

Integer Linear Programming

Introduction

Given: $A \in \mathbb{Z}^{m \times n}$, $b \in \mathbb{Z}^m$, $c \in \mathbb{Z}^n$

Task: Find $x \in \mathbb{Z}^n$, s.t. $Ax \leq b$ and $c^T x$ is maximized.

$$\begin{array}{ll} \max & c^T x \\ \text{s.t.} & Ax \leq b \\ & x \in \mathbb{Z}^n \end{array} \quad (\text{ILP})$$

More general: Mixed integer lin. programming (MILP); only some variables must be integral.

Powerful modelling framework:

▷ binary choice: $x_j \in \{0, 1\}$ (knapsack, shortest path)

▷ relation between vars.: $\sum_{j=1}^n x_j \leq 1$ (\Rightarrow at most one var. can be positive) ($x_j \geq 0$)

▷ disjunctive constraints:

want: $x \geq a$ or $y \geq b$ ($a, b \geq 0$, $x, y \geq 0$)

\Rightarrow introduce $\delta \in \{0, 1\}$

and model $x \geq \delta a$

$$y \geq (1-\delta)b$$

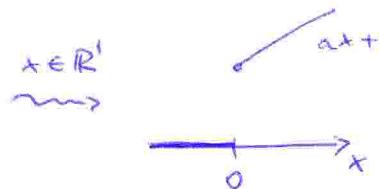
▷ conditional constraints:

want: if $x > a$ then $y \geq b$ (else $y \geq 0$)

$\Leftrightarrow x > a$ or $y \geq b \Rightarrow$ disjunctive constr.

▷ fixed cost: (min)

$$\text{want: } C(x) = \begin{cases} ax + b & \text{if } x > 0 \\ 0 & \text{otherwise.} \end{cases}$$



\Rightarrow introduce $\delta \in \{0, 1\}$

and $x \leq b\delta$, b = upper bound on x

then $C(x, \delta) = ax + b\delta$.

[Why? $x > 0 \Rightarrow \delta = 1 \Rightarrow C(x) = ax + b$]

$x = 0 \Rightarrow \delta = 0$ in opt sol., b.c. $a, b > 0 \Rightarrow C(x) = 0$]

→ ILP: • great flexibility in expressing discrete optimization problems ("it's an art")

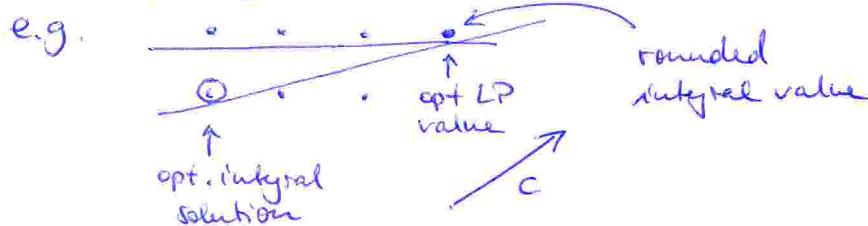
- for the price that it is much harder to solve than LP.

Note: simple rounding often no option!

(i) doesn't make sense if integral var. is decision var.

e.g. shortest path: $x_{uv} = \begin{cases} 1 & u \in SP \\ 0 & u \notin SP \end{cases}$

(ii) generally may cause large errors



Complexity of ILP

Thm. Solving ILP is NP-complete.

[To decide if there is a feasible integral solution is NP-complete.]

Pf. Show AP-hardness by reduction from SAT:

m clauses C_i and n vars. v_j :

$$\Phi = \underbrace{(x_{11} \vee x_{12})}_{C_1} \wedge \underbrace{(x_{21} \vee x_{22} \vee x_{23})}_{C_2} \wedge \dots \wedge \underbrace{(x_{m1} \vee x_{m2} \vee x_{m3} \dots)}_{C_m}$$

$x_{ij} \in \{v, \bar{v}\}$, $v \in \{v_1, \dots, v_n\}$ boolean vars.

Quest.: Does exist a satisfying truth assignment for Φ ?

Construct ILP: $v_j \rightarrow z_j \in \{0, 1\}$, $j = 1, \dots, n$

"false" "true"

For any clause C_i , $i=1, \dots, m$, let $J^+(i)$ and $J^-(i)$ denote the set of indices of non-negated and negated vars. in C_i , resp.

$$(ILP): \sum_{j \in J^+(i)} z_j + \sum_{j \in J^-(i)} (1-z_j) \geq 1, \quad i=1, \dots, m$$

$$z_j \in \{0, 1\}, \quad j=1, \dots, n$$

Claim: \exists satisfying truth assignment for $\phi \Leftrightarrow$ ILP has feas. sol.

