

Total Dual Integrality

Def. $Ax \leq b$ is called totally dual integral (TDI) if for each $c \in \mathbb{Z}^n$ with $\max \{c^T x \mid Ax \leq b\} < \infty$ holds:

$$\max \{c^T x \mid Ax \leq b\} = \min \{y^T b \mid y^T A = c^T, y \geq 0, y \in \mathbb{Z}^m\}.$$

\implies gives primal integrality "for free".

Cor. Let $A \in \mathbb{Q}^{m \times n}$, $b \in \mathbb{Z}^m$, and $Ax \leq b$ TDI $\implies \{x \mid Ax \leq b\}$ integral.

Pf. Def + Thm.

($b \in \mathbb{Z}^m \implies y^T b$ with $y \in \mathbb{Z}^m$ is integral again)

Application / Example

Given: directed graph $D = (V, A)$, $s, t \in V$
 $P = \{s-t \text{ paths in } D\}$, $c: A \rightarrow \mathbb{R}_+$

Task: Assign weights $y_a \geq 0, a \in A$, s.t. weight on any $s-t$ path is at least 1.

Obj.: $\min \sum_{a \in A} c(a) y_a$

LP formulation:

$$\begin{aligned} & \min \sum_{a \in A} c(a) y_a \\ & \text{s.t. } \sum_{P \in \mathcal{P}} y_P \geq 1, \quad P \in \mathcal{P} \\ & \quad y_a \geq 0, \quad a \in A \end{aligned} \quad \left. \vphantom{\begin{aligned} & \min \sum_{a \in A} c(a) y_a \\ & \text{s.t. } \sum_{P \in \mathcal{P}} y_P \geq 1, \quad P \in \mathcal{P} \\ & \quad y_a \geq 0, \quad a \in A \end{aligned}} \right\} \text{polyhedron } Q$$

Claim: Q is integral because it is TDI.

dual: $\max \sum_{P \in \mathcal{P}} 1 \cdot x_P$
 s.t. $\sum_{P: a \in P} x_P \leq c(a), \forall a \in A$
 $x_P \geq 0, \forall P \in \mathcal{P}$

\rightarrow This is a formulation of the max $s-t$ -flow problem. If the "capacities" $c(a), a \in A$, are integral, then there exists an integral max flow.
 \implies Coroll. above implies that Q is integral.

Remark: TDIness is not a property of polyhedra but a property of lin.ineq. systems. There can be two diff. descriptions of a particular polyhedron by ineq. systems s.t. one is TDI and the other one is not.

Ex.

$$\begin{pmatrix} 1 & 1 \\ 1 & 0 \\ 1 & -1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} \leq \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \quad \text{and} \quad \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} \leq \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

[TDI] [not TDI]

Generally TDI systems contain more constraints than necessary for just defining the polyhedron.

↳ Adding valid ineq. does not destroy TDI ness:

Prop. If $Ax \leq b$ is TDI and $a^T x \leq \beta$ is valid ineq. for $\{x \mid Ax \leq b\}$ then $Ax \leq b, a^T x \leq \beta$ is also TDI.

Pf. For $c \in \mathbb{Z}^n$:

$$\begin{aligned} (*) &= \min \{ y^T b \mid y^T A = c^T, y \geq 0 \} \stackrel{(D4)}{=} \max \{ c^T x \mid Ax \leq b \} \\ &= \max \{ c^T x \mid Ax \leq b, a^T x \leq \beta \} \\ &\stackrel{(dual)}{=} \min \{ y^T b + \gamma \beta \mid y^T A + \gamma a^T = c^T, y, \gamma \geq 0 \} \\ &= (***) \end{aligned}$$

(*) has opt. integral solution y^* since $Ax \leq b$ is TDI.

∴ (***) has opt. integral solution $(y^*, 0) = (y, \gamma)$. □

Cor. • $Ax \leq b, x \geq 0$ is TDI if $\min \{ y^T b \mid y^T A \geq c, y \geq 0 \}$ has integral opt. solution y for each $c \in \mathbb{Z}^n$ for which min is finite.

• $Ax = b, x \geq 0$ is TDI if $\min \{ y^T b \mid y^T A \geq c \}$ has integral opt. solution y for each $c \in \mathbb{Z}^n$ for which min is finite.

→ Existence of TDI description with integral A ?

Thm. For each rational polyhedron P , there exists a rational TDI-system $Ax \leq b$ with A integral and $P = \{x \mid Ax \leq b\}$.
 In particular, $b \in \mathbb{Z}^m \Leftrightarrow P$ integral.

→ Connection between TDI system and integral polyhedra.

=> "procedure" to prove integrality of polyhedra (justified by prev. Thm.)

- Find appropriate defining system $Ax \leq b$ with A, b integral.
- Prove $Ax \leq b$ TDI.
- From Thm. follows that $\{x \mid Ax \leq b\}$ integral.

must exist, but might be difficult to find!

Question:

Are there matrices A s.t. $Ax \leq b, x \geq 0$ is TDI for each $b \in \mathbb{Z}^m$?

→ totally unimodular matrices

