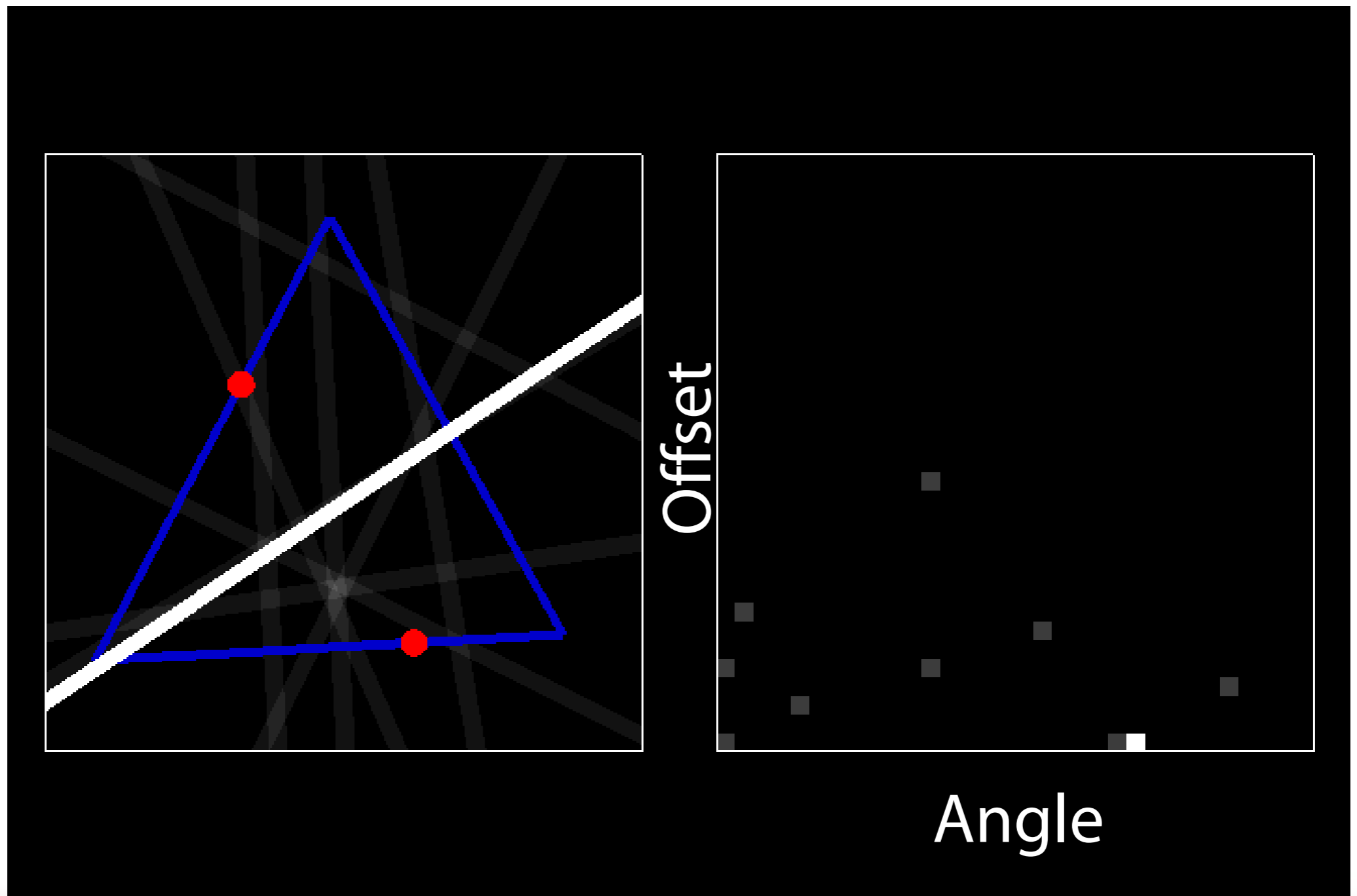
- Most of the dot product contains zeros.
- Use Monte-Carlo Importance Sampling.



