




Course 10
 Realistic Materials in Computer Graphics
Translucent Materials
 Michael Goesele
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 (moving to the University of Washington)

Translucent Objects




- light is scattered through the object
- incident illumination smoothed due to diffuse scattering inside media


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Inhomogeneous Translucent Objects





- caused by material variation or internal structure
- required for realistic appearance


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Varying Local Illumination



- caused by shadows or directional light sources



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Overview


- models for translucent objects
- the BSSRDF
- dipole approximation
- acquisition with DISCO
 - hierarchical model for multiple scattering



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Models for Translucent Objects



- basic physical properties
 - e.g., absorption and scattering cross sections σ_a and σ_s [Ishimaru78]
 - defined for the whole object volume
- rendering possible with variety of techniques such as
 - finite element methods [Rushmeier90, Sillion95, Blasi93]

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Models for Translucent Objects



- rendering techniques (contd.)
 - finite element methods [Rushmeier90, Sillion95, Blasi93]
 - bidirectional path tracing [Hanrahan93, Lafortune96]
 - photon mapping [Jensen98, Dorsey99]
 - Monte Carlo simulations [Pharr00, Jensen99]
 - diffusion [Stam95, Stam01]
 - precomputed radiance transfer [Sloan03a]

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Models for Translucent Objects



- light fields / reflectance fields
 - light fields [Levoy96, Gortler96, Miller98, Wood00, ...]
 - reflectance fields [Debevec00, Malzbender01]
 - opacity hulls [Matusik03]
 - incident light fields [Masselus03]
- ⇒ no correct response to locally varying illumination
- ⇒ see remainder of the course

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Models for Translucent Objects



- specialized models
 - BSSRDF [Nicomemus 1977]
 - dipole approximation [Jensen et al. 2001]
 - includes measurements of physical parameters for homogeneous materials
 - DISCO system to acquire diffuse multiple scattering model R_d [Goesele et al. 2004]
 - modeling of inhomogeneous materials

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The BSSRDF

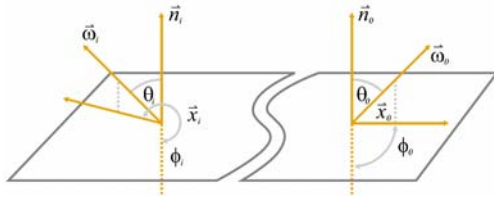


- bidirectional scattering-surface reflectance distribution function [Nicomemus 1977]
 - general model of light transport inside an object
 - (almost) equivalent to a reflectance field [Debevec et al. 2000]
 - ratio of reflected radiance to incident flux

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The BSSRDF



$$S(\vec{x}_i, \hat{\omega}_i; \vec{x}_o, \hat{\omega}_o) := \frac{dL^-(\vec{x}_o, \hat{\omega}_o)}{d\Phi^-(\vec{x}_i, \hat{\omega}_i)}$$

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The BSSRDF



- outgoing radiance computed by integrating over the whole surface and all incoming directions

$$L^-(\vec{x}_o, \hat{\omega}_o) = \int_A \int_{\Omega} L^-(\vec{x}_i, \hat{\omega}_i) \cdot S(\vec{x}_i, \hat{\omega}_i; \vec{x}_o, \hat{\omega}_o) \langle \hat{n}_i \cdot \hat{\omega}_i \rangle d\hat{\omega}_i d\vec{x}_i$$

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The BSSRDF



$$S(\vec{x}_i, \hat{\omega}_i; \vec{x}_o, \hat{\omega}_o) := \frac{dL^-(\vec{x}_o, \hat{\omega}_o)}{d\Phi^-(\vec{x}_i, \hat{\omega}_i)}$$

- 8 dimensional function, tedious to handle
- basic behavior of translucent objects:
 - light is scattered inside
 - light distribution gets diffuse after several scattering events

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Single Scattering vs. Multiple Scattering