" \Rightarrow " Given satisfying truth assignment v^* for ϕ ,
 construct $z^* : z_j^* = \begin{cases} 1 & \text{if } v_j^* = \text{true} \\ 0 & \text{if } v_j^* = \text{false} \end{cases}, j=1, \dots, n$.

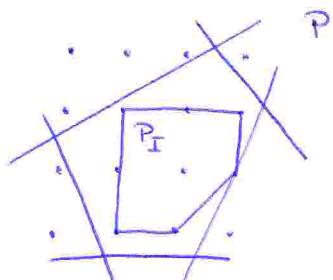
In each clause C_i at least one var. satisfied
 \Rightarrow correspond. ineq. in ILP are satisfied.

" \Leftarrow " z^* feas. solution to ILP \Rightarrow construct $v_j^* = \begin{cases} \text{true} & \text{if } z_j^* = 1 \\ \text{false, otherwise} & \end{cases}$
 \Rightarrow each clause has at least one var. satisfied $\rightarrow \phi$ satisf.

ILP in NP? \rightarrow O(1) - ILP yes, because given solution x^* has poly. size and can be verified in poly. time \Rightarrow oh.
 \rightarrow in general? From Ellipsoid method follows that the values x_j of an opt. sol. cannot be too large ($x_j \leq 4^{n^L} \dots [LN]$) \Rightarrow oh.

□

Integer hull of a polyhedron



- set of feasible integral solutions $\{x \mid Ax \leq b, x \in \mathbb{Z}^n\}$
- note that $P := \{x \mid Ax \leq b\}$ is a polyhedron

Let $P_I = \{x \mid Ax \leq b\}_I$ be the convex hull of the integral vectors in P . (= "integer hull of P ")

\Rightarrow Can write ILP as $\max \{c^T x \mid x \in P_I\}$ where $P_I = \{x \mid Ax \leq b\}$.

↑
 But not clear how to express in lin. ineq..

Proposition

- (i) P bounded $\Rightarrow P_I$ polyhedron ($\{x \mid Ax \leq b, x \in \mathbb{Z}^n\}$ finite)
- (ii) P unbounded, A, b rational $\Rightarrow P_I$ polyhedron
- (iii) P unbounded, A, b arbitrary real, then P_I in general no polyhedron.
- Ex.: $P = \{(x, y) \in \mathbb{R}^2 \mid y \leq \sqrt{2}x\}$

Important question:

Under which conditions is $P = P_I$?

Ans in this case ILP can be solved by solving LP relaxation, i.e.,

$$\begin{array}{ll}\text{max } & c^T x \\ \text{s.t. } & Ax \leq b \\ & \underline{x \in \mathbb{Z}^n} \quad (\text{relax})\end{array}$$

Definition: Polyhedron P is integral $\Leftrightarrow P = P_I$.

Thm. A rational polyhedron is integral

$\Leftrightarrow \max \{c^T x \mid x \in P\} \in \mathbb{Z}$ for any $c \in \mathbb{Z}^n$ (for which finite)

Pf. " \Rightarrow " \checkmark

" \Leftarrow " Suppose $\forall c \in \mathbb{Z}^n: \max \{c^T x \mid x \in P\} \in \mathbb{Z}$.

Let y be unique optimum to $\max \{c^T x \mid x \in P\}$ for some $c \in \mathbb{Z}^n$.

We may assume that $c^T y > c^T x + x_1 - y_1, \forall x \in P, x \neq y$.

(Otherwise multiply c with some large integer.)

$\Rightarrow y$ is also optimal to $\max \{\bar{c}^T x \mid x \in P\}$ for $\bar{c} := (c_1 + 1, c_2, \dots, c_n)^T$.

$$\Rightarrow \bar{c}^T y = c^T y + y_1$$

$$\begin{matrix} \uparrow & \uparrow \\ c \in \mathbb{Z} & \in \mathbb{Z} \end{matrix}$$

$$\Rightarrow y_1 \in \mathbb{Z}.$$

{

Repeat argument for all $y_i \Rightarrow y \in \mathbb{Z}^n$

□

Thm. Let P be rational polyhedron. The following are equivalent:

- (a) P is integral.
- (b) Each non-empty face of P contains integral vectors.
- (c) Each min. face of P contains integral vectors.
- (d) $\max \{ c^T x \mid x \in P\}$ is attained by an integral vector for each $c \in \mathbb{R}^n$ for which the max is finite.