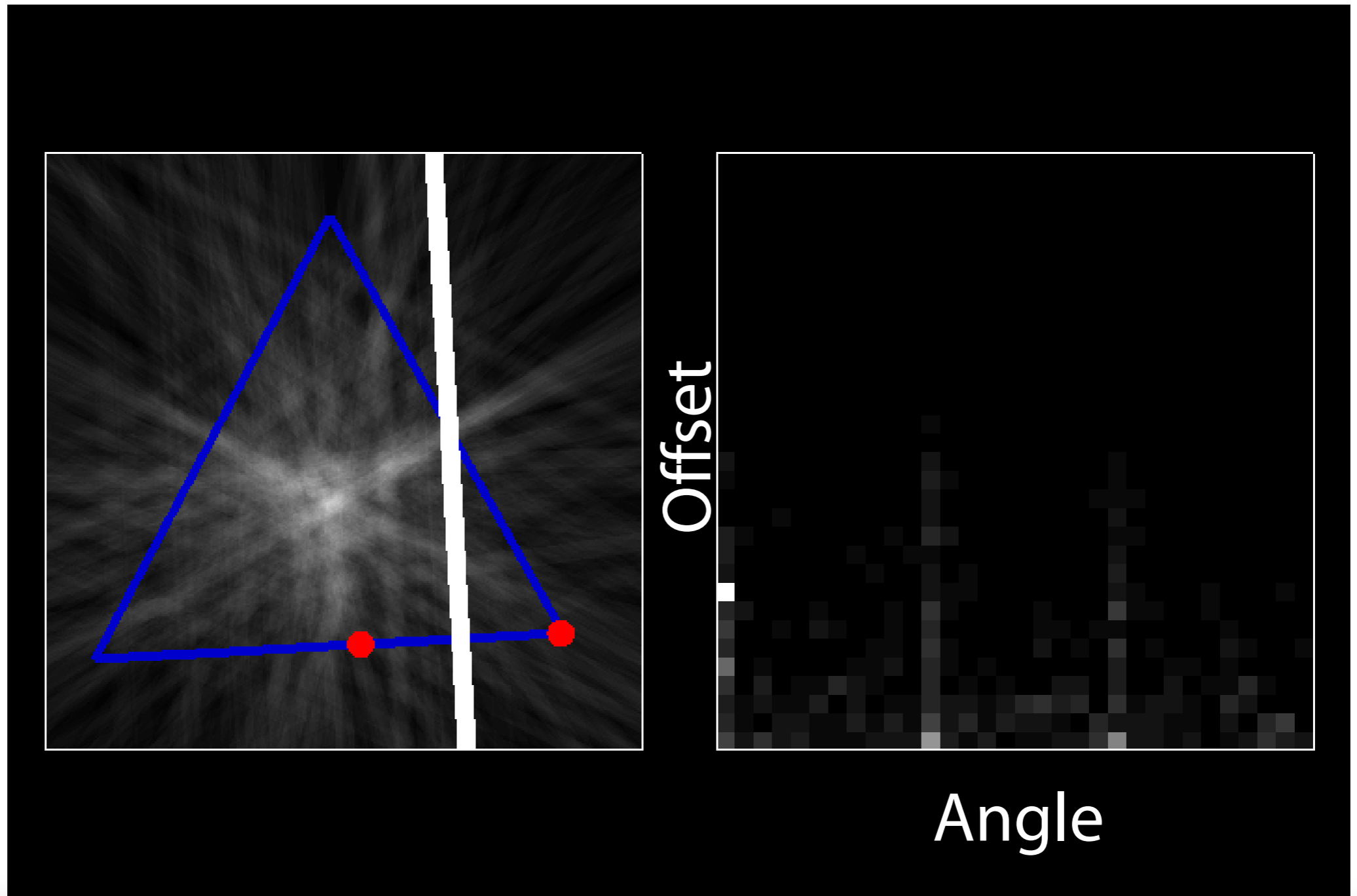


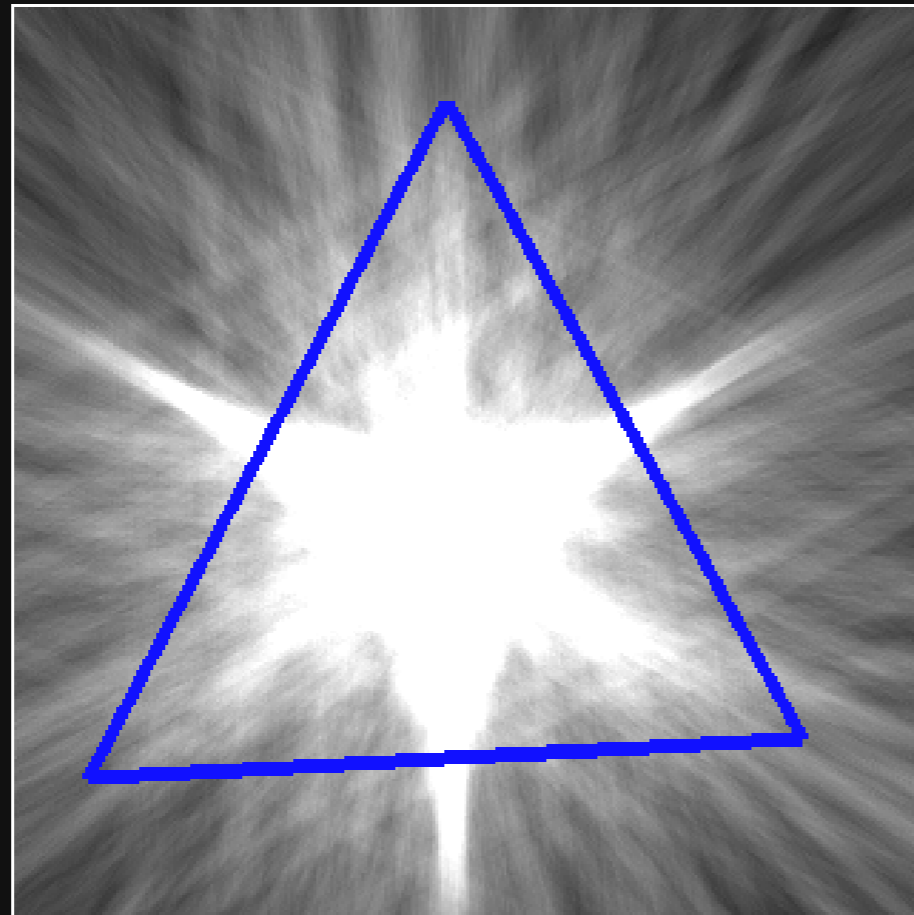




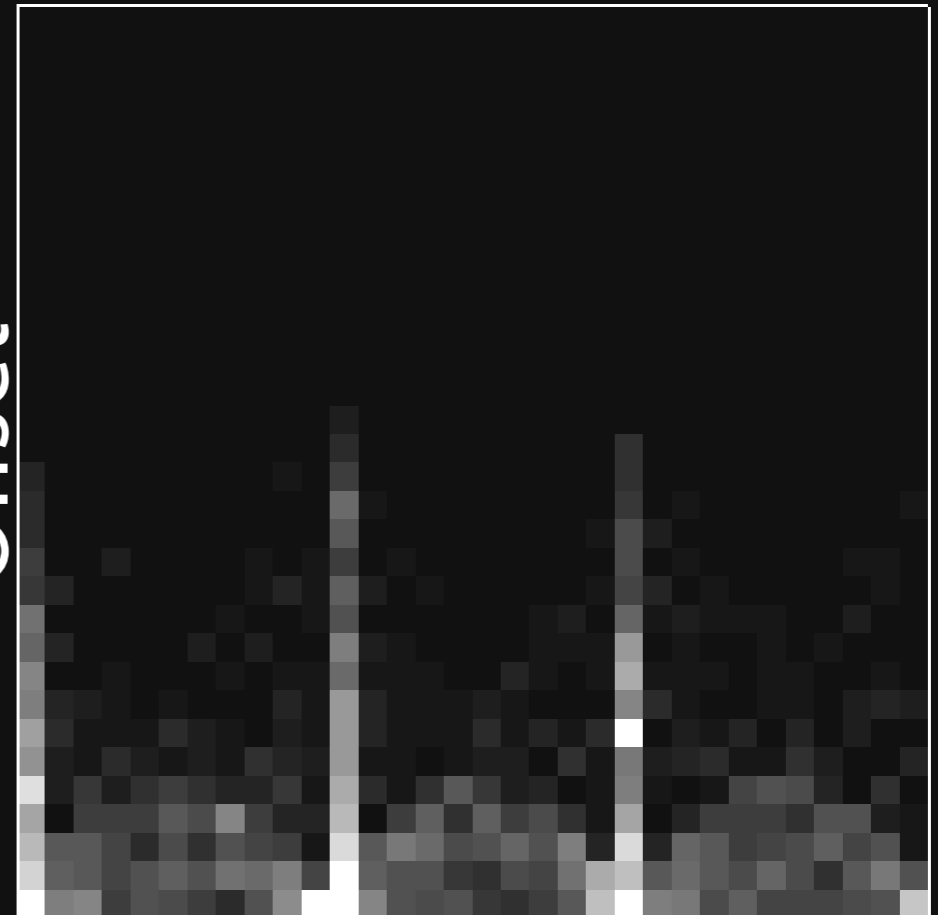


Monte Carlo





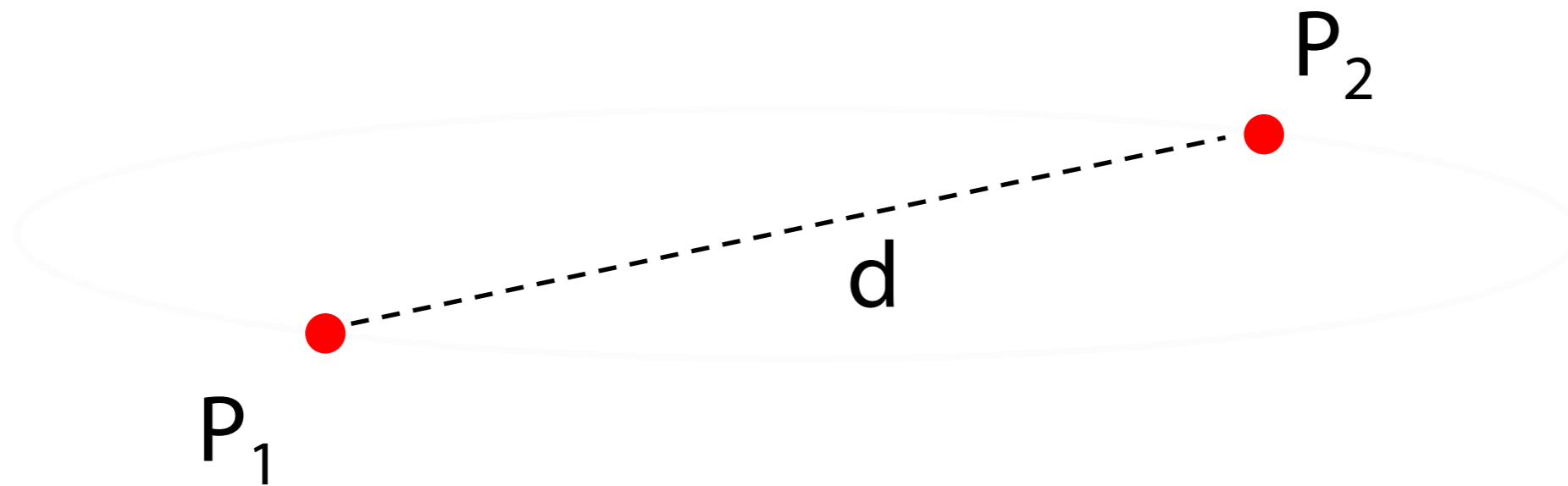
Offset