- single scattering contribution strongly dependent on incoming light direction
 - example: honey pot illuminated by a laser from the left



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Single Scattering vs. Multiple Scattering



- multiple scattering (almost) independent of incident light direction
 - example: alabaster block illuminated by a laser from the left



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Single Scattering vs. Multiple Scattering



- often modeled independently, e.g.,
 - single scattering using ray tracing
 - multiple scattering using a less complex model with diffuse approximation



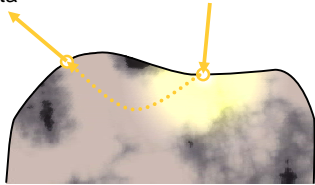
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Diffuse Approximation



- BSSRDF too complex for many application
 - acquisition, storage, ...
 - all combinations of directions and positions
 - 8D data



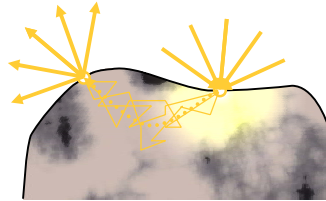
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Diffuse Approximation



- neglect directional dependence
 - frequent scattering events in optically dense media lead to diffuse scattering inside the media



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Diffuse Approximation



- approximate BSSRDF by diffuse reflectance
 - only 4 dimensions
 - requires Fresnel terms at incoming and outgoing locations
 - simplifies handling drastically

$$S(\vec{x}_i, \hat{\omega}_i; \vec{x}_o, \hat{\omega}_o) = \frac{1}{\pi} F_t(\eta, \hat{\omega}_i) R_d(\vec{x}_i, \vec{x}_o) F_t(\eta, \hat{\omega}_o)$$

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Overview



- models for translucent objects
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- **dipole approximation**
- acquisition with DISCO
 - hierarchical model for multiple scattering



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Dipole Approximation



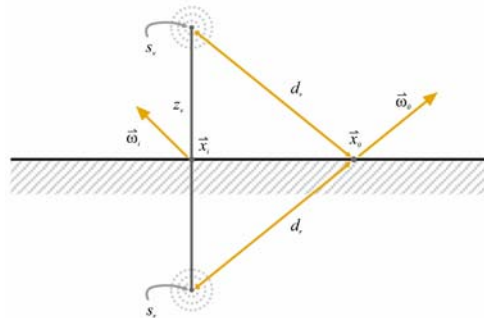
- [Jensen et al. 2001]
- infinite half-space of homogeneous material
- optically dense, modeling of multiple scattering

$$R_d(\vec{x}_i, \vec{x}_o) = \frac{\alpha'}{4\pi} \left[z_r (1 + \sigma_{tr} d_r) \frac{e^{-\sigma_t d_r}}{d_r^3} + z_v (1 + \sigma_{tv} d_v) \frac{e^{-\sigma_t d_v}}{d_v^3} \right]$$

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Dipole Approximation



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Dipole Approximation



$$\begin{aligned}
 z_r &= 1/\sigma'_t \\
 z_v &= z_r + 4AD \\
 d_r &= \|\vec{x}_r - \vec{x}_o\|, \text{ with } \vec{x}_r = \vec{x}_i - z_r \hat{n}_i \\
 d_v &= \|\vec{x}_v - \vec{x}_o\|, \text{ with } \vec{x}_v = \vec{x}_i + z_v \hat{n}_i \\
 A &= \frac{1 + F_{dr}}{1 - F_{dr}} \\
 F_{dr} &= -\frac{1.440}{\eta^2} + \frac{0.710}{\eta} + 0.668 + 0.0636\eta \\
 D &= 1/3\sigma'_t \\
 \sigma_{tr} &= \sqrt{3\sigma_a\sigma'_t} \\
 \sigma'_t &= \sigma_a + \sigma'_s \\
 \sigma'_t &= \sigma'_s / \sigma'_t
 \end{aligned}$$