Angle

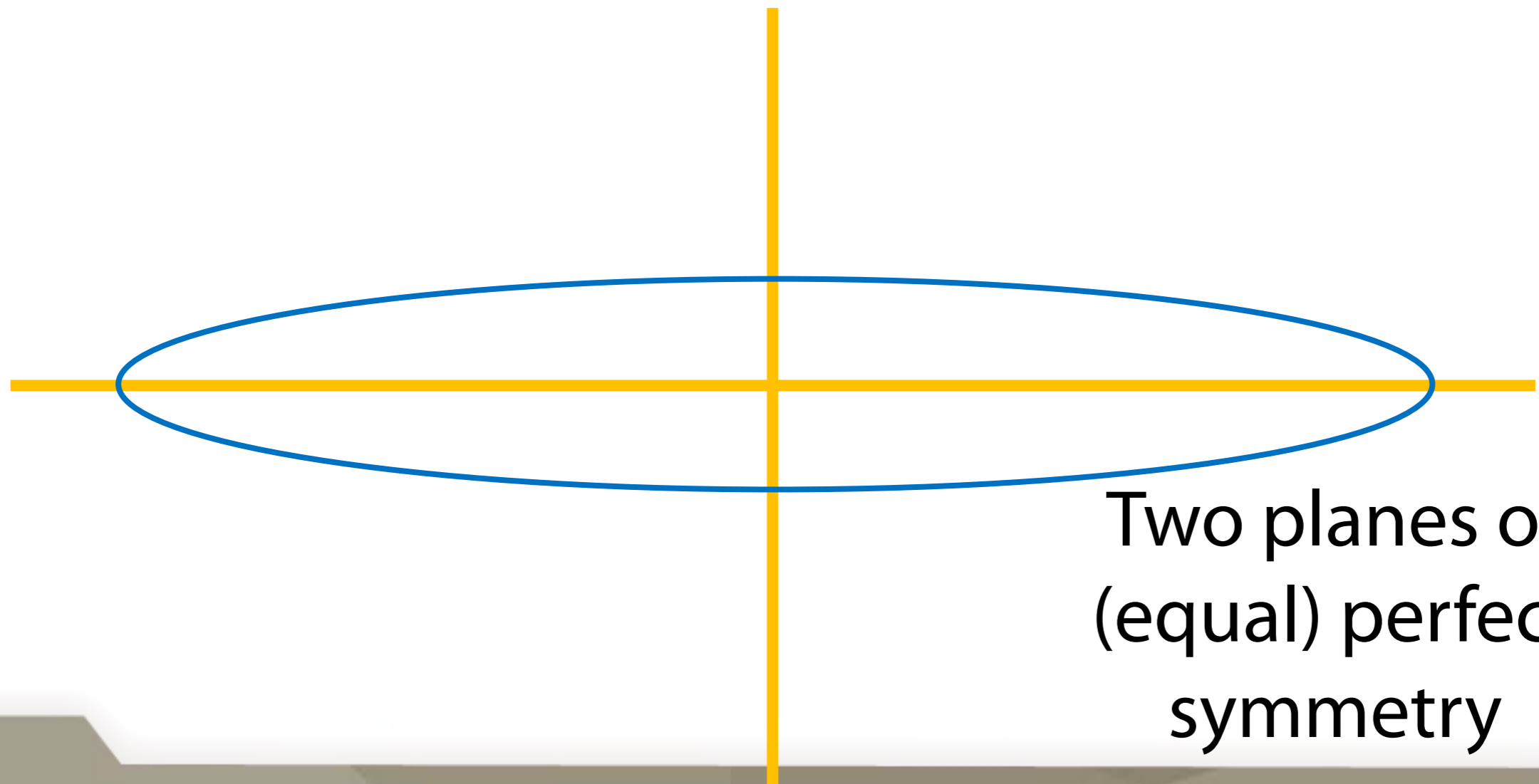
Weighting Samples

Need to weight sample pairs by the inverse of the distance between them



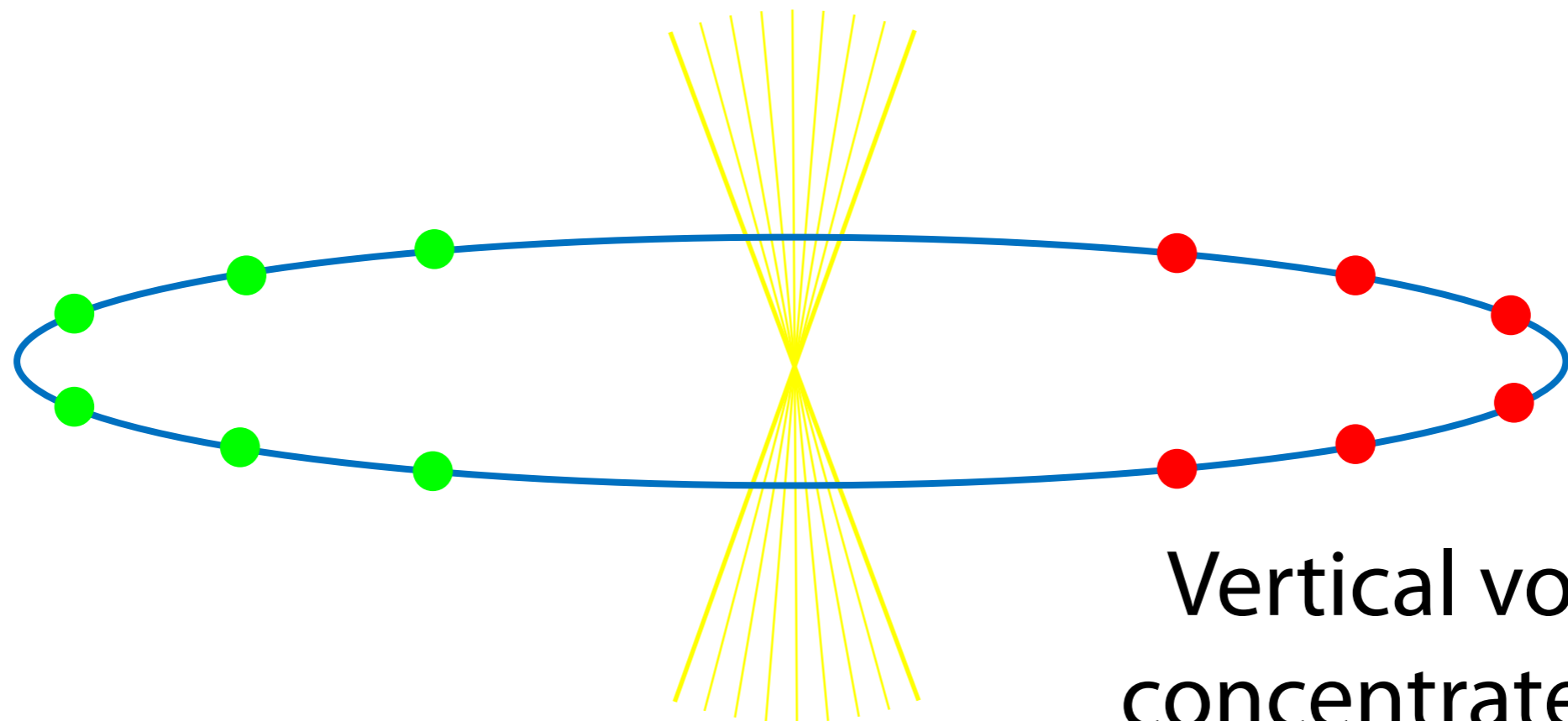
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Weighting Samples

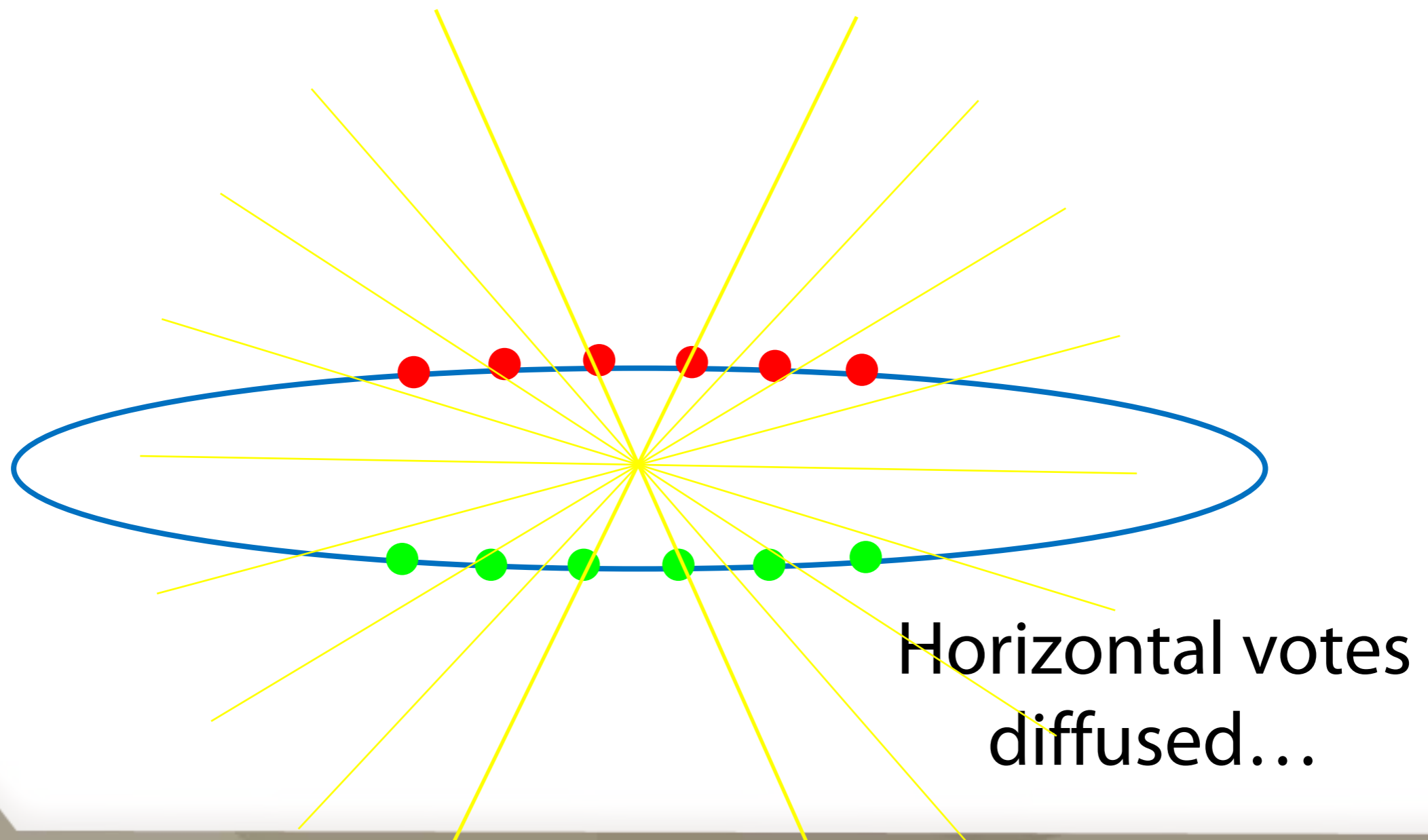
Need to weight sample pairs by the inverse of the distance between them



Vertical votes
concentrated...