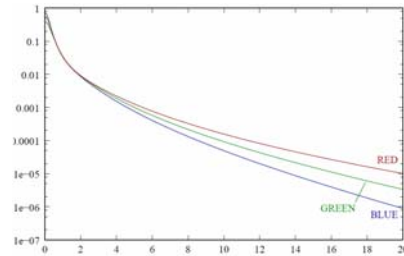
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Dipole Approximation



- example: marble from [Jensen et al. 2001]



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Determining Physical Parameters



- required for dipole approximation
 - scattering and absorption coefficient $\sigma'_s \sigma_a$
 - relative index of refraction η
- also required for evaluation of single scattering term

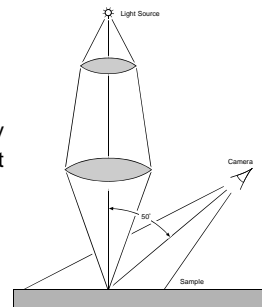
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Determining Physical Parameters



- image-based measurement setup [Jensen et al. 2001]
 - surface point illuminated by focused beam of white light
 - object observed by digital camera
 - parameters determined via diffusion solution



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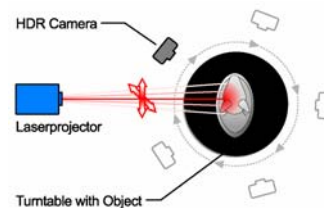
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DISCO Acquisition Approach



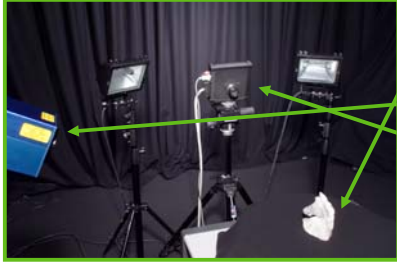
- illuminate individual surface points with laser projector
- record impulse response of the object with HDR video camera



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Acquisition Equipment



- turntable
- laser projector
- HDR camera
- black room

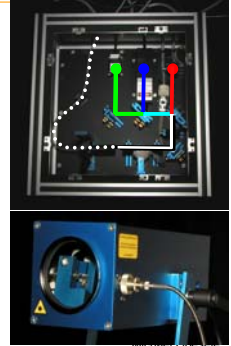
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Laser Projector



- three lasers
 - (635nm, 532nm, 476nm)
 - ~10mW optical power
- constancy
- resolution 4096x4096 steps
 - step size < 0.1 mm on object possible
- repeatable



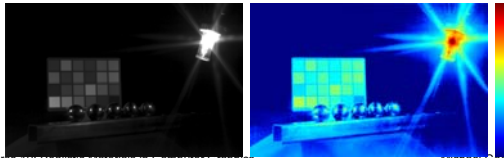
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HDR Video Camera



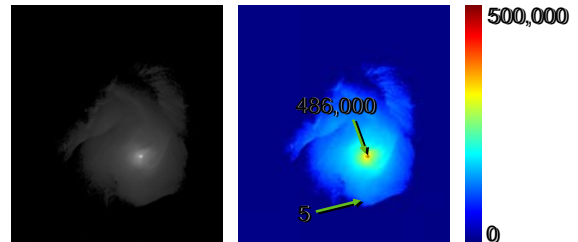
- Silicon Vision Lars III
 - other HDR video cameras also available
- monochrome HDR
- dynamic range > 1:1,000,000
- acquisition with 15 fps



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Inherent High Dynamic Range



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Throughput Factor Matrix



- 500,000-1,000,000 images acquired
- all views where the same point is illuminated yield one column of the point-to-point matrix

problems:

- approx $100,000^2$ entries
- still a lot of holes
- impractical to render

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Hierarchical Model



- properties of radiosity inside object
 - exponential fall-off
 - strong variation near incident illumination
 - smooth variation far away from incident illumination
 - modified by fine-scale structure close to surface