Weighting Samples

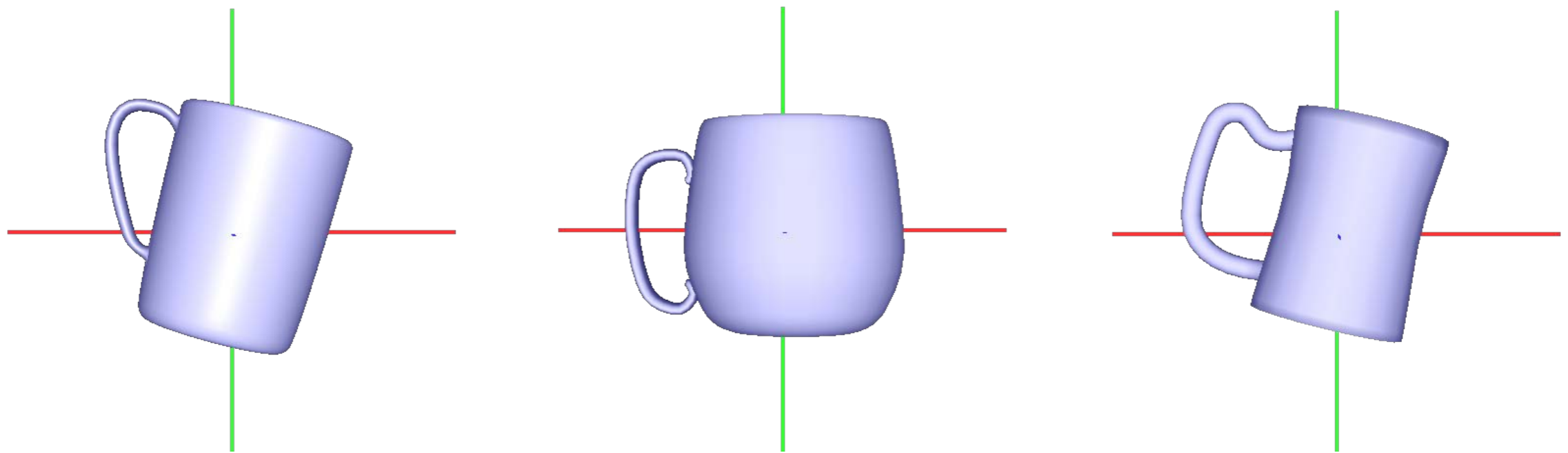
Need to weight sample pairs by the inverse of the distance between them



Motivation:

Composition of range scans

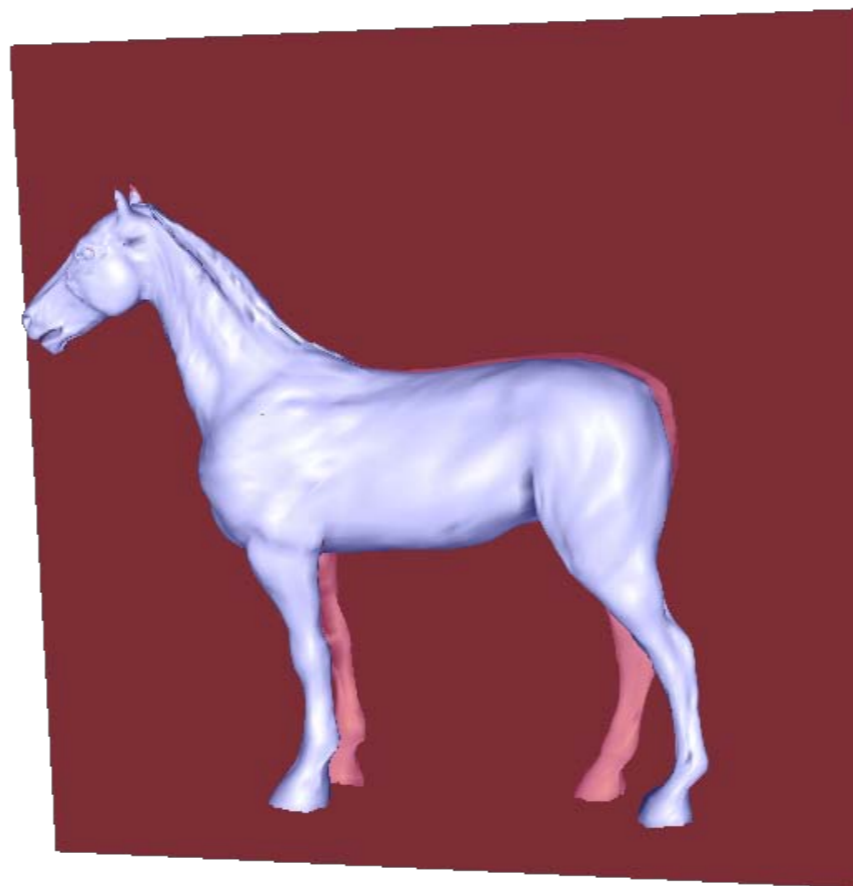
Morphing



PCA Alignment

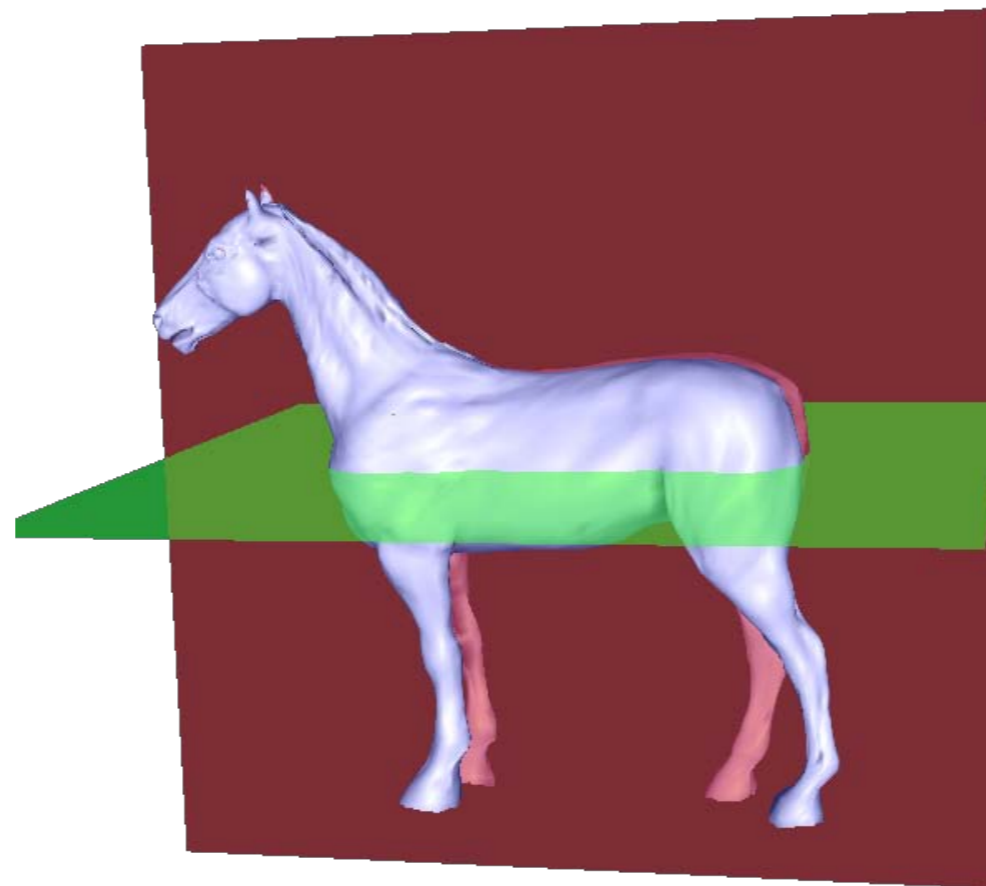
Approach:

Perpendicular planes with the greatest symmetries create a symmetry-based coordinate system.



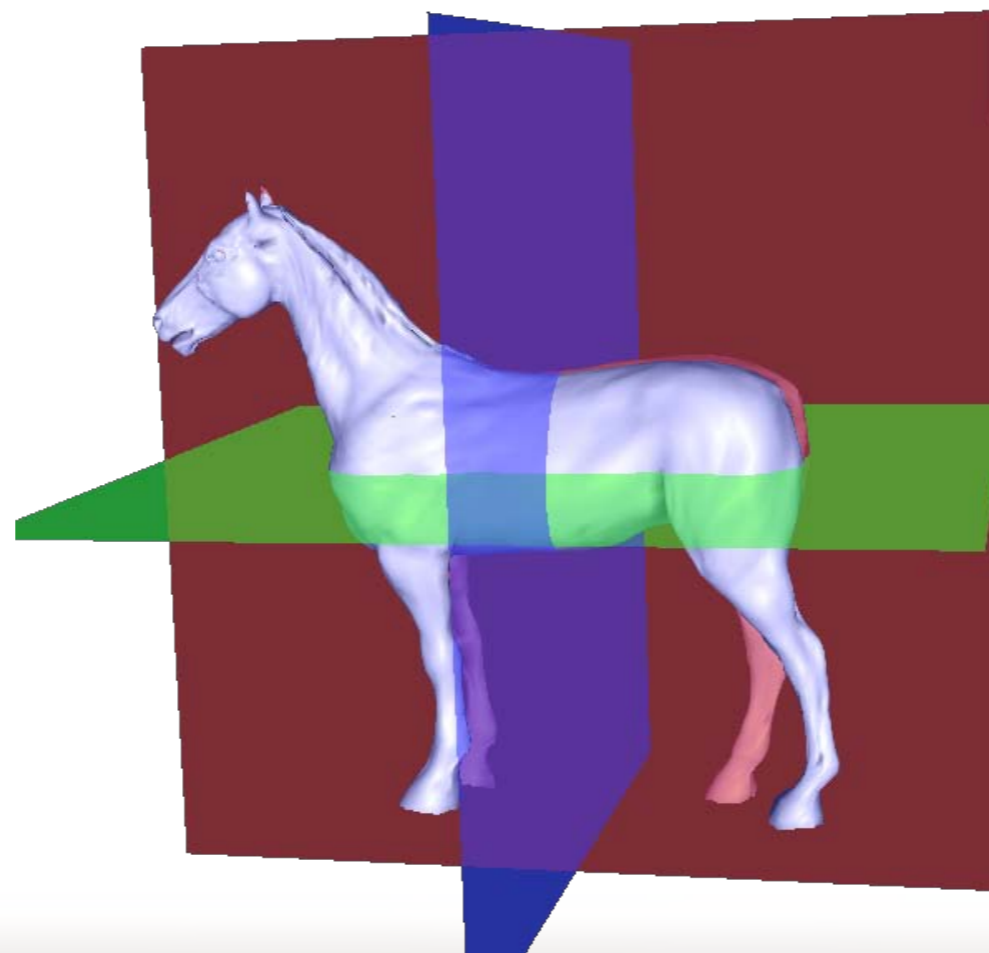
Approach:

Perpendicular planes with the greatest symmetries create a symmetry-based coordinate system.