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Hierarchical Model



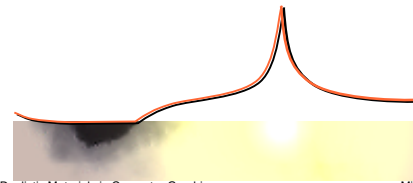
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Hierarchical Model



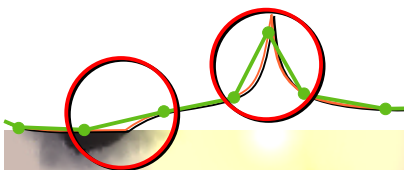
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Hierarchical Model



- global response as sparse transfer matrix
 - e.g., vertex-to-vertex throughput factors on mesh
 - fine scale detail preserved by a modulation texture



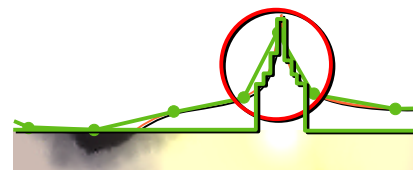
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Hierarchical Model



- local response
 - pixel-to-pixel throughput factors in texel space
 - small neighborhood only



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Resampling



- resample images into hierarchical model
 - assemble global term at vertex positions
 - determine filter kernels in texture space
- problems
 - incomplete sampling
 - *missing data needs to be interpolated*
 - measurement noise
 - see [Goesele et al. 2004] for details

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Results



photograph

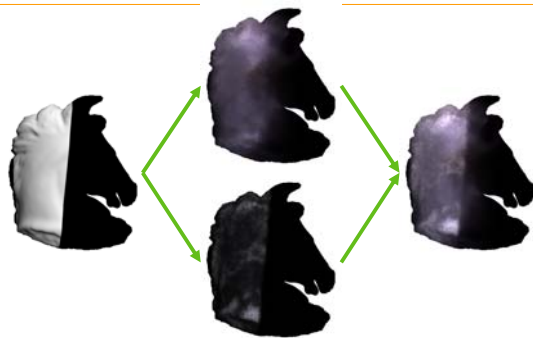


rendering

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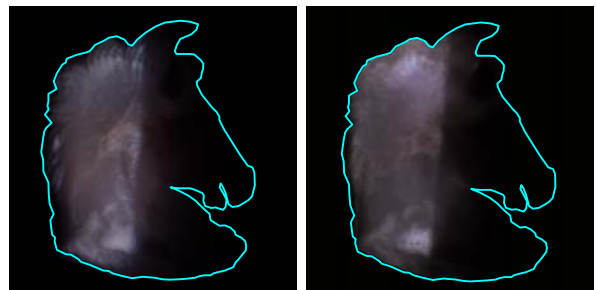
Results: Local Illumination Variation



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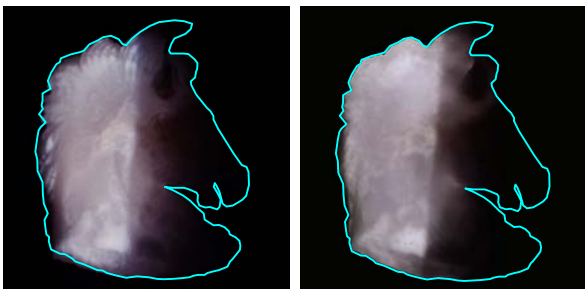
Results: Local Illumination Variation



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Results: Local Illumination Variation



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Results



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Schedule



- 1:45 Transparent/Specular Materials (Y.-Y. Chuang)
- 2:30 Fibers (S. Marschner)
- 3:30 Break
- 3:45 BTFs (G. Müller)
- 4:30 Reflectance Fields (T. Hawkins)
- 5:15 Conclusion, Questions & Answers (all)

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Course Web Pages



- find updated content at
<http://www.mpi-inf.mpg.de/resources/siggraph05-course-realistic-materials>
- please enter your comments at
http://www.siggraph.org/courses_evaluation

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