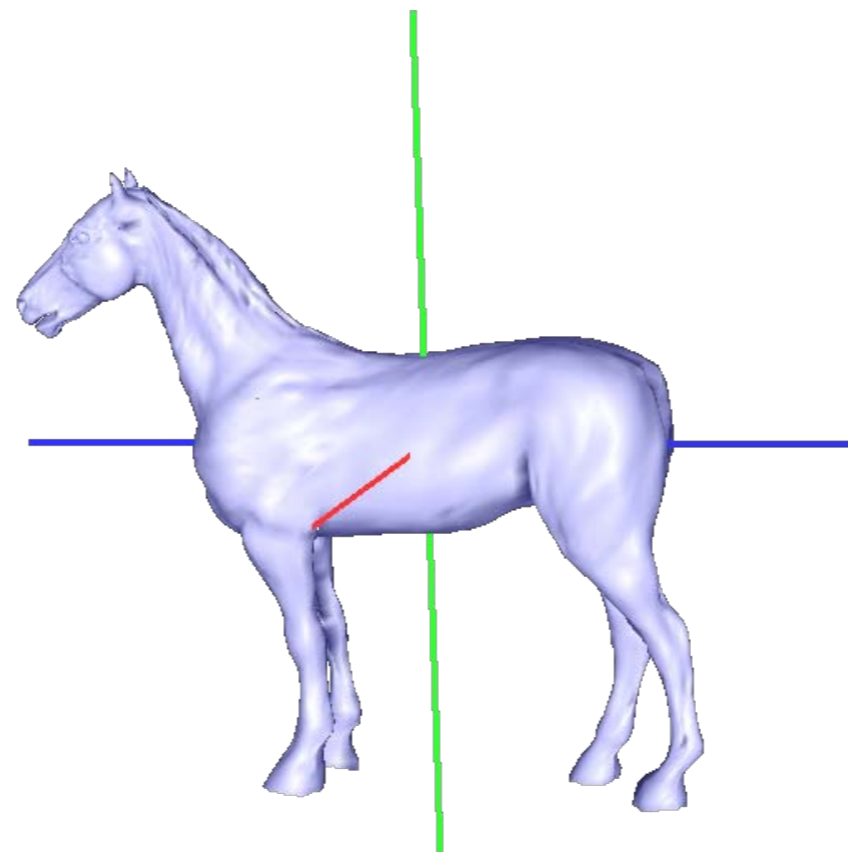
Approach:

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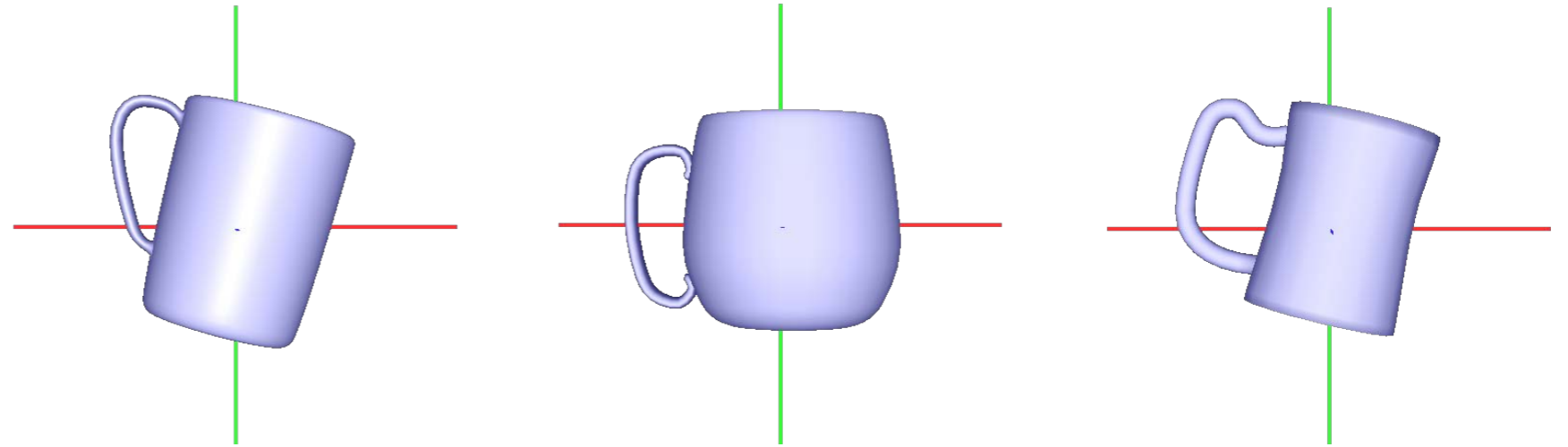
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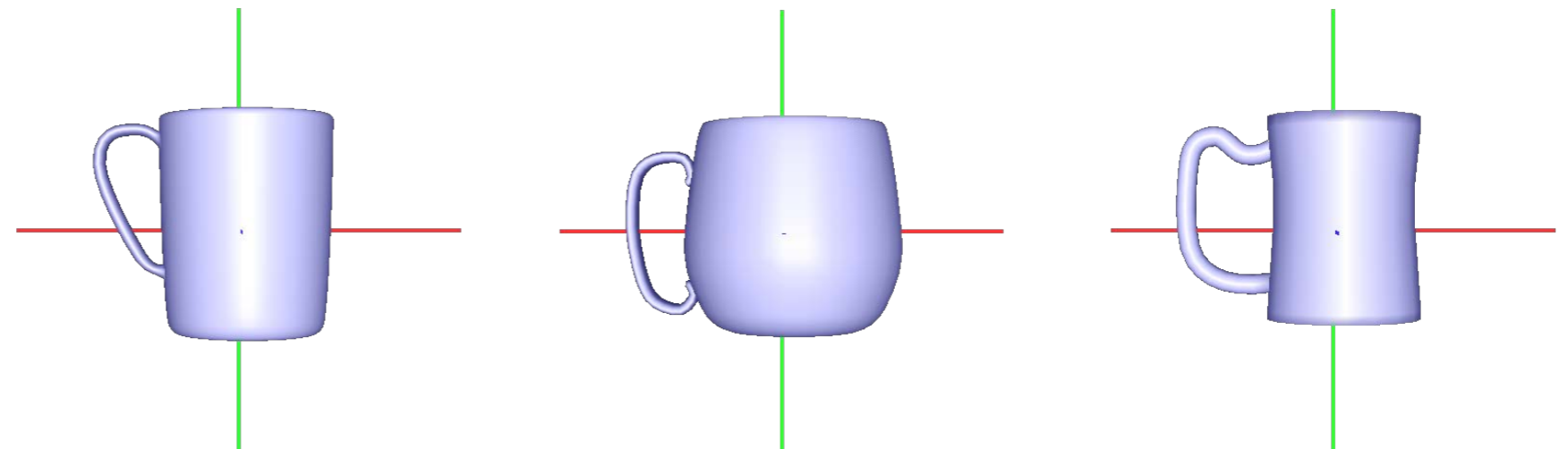


Results:

PCA
Alignment



Symmetry
Alignment

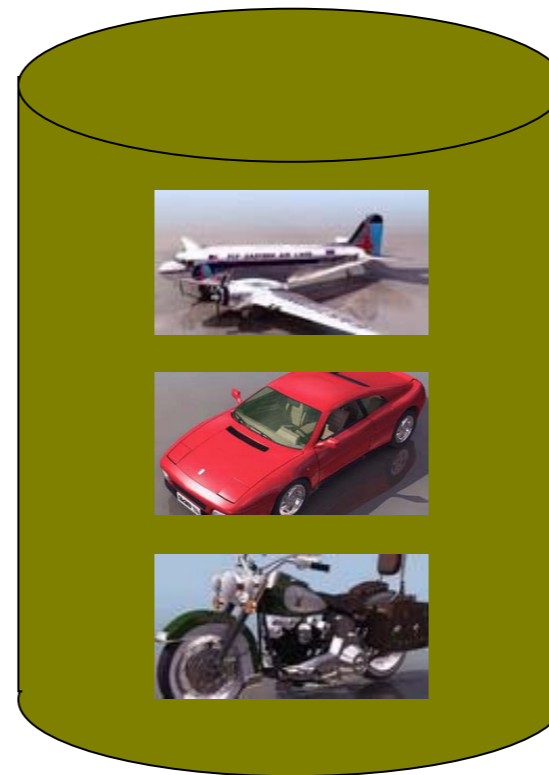


Motivation:

Database searching



Query



Database



Result

Observation:

All chairs display similar principal symmetries



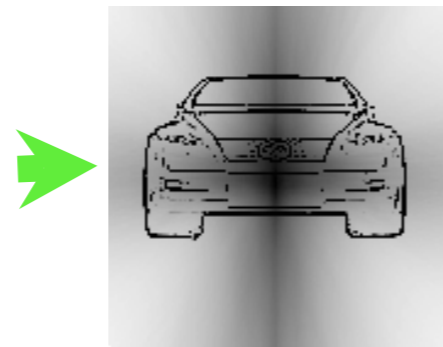
Application: Matching

Approach:

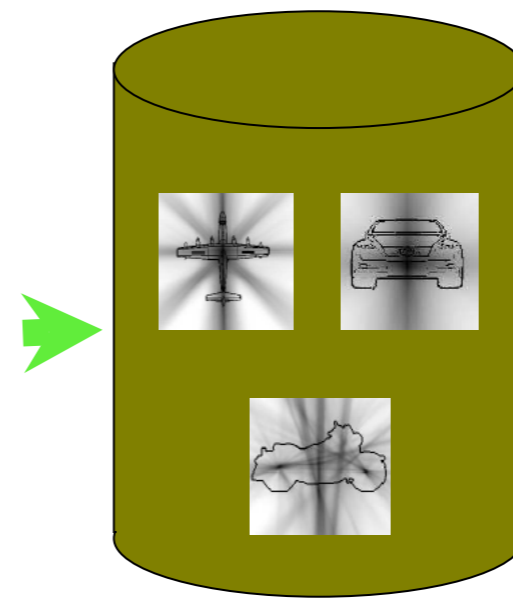
Use Symmetry transform as shape descriptor



Query



Transform



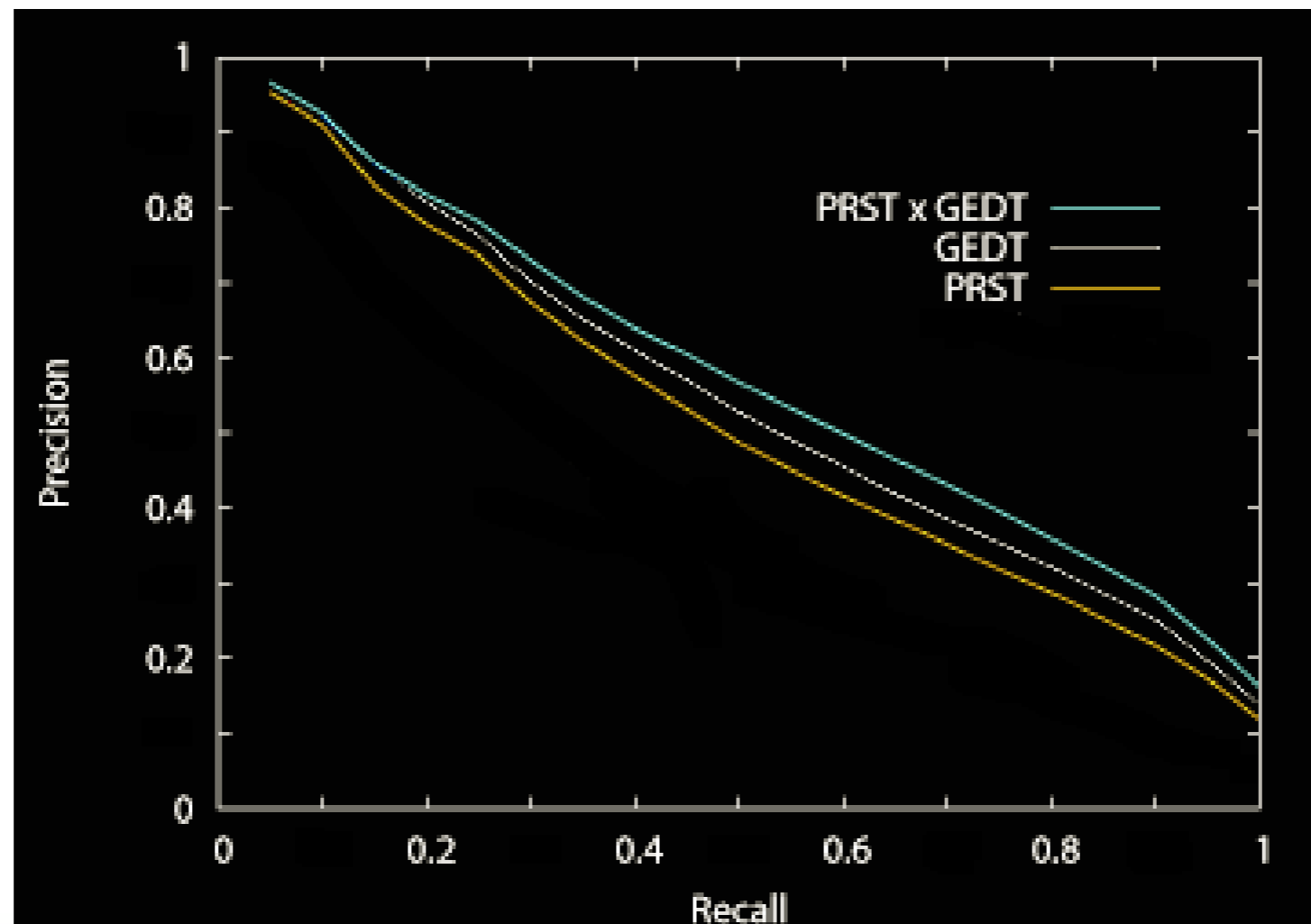
Database



Result

Results:

Symmetry provides orthogonal information about models and can therefore be combined with other descriptors



Planar-Reflective Symmetry Transform

Captures degree of reflectional symmetry about all planes

Monte Carlo computation

Applications: alignment, search, completion, segmentation, canonical viewpoints, ...